



Article New Method for Calculating the Heating of the Conductor

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Abstract: The paper describes the core heating of ACSR (aluminum conductor steel—reinforced) conductor in stable operation under different environmental conditions. The calculations are greatly simplified in a steady state—we can calculate on a balance of power instead of a balance of energies. At a known surface, the temperature of the conductor due to solar radiation, natural convection, and joules heating as well as the temperature of the steel core were calculated, which is relevant for the tensile strength of the rope. Measurements of the surface of the conductor and the core rejected a simple model of heat transfer—it is also necessary to take into account empty air spaces between the wires of a rope. On the basis of measurements, a new model has given satisfactory compliance with the measured values.

Keywords: conductor; ACSR rope; mathematical model; temperature; temperature gradient; calculation; measurements

1. Introduction

In the design of distribution and transmission networks the choice of cross-section affects several factors such as a voltage drop, a power loss, stability, and protection. The temperature rise [1] of the conductors above the ambient temperature is important. It is necessary to know the largest continuous current of the conductor, since it determines the maximum allowed temperature of the conductor. The temperature of the conductor affects the sag of the conductor between the pillars and determines the change in the tensile strength due to heating [2–5].

In calculating the load capacity of the conductors, attention must be paid primarily to the mechanical properties depending on the temperature [6–8].

Three temperatures are important: Joule heating [9] depends on the average conductor temperature, and natural convection [10] and radiation depend on the surface temperature of the conductor [11–13]. The change in the tensile strength in the first approximation depends on the temperature of the strands of the rope in the middle of the conductor.

In the articles [14–16], a sensitivity analysis was performed based on operating conditions (wind, solar, current) [14–16] and on the IEEE standard [17] for calculating the temperature of the conductor. In the article [13], a current is determined based on the calculation and measurement of the average temperature of the conductor [18].

It was also emphasized that, under exceptional conditions, the thermal creep and the loss of tensile strength of the conductor must be taken into account [15,19–21].

In this paper, a new method for calculating the warming of overhead lines (Al/Fe conductors) is presented.

Despite a good contact between the individual layers of aluminum, which is ensured at the time of manufacture, there is a great deal of influence between the empty spaces between the wires. If they are ignored, the rope has almost the same (thermal) properties as a homogeneous conductor, and the temperature in the axis is almost equal to the temperature on the surface. Considering the empty spaces between the wires, the thermal conductivity is about a hundred times smaller. The differences between the surface and center temperatures are also greater.

The new method, which results from the surface temperature of the conductor and takes into account the empty spaces between the wires, was confirmed by measurements.

In the paper, individual influencing factors on the conductor are shown, consequently indicating whether they heat it or cool it in a stable operation. In the second chapter, a general thermal equation of conductors has been written. In the third chapter, the simplification of the general equation for stable operation with emphasis on radiation, natural convection, and electric heating, is presented.

In the fourth chapter, the increase in temperature from the layers from the surface to the interior was determined. In the fifth chapter, the measurements that were rejected by the simple ACSR model of the conductor in the fourth chapter, are described. In the sixth chapter, in the conductor model, the empty spaces between the wires of the individual layers were taken into account, and the measured results confirmed the results. This is also confirmed by the new method of calculating the heating of the conductors.

2. Selection of Cross Section of the Conductors Considering on Heating

Each conductor is heated if an electric current flows through it. If all the heat produced in the conductor was consumed for heating, the temperature of the conductor would rise steadily. When the temperature of the conductor rises above the ambient temperature, the conductor sends the heat into the surroundings.

Figure 1 shows the flow of heat in the elemental volume with the indicated geometric and material parameters.



Figure 1. Heat flow in elementary volume [22].

General thermal equation of conductors (1) after V. T. Morgan [22]:

$$\frac{\partial}{\partial r} \left(\lambda(T) \cdot \frac{\partial T}{\partial r} \right) \cdot \left(1 + \frac{dr}{r} \right) + \frac{1}{r} \cdot \lambda(T) \cdot \frac{\partial T}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial}{\partial \varphi} \cdot \left(\lambda(T) \cdot \frac{\partial T}{\partial \varphi} \right) + \\ + \frac{\partial}{\partial z} \left(\lambda(T) \cdot \frac{\partial T}{\partial z} \cdot \left(1 + \frac{dr}{2r} \right) \right) + Q(T) \cdot \left(1 + \frac{dr}{2r} \right) - \gamma(T) \cdot c(T) \cdot \frac{dT}{dt} \cdot \left(1 + \frac{dr}{2r} \right) = 0$$

$$\tag{1}$$

where Q(T) is temperature-dependent heat produced per unit volume, $\lambda(T)$ is temperature-dependent thermal conductivity, γ is specific weight, *c* is specific heat, *T* is temperature, and *r*, *z*, φ are geometric parameters.

3. Stabile Operation

In stable operation, there are events observed—energy in a time unit, that is, power. All energy equilibrium is simplified in the balance of power. For reasons of transparency, the fact that the conductor can be hidden a few meters from the sun so the heat flow is not observed in the longitudinal direction (z-axis) is not taken into account. Given the fact that the factors of immission and emissivity for clear, cloudy skies, grassy surfaces and fields are not known, both the emissivity and the albedo are set up by the same one, thus obtaining a rotational symmetric system [23].

3.1. Power of Radiation

In the case of heating the conductor, a comparison between the calculated values with the new method and during the measurements was made.

Figure 2 shows the conductor we are exploring and on which we performed the measurements described below in the article.



Figure 2. ACSR (aluminum conductor steel—reinforced) conductor Al/Fe 490/65 mm².

Using (2), the amount of light that irradiates a 1 m long piece of the conductor at temperature $T = 20 \text{ }^{\circ}\text{C} = 293 \text{ K}$ was calculated. For reasons of transparency it is supposed that the surface is ideally black.

$$P = \varphi \cdot S_{\rm v} = \sigma \cdot T^4 \cdot S_{\rm v} = 40 \,\,{\rm W} \tag{2}$$

where *P* means light current, S_v is surface of the conductor [m²], $S_v = 2 \cdot \pi \cdot r \cdot 1$ m = $2 \cdot \pi \cdot 0.0153$ m·1 m = 0.096 m², φ is density of radiation flow of the black body, σ is a universal constant, known as Štefan–Boltzmann constant, *T* is temperature.

Because the rope conductor loses 40 J at a temperature of 20 °C per second, under these circumstances, it would be cooled every second for $(P/(m \cdot c_p \cdot dT) = 40/1547) = 0.026$ K.

Bodies around the rope also have the same temperature (20 $^{\circ}$ C) and are not ideally black. The rope from the surroundings gets exactly the same amount of energy, namely

$$\sigma \cdot T_{\rm o}^4 \cdot S_{\rm v} = 40 \text{ W per second.} \tag{3}$$

When the sun shines on the conductor, the light flux is joined by the previous 40 watts:

$$P_{\rm s} = \Phi_{\rm s} = \varphi_{\rm s} \cdot A_{\rm p} = 30 \,\mathrm{W} \tag{4}$$

where φ_s is a solar constant (1000 W/m²).

As an irradiated surface, due to the curvature, the longitudinal cross-section $A_p = 2 \cdot r \cdot 1 = 2 \cdot 0.0153$ m·1 m = 0.0306 m² is taken. The conductor reaches such a *T* temperature to transmit exactly as much energy per second as it receives. If only the light currents are considered, the balance is the following:

$$\varphi_{\rm s} \cdot A_{\rm p} + \sigma \cdot T_{\rm o}^4 \cdot S_{\rm v} = \sigma \cdot T_{\rm p}^4 \cdot S_{\rm v} \tag{5}$$

where φ_s is solar energy density at surface [W/m²], A_p is longitudinal section of the conductor [m²], σ is Štefan–Boltzmann's constant 5.68 × 10⁸ W/(m² K⁴), T_0 is ambient temperature [K], T_p is surface temperature of the conductor [K], S_v is surface of the conductor [m²].

Considering the solar constant ($E_0 = 1367 \text{ W/m}^2$) less for passing through the atmosphere ($\varphi_s = 1000 \text{ W/m}^2$), it is:

$$T = \sqrt[4]{T_{\rm o}^4 + \frac{j_{\rm s} \cdot A_{\rm p}}{\sigma \cdot S_{\rm v}}} = 338 \text{ K} = 65 \text{ }^{\circ}\text{C}$$
(6)

Figure 3 shows the heat flux in equilibrium.



Figure 3. Thermal balance of the conductor in the sun. Note: sun = 30 W, surrounding = 40 W, conductor at 65 °C = 70 W.

3.2. Convection

Convection is the transition of heat from solid bodies to a gaseous (liquid) medium and vice versa [24].

The research of heat flows due to convection [25,26] gave the following empirical formulas for determining the size of these flows:

$$\Phi = S \cdot \alpha \cdot \left(T_{\rm p} - T_{\rm o}\right) \, \left[W\right]; \varphi = \alpha \cdot \left(T_{\rm p} - T_{\rm o}\right) \left[\frac{W}{{\rm m}^2}\right] \tag{7}$$

where α is thermal transfer coefficient [W/(m² K)] (depending on the position and shape of the wall), $T_{\rm p}$ is the temperature of the convection surface [K], $T_{\rm o}$ is the temperature of the surrounding medium [K], *S* is surface [m²].

For a horizontal tube [27], the heat flux density can be calculated as follows:

$$\varphi = \alpha \cdot \left(T_{\rm p} - T_{\rm o}\right) = 1.4 \cdot \sqrt[4]{\frac{T_{\rm p} - T_{\rm o}}{d}} \cdot \left(T_{\rm p} - T_{\rm o}\right) \tag{8}$$

Taking radiation and convection into account, the equilibrium equation for power is for Al/Fe 490/65 mm² conductor per unit of length:

$$\varphi_s \cdot A_p + \sigma \cdot T_o^4 \cdot S_v = \sigma \cdot T_p^4 \cdot S_v + \frac{1.4}{\sqrt[4]{d}} \cdot \left(T_p - T_o\right)^{1.25}$$
(9)

In this case, the markings are equal to (5) and additionally *d* is a pipe diameter (conductor) [m].

The equation is not algebraically solvable. With the numerical tangent method [28], the surface temperature of the conductor is 316 K. or 43 $^{\circ}$ C.

Assuming that the surface of the conductor is the ideal black body, it is heated in the sun to 65 $^{\circ}$ C, the convection (without wind) cools it to 43 $^{\circ}$ C (Figure 4).



Figure 4. Thermal balance of the cylinder in the sun, taking convection into account. Note: sun = 30 W, surrounding = 40 W, convection = 16 W, conductor at 43 $^{\circ}$ C = 54 W.

3.3. Electric Heating

The amount of heat released is proportional to the square of the current (Joule's law):

$$Q \propto I^2 \cdot R \cdot t = I^2 \cdot \frac{\rho_{\rm el}}{A} \cdot t \quad [J]$$
(10)

where *Q* is heat due to electric current, *I* is current of the conductor, *R* is resistance of the conductor, *t* is time, ρ_{el} is specific resistance and *A* is section of the conductor.

The resistance of the conductor depends on the shape and the substance forming the conductor, and furthermore from the temperature, frequency and current density flowing through the conductor [10].

Normally, at the ropes, in the calculations of operating states, only the resistance (conductivity) of the aluminum cover is considered. For the generality, the conductivity of the steel core and the proper distribution of the current along the layers [29] will also be taken into account. The maximum allowed current for the conductor Al/Fe 490/65 mm² is 960 A.

The equilibrium equation, taking into account the current, is then:

$$\varphi_{s} \cdot A_{p} + \sigma \cdot T_{o}^{4} \cdot S_{v} + I^{2} \cdot R_{T} =$$

$$= \sigma \cdot T_{p}^{4} \cdot S_{v} + \frac{1.4}{\sqrt[4]{d}} \cdot \left(T_{p} - T_{o}\right)^{1.25}$$
(11)

In this case the marks are as in (5).

Using the tangent numerical method [28], the surface of the conductor is obtained 354 K or 81 °C. Assuming that the surface of the conductor is the ideal black body, it is heated in the sun to 65 °C, the convection cools it to 43 °C, maximum allowable current I = 960 A heats it to 81 °C (Figure 5).



Figure 5. The heat balance of the conductor in the sun, taking into account electrical heating and convection. Note: sun = 30 W, surrounding = 40 W, Joule's heating = 70 W, convection = 55 W, conductor at 43 $^{\circ}$ C = 54 W.

4. Heating a Conductor by Layers

In the case of electric conductors, mainly the steel core determines the tensile strength and thus the sag and spacing from the ground [21,30]. The change in the tensile strength in the first approximation depends on the temperature of the strands of the rope. Internal, warmer strands lose tensile strength faster, therefore, it is necessary to count or also measure the temperature gradient.

In the steady state, the temperature of the surface of the conductor was calculated. The basic equation for calculating the temperature of individual layers is the equation for the heat flux (power) through a differential thin wall [22]:

$$\Phi = P = -\lambda \cdot S \cdot \frac{\mathrm{d}T}{\mathrm{d}r} \tag{12}$$

where P, P_{Fe} and P_{Al} is electrical power at the appropriate temperature.

Through a differential thin tube (wall thickness d*r*) in time d*t* transfers heat flow ϕ from the steel core (*P*_{Fe}) and a part of the heat flow from a source in aluminum to a radius *r* (Figure 6):

$$\Phi = P_{\rm Fe} + P_{\rm AI}' = P_{\rm Fe} + \frac{P_{\rm AI}}{V_{\rm AI}} \cdot \pi \cdot \left(r^2 - r_{\rm Fe}^2\right) \cdot l \tag{13}$$

$$-\lambda_{\rm AI} \cdot 2 \cdot \pi \cdot r \cdot l \cdot \frac{dT}{dr} = P_{\rm Fe} + \frac{P_{\rm AI}}{V_{\rm AI}} \cdot \pi \cdot \left(r^2 - r_{\rm Fe}^2\right) \cdot l \qquad (13)$$

$$- \int_{T_{\rm P}}^{T(r)} dT = \frac{P_{\rm Fe} - \pi \cdot l \cdot \frac{P_{\rm AI}}{V_{\rm AI}} \cdot r_{\rm Fe}^2}{2 \cdot \pi \cdot l \cdot \lambda_{\rm AI}} \cdot \int_{r_{\rm AI}}^r \frac{dr}{r} + \frac{\frac{P_{\rm AI}}{2 \cdot \lambda_{\rm AI}}}{2 \cdot \lambda_{\rm AI}} \cdot \int_{r_{\rm AI}}^r r \cdot dr \qquad (14)$$

$$T(r) = T_{\rm p} + \frac{P_{\rm Fe} - \pi \cdot l \cdot \frac{P_{\rm AI}}{V_{\rm AI}} \cdot r_{\rm Fe}^2}{2 \cdot \pi \cdot l \cdot \lambda_{\rm AI}} \cdot \ln \frac{r_{\rm AI}}{r} + \frac{\frac{P_{\rm AI}}{V_{\rm AI}}}{4 \cdot \lambda_{\rm AI}} \cdot \left(r_{\rm AI}^2 - r^2\right)$$

$$T_{\rm Fe} = T(r_{\rm Fe}) = T_{\rm p} + \frac{p_{\rm Fe} - \frac{p_{\rm AI} \cdot r_{\rm Fe}^2}{2 \cdot \pi \cdot \lambda_{\rm AI}} \cdot \ln \frac{r_{\rm AI}}{r_{\rm Fe}} + \frac{p_{\rm AI}}{4 \cdot \pi \cdot \lambda_{\rm AI}}$$

$$dT = T_{\rm Fe} = T(r_{\rm Fe}) = T_{\rm p} + \frac{p_{\rm Fe} - \frac{T_{\rm AI} \cdot r_{\rm Fe}^2}{2 \cdot \pi \cdot \lambda_{\rm AI}} \cdot \ln \frac{r_{\rm AI}}{r_{\rm Fe}} + \frac{p_{\rm AI}}{4 \cdot \pi \cdot \lambda_{\rm AI}}$$



Figure 6. Heat current from the steel core. Note: *r* is appropriate radius, *T* appropriate temperature, λ appropriate conductivity.

The temperature in the axis of the conductor can also be calculated (Figure 7).

$$\Phi = P = \frac{P_{\text{Fe}}}{V_{\text{Fe}}} \cdot \pi \cdot r^2 \cdot l = -\lambda_{\text{Fe}} \cdot 2 \cdot \pi \cdot l \cdot \frac{dT}{dr}$$

$$- \int_{T_p}^{T(r)} dT = \frac{\frac{P_{\text{Fe}}}{2 \cdot \lambda_{\text{Fe}}}}{2 \cdot \lambda_{\text{Fe}}} \cdot \int_{r_{\text{Fe}}}^{r} r \cdot dr$$
(15)

$$T(r) = T_{\rm Fe} + \frac{p_{\rm Fe}}{4 \cdot \lambda_{\rm Fe} \cdot \pi \cdot r_{\rm Fe}^2} \cdot \left(r_{\rm Fe}^2 - r^2\right)$$
(16)
$$T_{\rm o} = T(r=0) = T_{\rm Fe} + \frac{p_{\rm Fe}}{4 \cdot \pi \cdot \lambda_{\rm Fe}}$$

where ϕ is heat due to electric current, *P*, *P*_{Fe} and *P*_{Al} is power or specific power, *V*_{Fe} and *V*_{Al} is volume, *r*, *r*_{Al} and *r*_{Fe} is radius, *l* is length, λ_{Al} and, λ_{Fe} is specific conductivity, and *T*_p is surface temperature.



Figure 7. Calculating the temperature in the steel core axis.

In Table 1, the temperatures are given as a function of the distance from/to the surface.

Radius	<i>r</i> [m]	ϑ [°C]			
r_{Al3}	0.0153	50.80			
r_{Al2}	0.0119	50.8088			
$r_{\rm Al1}$	0.0085	50.8148			
r _{Fe2}	0.0051	50.8177			
r _{Fe1}	0.0017	50.8212			
center	0.0000	50.8223			
$I = 960 \text{ A}, \varphi = 200 \text{ W/m}^2, T_0 = 5 \text{ °C}.$					

Table 1. Temperature in dependence of radius.

Despite of calculating the layers, the heat flow is the same as for a solid conductor.

5. Measurement of Current by Layers

In order to check the accuracy of the calculations in the previous chapter, the distribution of the current along the layers had to be checked first. At about 2 m long piece of the stranded conductor, about 10 cm of aluminum wires were removed in the middle (to gain access to the steel core) and the 'peeled' part of the rope only with the removed aluminum wires were shortened (Figure 8).

The results of the measurements were different from the expectations (Table 2).

The sum of the currents was in the class of accuracy of the clamp meters. In checking the matching of all three measured currents, it was found that the deviations were within the limits of the accuracy class of the clamp meters.

The expected current distribution at the total current 960 A was 96.13% current in aluminum coat and 3.85% in steel core. The divergence was explained with the basics of electrical engineering. An electrical substitute circuit with calculated currents for 2 m long conductor is shown in Figure 9.



Figure 8. (a) Measurement scheme with interrupted aluminum coat. (b) Picture of measurement with interrupted aluminum coat.

 Table 2. Results of measurement with interrupted aluminum coat.

 Current through the Clamp Meter Km2

 Current through the Clamp Meter Km2

Current through the Clamp Meter Km1 [A]	Current through the (Aluminun	e Clamp Meter Km2 1—Surface)	Current through the Clamp Meter Km3 (Steel—Core)		
	[A]	[/]	[A]	[/]	
57	46	0.81	12	0.21	
100	84	0.84	22	0.22	
206	166	0.81	43	0.21	
408	323	0.79	82	0.20	
605	492	0.81	122	0.20	
810	650	0.80	159	0.20	
1004	811	0.81	198	0.20	
1209	971	0.80	250	0.21	
1406	1165	0.83	310	0.22	



Figure 9. Theoretical current distribution between the steel core and the aluminum coat. Picture of measurement with interrupted aluminum coat.

Obviously, the distribution of the current in accessories (couplings) with the cut aluminum coat was different than planned. The decision to check and pull out the steel core and parallelly attached to the source the steel core and an aluminum coat was made (Figure 10).



Figure 10. Measurement of current in parallel binding of aluminum coat and steel core.

At the same time, the temperature of the surface of the conductors was measured with a thermography camera. An example of a measurement is in the Figure 11.

Figure 11 shows the measured temperature with the thermography. The left figure shows the temperature of the aluminum—the surface of the conductor, the right picture the temperature of the steel core—the temperature in the axis of the conductor.



Figure 11. Camera measured temperature at parallel binding.

The current distribution between the layers was in line with expectations.

The difference between the calculated temperatures on the surface and in the middle of the rope compared with the measurements shows that in the calculations we did not take into account the empty spaces between the rope wires (Figure 12). In the next chapter the attention was paid to these empty spaces.

To summarize, the heat transfer to the surface is worse than it was assumed in the previous section.



Figure 12. Conductor with drawn replaced rings of air. Note: dark gray—circle and ring of metal (Fe) with the same surface as steel wires; light gray—the metal rings (Al) with the same surface as the wires in the individual layers; white—rings of air with the same surface as the empty spaces between the wires.

6. Heating of Conductor by Layers with Compliance of Air between Spaces

Measurements have shown that the model of heating in layers is not the best, since it shows almost the same values of core and surface temperatures (Table 3). Significantly higher core temperatures were measured (Table 3). Despite the good contact between the individual layers of Aluminum, which is ensured at the time of production, there is a considerable effect between the empty spaces between the wires [31]. In the new model for the calculation of heat transfer from the middle to the surface, concentric coils of metal and air were assumed (Figure 12). In the cross-section, these are coils with the same surface as the actual metals or air spaces.

The basic equation for calculating the temperature of individual layers is the equation for the heat flux (power) through a differential thin wall (12).

Once again the temperature of the conductor from the surface in a steady state (second chapter) was re-emerged. In the case of heat transfer, the transmission through the layer of air has to be separated, where the heat flow is constant (there are no sources) and the transition through the metal layer (aluminum or steel, where the heat produced in the layer is to be added to the heat flow from the inside).

Air layer: In a steady state, the heat flow is constant (no sources) and is equal to the heat flow to the air. In the case of the fourth layer of air it is ϕ from the steel core and inner layers of aluminum (P_{not}) at a distance r_{Al2} from the center of the conductor (Figures 12 and 13).

$$-\lambda_{\text{zrak}} \cdot 2 \cdot \pi \cdot r \cdot l \cdot \frac{\mathrm{d}T}{\mathrm{d}r} = P_{\text{not}}$$

$$-\int_{T_{p}}^{T(r)} \mathrm{d}T = \frac{P_{\text{not}}}{2 \cdot \pi \cdot l \cdot \lambda_{\text{zrak}}} \cdot \int_{r_{p}}^{r} \frac{\mathrm{d}r}{r}$$
(17)

$$T(r) = T_{\text{zrak4}} + \frac{p_{\text{not}}}{2 \cdot \pi \cdot \lambda_{\text{zrak}}} \cdot \ln \frac{r_{\text{zrak4}}}{r}$$
(18)
$$T_{\text{Al2}} = T(r_{\text{Al2}}) = T_{\text{zrak4}} + \frac{p_{\text{not}}}{2 \cdot \pi \cdot \lambda_{\text{zrak}}} \cdot \ln \frac{r_{\text{zrak4}}}{r_{\text{Al2}}}$$

Table 3. Measured and calculated currents and temperatures at parallel binding of steel core and aluminum coat.

Current through the	Clamp Meter Km2 (Aluminum—Surface)			Clamp Meter Km3 (Steel—Core ro)			
[A] [A]							
	[A]			נהן			
		Measured *	Calculated		Measured *	Calculated	
57	56	25.7	25.9	2	25.3	25.9	
104	99		26.3	4	-	26.3	
205	199	27.4	27.92	7	-	27.9	
414	397		34.2	15	-	34.2	
611	593	41.7	43.6	22	47.9	43.6	
814	792		56.4	29	-	56.4	
1005	986		71.4	37	-	71.4	
1210	1176		90.5	44	-	90.5	
1416	1370	92.3	112.8	50	>160	112.9	

* at higher current values, the stationary condition was not guaranteed.



Figure 13. Heat flow from the interior through the air layer.

In Table 4, the temperatures are shown in dependency of radius taking into account the empty spaces in the conductor with the air cylinders.

Table 4. Temperatures in dependency from radius and environmental conditions.

Radius	<i>r</i> [m]	θ [°C]			
r _{Al3}	0.015	50.8			
r _{zrak4}	0.012	50.807			
r_{Al2}	0.011	52.319			
r _{zrak3}	0.009	52.323			
$r_{\rm Al1}$	0.008	53.250			
r _{zrak2}	0.006	53.253			
$r_{\rm Fe2}$	0.005	53.479			
$r_{\rm zrak1}$	0.002	53.482			
r _{Fe1}	0.002	53.521			
center	0.000	53.522			
$I = 960 \text{ A}, \varphi = 200 \text{ W/m}^2, T_0 = 5 \text{ °C}.$					

The comparison of Tables 1 and 4 shows that already at a low ambient temperature of 5°C and a slight radiation of the sun ($\varphi = 200 \text{ W/m}^2$), the difference between the center and the surface for the new model is calculated 3 degrees, but earlier there were almost no differences.

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Table 5 is a replicated Table 3 with measured and calculated temperatures, taking into account the empty spaces inside the conductor as thin air cylinders.

The comparison of Tables 3 and 5 shows that the difference of the current of 611 A of middle temperature is higher for 7 degrees or 16%, while for the highest measured current, the difference is in the order of 80 degrees according to the new model. In the model without regard to the airspace, at 611 A there is practically no difference.

Table 5. Measured and calculated currents and temperatures at parallel binding of steel core and Aluminum coat taking into account the empty spaces.

Current through the Clamp Meter Km1	Clamp Meter Km2 (Aluminum—Surface)			Clamp Meter Km3 (Steel—Core ro)				
	Cu	rrent	rent [°C]		Current		Temperature [°C]	
[A]	[A]	[/]	Measured	Calculated	[A]	[/]	Measured	Calculated
57	56	98.25	25.7	25.9	2	3.51	25.3	26.1
104	99	95.19	-	26.3	4	3.85	-	26.1
205	199	97.07	27.4	27.9	7	3.41	-	27.9
414	397	95.89	-	34.3	15	3.62	-	37.1
611	593	97.05	41.7	43.9	22	3.60	47.9	50.9
814	792	97.30	-	57.3	29	3.56	-	73.9
1005	986	98.11	-	73.2	37	3.68	-	103.3
1210	1176	97.19	-	94.3	44	3.64	-	144.4
1416	1370	96.75	92.3	119.6	50	3.53	>160	197.3

Note: at higher current values, the stationary condition was not guaranteed. We wanted to measure the steady state even also at the nominal current of the conductor, but we managed to complete the entire measurement only at 1370 A. During this current, the point source and the conductor were overloaded. The temperature meter (camera) showed more than 160 degrees. At this temperature, the measurement was interrupted, and 197 degrees were calculated.

7. Discussion

The purpose of authors was to determine the core temperature of an ACSR (aluminum conductor steel—reinforced) conductor by simply measuring method.

In the analysis the level of heating of the conductor in a steady state of operation has been examined. Assuming that the surface of the conductor is the ideal black body, it heats up ($\varphi_s = 1000 \text{ W/m}^2$) to 65 °C in the sun, in a state without wind, the convection cools it to 36 °C, maximum allowable current I = 960 A heats it up to 80 °C.

In the case of electric conductors, the steel core frequently determines the tensile strength and thus the pitch and spacing from the ground. Joule heating depends on the average conductor temperature, while convection and radiation depend on the surface temperature of the conductor. The change in the tensile strength in the first approximation depends on the temperature of the strands of the rope. Internal, warmer strands lose tensile strength faster, therefore, it is necessary to count or also measure the temperature gradient.

At a known temperature of the surface of the conductor, the temperature rise in the interior was calculated as a function of the distance from the surface. At the measured current 611 A, there is practically no difference of the temperature of the conductor 490/65 mm² Al/Fe in the center of the steel core, if we do not take into account the empty spaces between the wires. Considering the empty spaces of air, the difference is 7 °C. In the measurements, the difference in the center of the steel core was about 6 degrees at current 611 A.

Using the new method, taking into account the empty spaces between the wires, it was calculated and confirmed, while using the measurement that the temperature of the steel core is higher than would be expected from the surface of the conductor. This is of great importance because it affects the temperature of the core on the creep and the tensile strength of the conductor and the related sag. The new calculation method is closer to the real state, since it takes into account empty airspaces between individual wires. Therefore, it is proposed to use the new method in assessing the temperature of the center of the conductors (steel core) at a known surface temperature of the conductors, which can be easily measured, for example, with a thermography camera. This gives us the information on the appropriate mechanical strength of the conductor.

The method is suitable especially at high ambient temperatures, while the limitation is the measurement (assessment) of the conductor temperature.

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