



Article

Application of Machine Learning in Evaluation of the Static Young's Modulus for Sandstone Formations

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Abstract: Prediction of the mechanical characteristics of the reservoir formations, such as static Young's modulus (E_{static}), is very important for the evaluation of the wellbore stability and development of the earth geomechanical model. E_{static} considerably varies with the change in the lithology. Therefore, a robust model for E_{static} prediction is needed. In this study, the predictability of E_{static} for sandstone formation using four machine learning models was evaluated. The design parameters of the machine learning models were optimized to improve their predictability. The machine learning models were trained to estimate E_{static} based on bulk formation density, compressional transit time, and shear transit time. The machine learning models were trained and tested using 592 well log data points and their corresponding core-derived E_{static} values collected from one sandstone formation in well-A and then validated on 38 data points collected from a sandstone formation in well-B. Among the machine learning models developed in this work, Mamdani fuzzy interference system was the highly accurate model to predict E_{static} for the validation data with an average absolute percentage error of only 1.56% and R of 0.999. The developed static Young's modulus prediction models could help the new generation to characterize the formation rock with less cost and safe operation.

Keywords: static Young's modulus; sandstone formations; machine learning

1. Introduction

Prediction of the mechanical characteristics of the reservoir formations, such as Young's modulus (E), is necessary for the evaluation of the wellbore stability, reservoir compaction, hydraulic fracturing, and formation control [1]. E is a mechanical parameter that gives an indication of the resistance of the rock samples when exposed to a uniaxial load [2]. On the other hand, static Young's modulus (E_{static}) is a critical parameter needed to build the earth geomechanical model [3]. It is also used for fractures' designing and mapping [4,5]. While drilling hydrocarbon wells, E_{static} is also needed with other mechanical and petrophysical properties to make a full description of the in-situ stresses to ensure wellbore stability [6].

 E_{static} varies significantly with the change in lithology [2,7]. E_{static} for shale ranges from 0.69 to 6.89 GPa. For limestone, it is between 55.16 and 82.74 GPa, and for sandstone, it is between 13.79 and 68.95 GPa [7]. These ranges confirm the wide difference in E_{static} from one formation type to another and the huge change within the same lithology. Therefore, it is necessary to estimate E_{static} along the whole drilled hydrocarbon well.

Two methods for rock elastic parameters' estimation are currently available. These are the experimental laboratory method or the use of empirical correlations. The experimental laboratory method is based on conducting laboratory experiments on the rock samples using static or dynamic testing techniques. In the static technique, the sample is subjected to a uniaxial or triaxial load and the deformation of the sample is measured, while in the dynamic technique, shear and compressional

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wave velocities along the tested sample are measured and then the sample's elastic parameters are calculated based on the shear wave (V_s) and compressional wave (V_p) velocity [8]. In the field, wireline logging tools are used to measure V_s and V_p . The dynamic Young's modulus $(E_{dynamic})$ can then be evaluated based on V_s and V_p and using Equation (1).

$$E_{\text{dynamic}} = \frac{\rho V_{\text{S}}^2 (3V_{\text{P}}^2 - 4V_{\text{S}}^2)}{V_{\text{P}}^2 - V_{\text{S}}^2}$$
(1)

where ρ denotes the formation's bulk density in g/cm³, V_S and V_P are in km/s, and $E_{dynamic}$ is in GPa. Several previous studies confirmed that the laboratory-measured $E_{dynamic}$ for the same rock sample is significantly greater than E_{static} [9–11]. $E_{dynamic}$ could be 1.5 to 3 times greater than E_{static} [12] and some recent studies reported that $E_{dynamic}$ could be ten times greater than E_{static} [13,14]. The strain amplitude between the two experimentally testing methods is the main reason for this huge difference, which decreases as the rock strength increase [15].

The static elastic parameters are actually representative of the in-situ stress–strain conditions of the reservoir [16]. Accurate determination of the static elastic parameters requires conducting a time consuming and costly experimental tests on real core samples [17]. The common practice to decrease this high cost is to select core samples at specific intervals and conduct the experimental tests of these cores only. Then an empirical correlation between the laboratory-derived parameters and the conventional well log data will be developed based on the results of laboratory tests. The static moduli throughout the whole reservoir depths can then be predicted by calibrating the dynamic moduli using the developed correlations [4]. Because of the heterogeneity of the reservoir formations, the developed well log-based empirical equations are usually not generalized to all formation types. Therefore, different correlations need to be developed for every formation type to track the changes in the static parameters along the whole reservoir.

The correlation in Equation (2) was developed by Fei et al. [18] for the evaluation of E_{static} for sandstone formations; this correlation evaluates E_{static} as a function of $E_{dynamic}$, which was developed based on 22 triaxial tests results.

$$E_{\text{static}} = 0.564 E_{\text{dynamic}} - 3.4941$$
 (2)

where E_{static} and E_{dynamic} are in GPa.

Mahmoud et al. [19] developed a set of equations to estimate E_{static} for different types of formations. The main advantage of the correlations developed by Mahmoud et al. [19] is the ability to implement these correlations directly to evaluate E_{static} without the need for $E_{dynamic}$, these correlations are only a function of the bulk formation density (RHOB), compressional transit time (DT_c), and shear transit time data (DT_s).

Different recent studies confirmed the ability of machine learning techniques to accurately estimate rock mechanical properties. Abdulraheem et al. [20] optimized three machine learning models of the artificial neural networks (ANN), fuzzy logic model, and functional neural networks (FNN) for estimation of E_{static} and the static Poison's ratio for the hydrocarbon reservoirs. The authors did not specify the reservoir rock formation type. The developed models confirmed their ability to estimate the reservoir rock mechanical properties.

In another study, Tariq et al. [21] developed three machine learning models of ANN, fuzzy logic, and support vector machine (SVM) to estimate E_{static} for limestone formation. The ANN model overperformed the other machine learning models and the currently available empirical correlation for E_{static} estimation.

Tariq et al. [22] developed empirical correlations for the estimation of the mechanical properties of E_{static} , Poisson's ratio, and unconfined compressive strength based on the application of the artificial neural networks (ANN) and the use of the conventional well log data, the authors also did not specify

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the type of the formation they used in this study. The developed correlations improved their ability to accurately estimate the rock mechanical properties.

In 2017, Parapuram et al. [23] developed an ANN model to estimate the geomechanical properties of the upper Bakken shale based on well log data. The results of this study confirmed the ability of the ANN model to accurately estimate the rock mechanical properties.

Recently, in our previous study, Mahmoud et al. [24], we evaluated the use of the ANN in estimating E_{static} for sandstone formations. Mahmoud et al. [24] reported that ANN is able to predict E_{static} with very high accuracy, and it overperformed all available empirical equations currently in use.

Sustainable development can be defined as development that meets the needs of the present without compromising the ability of future generations. This study is aimed at evaluating the ability of four machine learning techniques namely ANN, SVM, FNN, and the Mamdani fuzzy interference system (M-FIS) in estimating E_{static} for sandstone formations as a function of RHOB, DT_s, and DT_c. The new systems of static Young's modulus prediction are examples of the new development which will help the new generation to discover and extract the oil and gas at lower cost and with safer operation. The developed method depends on taking the reading from the well logging tools and applying the artificial neural network models to predict the static Young's modulus and provide a continuous profile of the elastic property through the whole reservoir. This will improve the time necessary for the decision on the required action based on given information.

2. Theory of Machine Learning Techniques Considered in This Study

The first machine learning technique used in this work was the ANN, which is a computing system that is designed to mimic the way the biological systems, such as the human or animal brains, behave. ANN is developed to identify, estimate, classify, or make a decision by using a machine program. ANN is available in different structures; the simplest ANN structure, which was used in this study, is called multi-layered perceptron (MLP) which consists of one input layer, one or several hidden (learning) layers, and one output layer, as shown in Figure 1 [25]. The ANN systems are trained originally using training data (supervised learning) to perform the needed tasks [26].

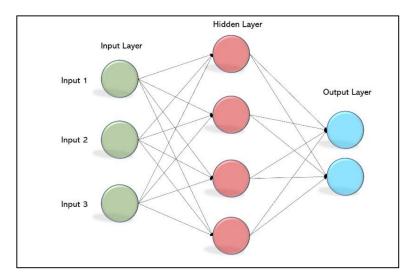


Figure 1. Artificial neural networks model with input layers of three inputs, one hidden layer, and an output layer.

M-FIS was the second machine learning technique used in this study, which combines the adaptive neuro-fuzzy inference system (ANFIS) and subtractive clustering, where ANFIS is a multilayer feed-forward adaptive network in which the incoming signal will be subjected to a particular function performed by each training node where every node has its own parameters pertaining (Figure 2). The hybrid learning procedure was performed in two steps; the first step was the forward pass in which

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the functional signals representing the input data go forward and the least square formula was used to identify the parameters in the output layer (layer 5). The second step was the backward pass, in which the error rates propagate, in the opposite way, and the gradient method was implemented to update the parameters in the input layer (layer 1) [27].

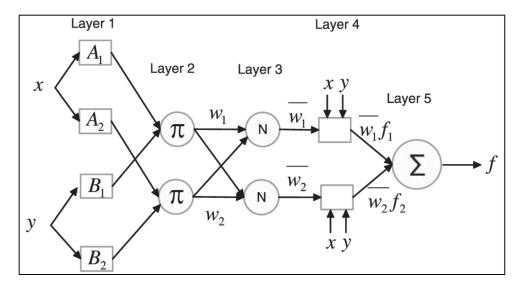


Figure 2. Adaptive neuro-fuzzy inference system architecture of a model using two inputs layers and one output parameter.

The subtractive clustering is an unsupervised clustering algorithm that aims to examine the density of the available input data. Then it defines the point surrounded by the highest number of neighbors as the cluster's center. It then subtracts (removes) the other data points within a pre-specified fuzzy radius, and the subtractive clustering algorithm considers only the point defined as the cluster's center. This process is repeated to examine all input data points. Subtractive clustering generates the rules that approximate a function [28].

The third machine learning technique used in this study was the FNN model, compared to the ANN which uses the sigmoidal common model. The FNN model works with the generalized functional models. In FNN, the neuron's function is learned from the existing data, which means they are not constant. Therefore, the weights related to links are not needed because the neuron functions include the effect of weights [29]. FNN contains an input layer, an output layer and layers of computing units that are related to each other. In FNN, there are different arguments in neural functions instead of one argument, such as in ANN [30].

The fourth machine learning model considered in this study was the SVM, which is one of the most famous classifying algorithms developed by Vapnik [31] in the framework of statistical learning theory. It performs classification of the data optimally into two or more divisions by applying a multidimensional hyperplane; this hyperplane is set to classify the data based on the tuning parameters (design parameters) of the kernel, regularization parameter (C), gamma, and margin. In its nature, SVM is very similar to a neural network, where the use of SVM with sigmoid kernel function is almost identical to the use of the perceptron neural network, having two hidden layers. Although it was originally developed in the statistical learning theory, the SVM technique is applicable in regression and classification problems, and it is also suitable for solving non-linear problems [32].

3. Applications of Machine Learning in Petroleum Engineering

Machine learning techniques are used in several scientific and engineering fields since the early 1990s to solve complicated non-linear problems. Petroleum engineers and petroleum geologists use different machine learning techniques to solve problems related to petroleum industry, such as the characterization of the heterogeneous hydrocarbon reservoirs [33,34], evaluation of the reserve

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of unconventional reservoirs [35–38], estimation of the rock mechanical parameters, such as the static Poisson's ratio in carbonate reservoirs [39] and the static Young's modulus for sandstone reservoirs [24,40], evaluation of the integrity of wellbore casing [41,42], optimization of drilling hydraulics [43], evaluation of pore pressure and fracture pressure [44,45], hydrocarbon recovery factor estimation [46,47], determination of the alteration in the drilling fluids rheology in real-time [48,49], optimization of rate of penetration [50,51], prediction of the formation tops [52], and others.

4. Application to the Well Log Data

The predictability of the machine learning models depends on the amount of training data points and the design parameters of every model. In this work, the machine learning model's design parameters and the selection of the optimum training data points were conducted based on the optimization process of all combinations of the design parameters, as will be discussed in the following sections.

4.1. Data Preparation

The machine learning models are trained in this study to predict E_{static} based on the RHOB, DT_s , and DT_c as inputs. In this study, core-derived E_{static} and their corresponding well log data collected from two different sandstone wells (598 collected from Well-A and 38 from Well-B) were used. The data of Well-A was used to build and test the machine learning models, and Well-B data (unseen data) was used to validate the trained machine learning models. Both formations considered in wells A and B were sandstone formations.

Before training the machine learning models, the data were studied statistically to remove all noise, unreal values, and outliers from the training data. The standard deviation (SD) was considered for removing the outliers; based on this, all data points without the range of \pm 3.0 SD were considered as outliers and removed from the input dataset. This preprocessing is very important to ensure accurate estimation of the targeted parameter by applying the machine learning techniques [53]. Out of the 598 data points collected from Well-A, 6 data points were considered as outliers, these data points were removed from the data before the start of the training process.

Since the core derived E_{static} was estimated based on well log data, it was very important to perform depth matching between the well log input data and core derived E_{static} . Although the gamma-ray log was not considered as input in this study, it was considered at this step to perform the depth matching.

4.2. Training the Machine Learning Models

After data preprocessing, 592 well log data points and their corresponding core derived E_{static} were considered valid for machine learning models training. Four hundred and fourteen, 178, 355, and 444 well log data points (out of the 592) were considered to train ANN, M-FIS, FNN, and SVM models, respectively. The number of the training data was selected based on the optimization process, where the optimum number of the training data that optimize the predictability of the different machine learning models was selected in every case. The statistical characteristics for the training datasets for the different machine learning models are summarized in Table 1. The data of Table 1 is very important when the machine learning models are to be used for evaluating E_{static} for a new dataset; the new testing data should be within the ranges in Table 1.

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Table 1. The statistical characteristics for th	e training data set.
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Artificial Neural Networks.					
	RHOB, g/cm ³	DT _c , μs/ft	DT _s , μs/ft	E _{static} , GPa	
Minimum	2.32	44.4	73.2	7.50	
Maximum	2.98	78.9	136	92.8	
Range	0.66	34.6	62.4	85.3	
Standard Deviation	0.114	5.06	8.91	14.9	
Sample Variance	0.013	25.6	79.4	221	
	Mamdani Fuz	zy Interference S	ystem		
	RHOB, g/cm ³	DT _c , μs/ft	DT _s , μs/ft	E _{static} , GPa	
Minimum	2.33	44.6	73.2	8.63	
Maximum	2.98	78.7	133	92.8	
Range	0.66	34.1	60.0	84.2	
Standard Deviation	0.114	5.45	9.47	15.2	
Sample Variance	0.013	29.7	89.6	232	
	Functiona	ıl Neural Networ	ks		
	RHOB, g/cm ³	DT _c , μs/ft	DT _s , μs/ft	E _{static} , GPa	
Minimum	2.31	44.5	73.6	7.50	
Maximum	2.98	78.9	136	92.6	
Range	0.67	34.4	62.5	85.1	
Standard Deviation	0.112	5.27	9.20	14.9	
Sample Variance	0.013	27.7	84.7	222	
	Suppor	t Vector Machine			
	RHOB, g/cm ³	DT _c , μs/ft	DT _s , μs/ft	E _{static} , GPa	
Minimum	2.31	44.3	73.2	7.50	
Maximum	2.98	78.9	136	92.8	
Range	0.67	34.6	62.9	85.3	
Standard Deviation	0.113	5.21	8.99	14.5	
Sample Variance	0.013	27.1	80.8	210	

The input training well logs data were selected based on their relative importance on the actual E_{static} which was determined in this study based on the correlation coefficient (R), Figure 3 compares R for the input well log data used to train the different machine learning model. As indicated in Figure 3, all well log parameters used to train the machine learning models are strongly related to E_{static} with high Rs of >0.7 for the bulk density, >0.8 for the compressional transit time, and >0.95 for the shear transit time.

Figure 4 shows the inputs used to learn the machine learning models. Inserted *for* loops were designed using MATLAB software to optimize all combinations of the machine learning model's design parameters for E_{static} estimation; every single *for* loop represents one design parameter. Sensitivity analysis was conducted to evaluate the effect of changing every single design parameter on the predictability of E_{static} by the different machine learning models considered in this study. The sensitivity analysis is a critical step in optimizing the design parameters of the machine learning models and several previous studies considered it as a crucial step in optimizing the performance of different mathematical models [54–56]. Based on the sensitivity analysis results, the combinations of the variables in Table 2 were found to optimize E_{static} estimation using the different machine learning models; these parameters predicted E_{static} with the lowest average absolute percentage error (AAPE) and the highest R; the AAPE was calculated using Equation (3).

$$AAPE = \frac{1}{N} \sum_{i=1}^{N} \left(\left| \frac{(E_{statica})_i - (E_{staticm})_i}{(E_{statica})_i} \right| \times 100 \right)$$
 (3)

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where N represents the number of the data points, a and m denote the actual and estimated E_{static} , respectively.

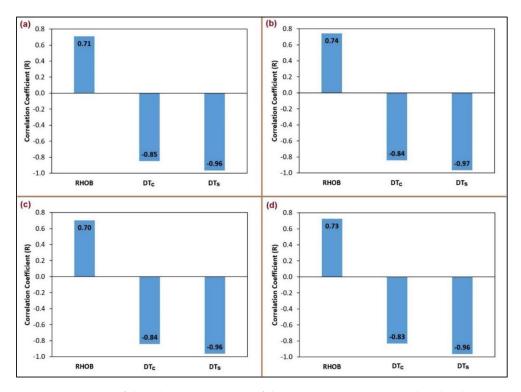


Figure 3. Comparison of the relative importance of the training parameters used to develop (a) ANN, (b) the Mamdani fuzzy interference system (M-FIS), (c) functional neural networks (FNN), and (d) support vector machine (SVM) models.

Table 2. Optimized design parameters for the machine learning models.

Artificial Neural Networks				
Training Data (out of total data from Well-A)	70%			
Testing Data (out of total data from Well-A)	30%			
Learning Function	Trainbr			
Transfer Function	Logsig			
Number of Training Layers	Single Layer			
Neurons per Training Layer	20			
Mamdani Fuzzy Ir	nterference System			
Training Data (out of total data from Well-A)	30%			
Testing Data (out of total data from Well-A)	70%			
Cluster Radius	0.3			
Number of Iterations	180			
Functional Ne	ural Networks			
Training Data (out of total data from Well-A)	60%			
Testing Data (out of total data from Well-A)	40%			
Training Method	Forward Selection Method			
Function Type	Non-linear Function with No Iteration Term			
Support Vec	tor Machine			
Training Data (out of total data from Well-A)	75%			
Testing Data (out of total data from Well-A)	25%			
Verbose	0.7			
C 3000				
Epsilon	0.5			
Lambda	1×10^{-7}			
Kernel	gaussian			
Kerneloption	9			

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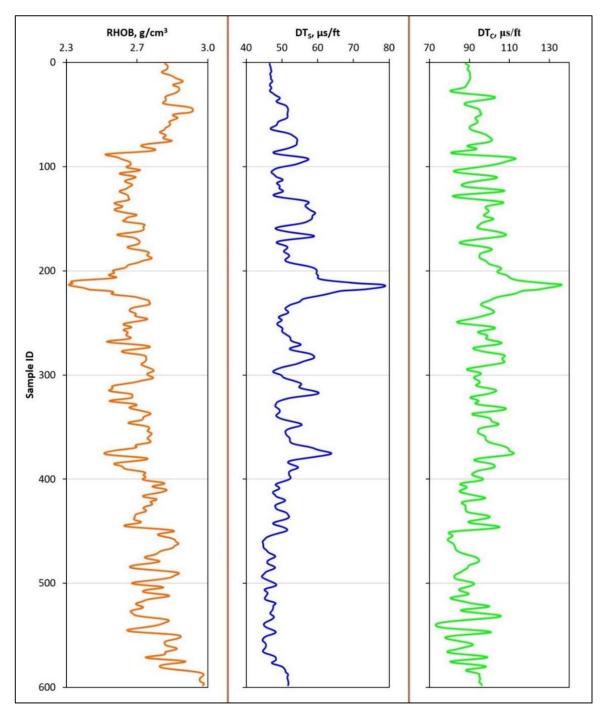


Figure 4. The training input well log data collected from Well-A.

4.3. Evaluation of the Developed Machine Learning Models

After training, the developed machine learning models were then tested using the remaining data collected from the same training sandstone formation in Well-A and then validated using 38 data points (unseen data) collected from a sandstone formation in Well-B.

Uncertainty quantification is at the heart of decision making, especially in subsurface applications. Uncertainty about the geological structures, rocks, and fluids is because of the lack of access to the subsurface geological medium [57,58]. The uncertainty in the prediction results of all machine learning models developed in this study was directly controlled by the uncertainty on the well log data used

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to develop these models which were highly controlled by the depth of investigation and vertical resolution of every logging tool.

5. Results and Discussion

5.1. Machine Learning Models Development

The machine learning models were trained to predict E_{static} as a function of the RHOB, DT_s , and DT_c . The training data were collected from Well-A. Figure 5 compares the actual and estimated E_{static} for the training dataset.

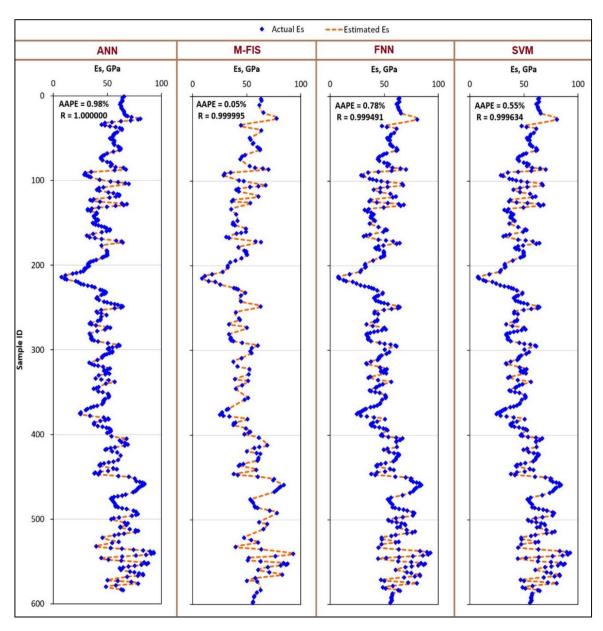


Figure 5. Actual and estimated static Young's modulus (E_{static}) for the training dataset collected from Well-A.

Figure 5 shows that all machine learning models predicted E_{static} with very high accuracy. M-FIS predicted E_{static} with AAPE of only 0.05% and R of 0.999995. FNN model estimated the E_{static} with AAPE and R of 0.78% and 0.999491, respectively, while SVM model estimated E_{static} with AAPE of 0.55% and R of 0.999634, and the ANN model predicted E_{static} with AAPE of 0.98% and R of 1.000000.

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The good matching between the actual and estimated E_{static} for the training dataset shown in Figure 5 proves the high accuracy of the machine learning models in evaluating E_{static} .

5.2. Testing the Developed Machine Learning Models

The performance of the developed machine learning models in evaluating the E_{static} for the testing dataset, which was collected from the same training formation used to developed machine learning models (i.e., from Well-A), was evaluated. As indicated in Figure 6, all machine learning models predicted E_{static} with very high accuracy. M-FIS predicted E_{static} for the testing dataset with AAPE and R of 0.09% and 0.999992, respectively, FNN model predicted E_{static} with AAPE of 0.85% and R of 0.999311, then SVM model which estimated E_{static} with an AAPE and R of 0.62% and 0.999813, respectively, and the ANN estimated E_{static} with AAPE of 1.46% and R of 1.000000. Visual check of the actual and estimated E_{static} of the testing data set also confirmed the high accuracy of the machine learning models, as indicated by the good matching between the actual and estimated E_{static} .

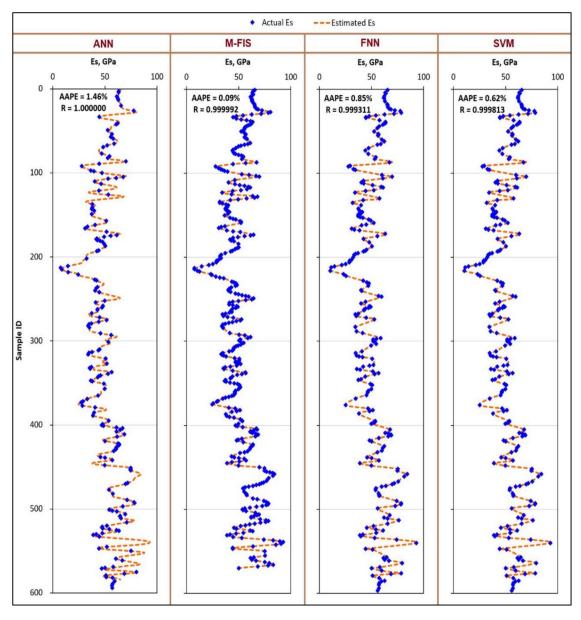


Figure 6. Actual and estimated E_{static} for the testing dataset collected from Well-A.

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5.3. Validation of the Developed Machine Learning Models

The machine learning models' accuracy was finally validated using 38 data points collected from another sandstone formation in Well-B. Figure 7 compares the actual core derived and estimated E_{static} using the developed machine learning for the validation data set. The results in Figure 7 confirmed that all machine learning models predicted E_{static} with very high accuracy. This figure also confirmed that M-FIS technique is the best among the others on estimating E_{static} for the validation data set, where the developed M-FIS predicted E_{static} with AAPE of 1.56% and R of 0.999, followed by SVM model which predicted E_{static} with AAPE of 2.03% and R of 0.999, then FNN model which estimated E_{static} with AAPE of 2.54% and R of 0.997, and the least accurate model was the ANN which predicted E_{static} with AAPE of 3.80% and R of 0.991.

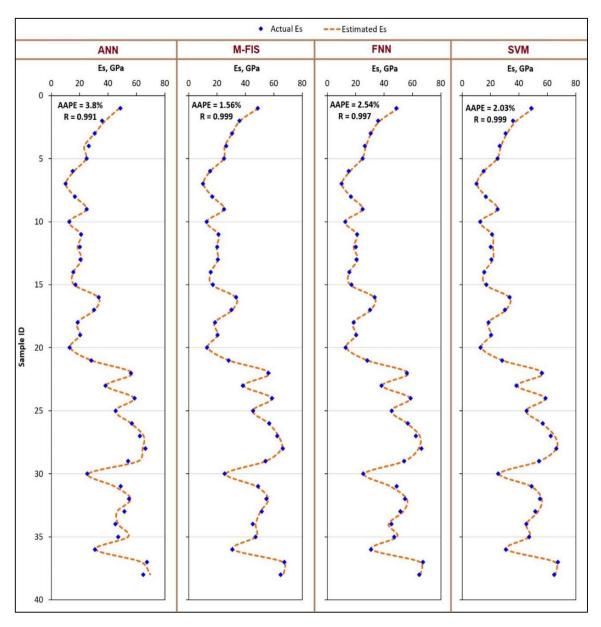


Figure 7. Core-derived and predicted E_{static} for the validation dataset collected from Well-B.

A visual check of the actual and estimated E_{static} of the validation data set also confirmed the high accuracy of all machine learning models considered in this work, as confirmed by the good matching between the estimated and core derived E_{static} . A continuous profile of E_{static} along the drilled sections of Well-B was obtained using the machine learning models. This is not possible to

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achieve by conducting laboratory work only. The confidence intervals for the validation data were \pm 0.574, \pm 0.804, \pm 0.843, and \pm 0.877, with a confidence level of 99% for M-FIS, SVM, ANN, and FNN models, respectively.

Figure 8 compares the AAPE for the calculated E_{static} for training, testing, and validation datasets using the different machine learning models. This figure confirms that the developed M-FIS model overperformed the other machine learning models in predicting E_{static} for the training, testing, and validation datasets in terms of AAPE. M-FIS predicted E_{static} with the lowest AAPE of 1.56 %, while the AAPE for the SVM, FNN, and ANN were 2.03, 2.54, and 3.80, respectively.

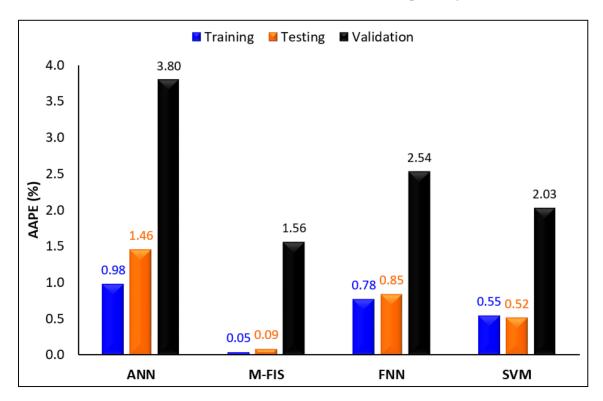


Figure 8. Comparison of the AAPE for the training, testing, and validation datasets for all machine learning models.

Out of the results of training, testing, and validation data and considering the similarity of the results of the evaluation parameters (AAPE and R) and taking into consideration that adding or omitting a few points may change the highest-to-lowest order of the models accuracy, we conclude that the four models are equally adequate to estimate E_{static} using only the conventional well log used in this study. Nevertheless, we recommend using the M-FIS model as it is the best-performed model for estimating E_{static} for the training, testing, and validation data.

The machine learning models developed in this work are very helpful for the petroleum engineers and petroleum industry since they could positively improve E_{static} estimation, therefore, enabling petroleum engineers and geoscientists to construct the earth geomechanical map and to evaluate the wellbore stability condition, the reservoir compaction, hydraulic fracturing, and the formation control [1,3].

6. Conclusions

Four machine learning techniques were applied in this study to develop models for estimating E_{static} for sandstone formations, these machine learning techniques were ANN, FNN, M-FIS, and SVM. The machine learning models were trained to evaluate E_{static} based on conventional well log data of the RHOB, DT_{s} , and DT_{c} . The machine learning models were trained and tested based on data gathered from sandstone formation in Well-A and then the developed models were validated on unseen data

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collected from a sandstone formation in Well-B. The outcomes of this work confirmed the high accuracy of all machine learning models, and M-FIS models overperformed all others in estimating E_{static} for training, testing, and validation data sets. For the validation data, M-FIS predicted E_{static} with a very low AAPE of 1.56% and R of 0.999. The high accuracy of the developed machine learning models was also confirmed by visual comparison of the estimated and actual E_{static} .

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Conflicts of Interest: The authors declare no conflict of interest.

Nomenclature

AAPE Average absolute percentage error

ANN Artificial neural networks
DT_c Compressional transit time

DT_s Shear transit time

 $\begin{array}{ll} E_{dynamic} & Dynamic Young's \ modulus \\ E_{static} & Static Young's \ modulus \\ FNN & Functional \ neural \ networks \end{array}$

M-FIS Mamdani fuzzy interference system

SVM Support vector machine R Correlation coefficient RHOB Formation bulk density

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