

Correction

Correction: Li et al. Automatic Point Cloud Registration for Large Outdoor Scenes Using a Priori Semantic Information. *Remote Sens.* 2021, 13, 3474

Remote Sensing Editorial Office

MDPI Branch Office, Beijing 101100, China; remotesensing@mdpi.com

Error in Figure

In the original article [1], there was a mistake in Figure 5 as published. The positions of subfigures (a) and (e) are reversed. This is because of a layout error. The correct figure appears below. The editorial office apologizes for any inconvenience caused and state that the scientific conclusions are unaffected. The original article has been updated.



Citation: Remote Sensing Editorial Office. Correction: Li et al. Automatic Point Cloud Registration for Large Outdoor Scenes Using a Priori Semantic Information. *Remote Sens.* 2021, 13, 3474. *Remote Sens.* 2022, 14, 2413. <https://doi.org/10.3390/rs14102413>

Received: 24 November 2021

Accepted: 6 May 2022

Published: 18 May 2022

Publisher's Note: MDPI stays neutral with regard to jurisdictional claims in published maps and institutional affiliations.



Copyright: © 2022 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

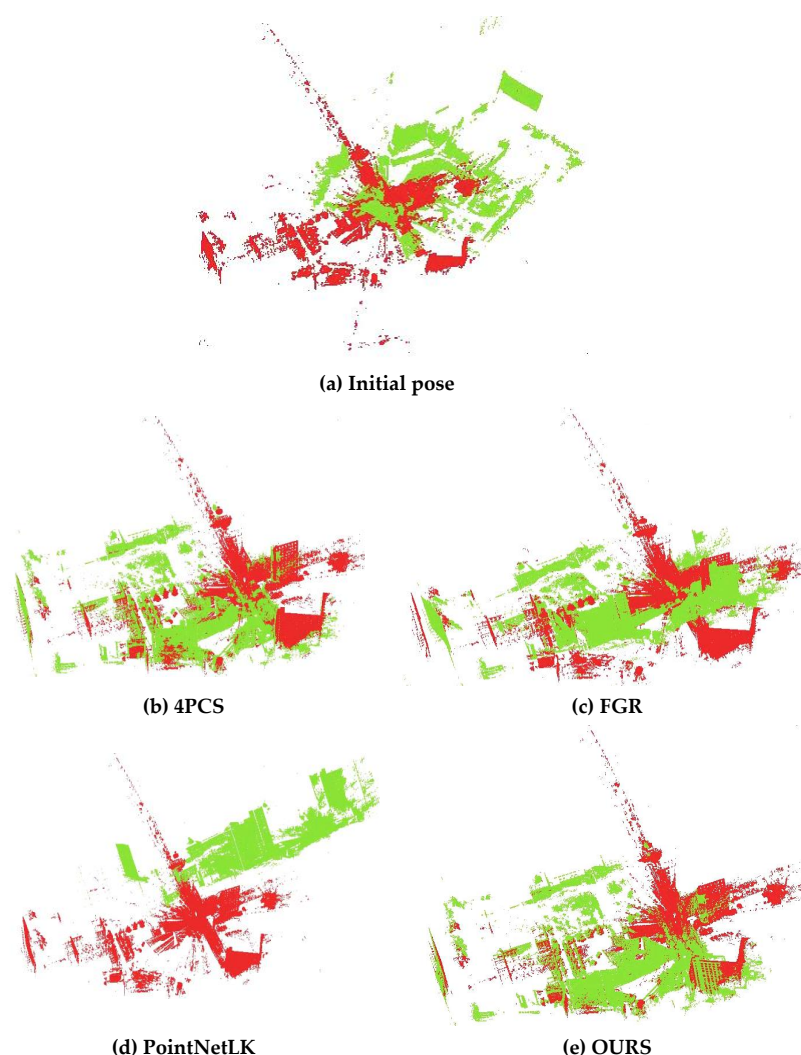


Figure 5. Registration results of each algorithm for campus scenes.

Reference

1. Li, J.; Huang, S.; Cui, H.; Ma, Y.; Chen, X. Automatic Point Cloud Registration for Large Outdoor Scenes Using a Priori Semantic Information. *Remote Sens.* **2021**, *13*, 3474. [[CrossRef](#)]