## Supplemental file

# Network as a biomarker: A novel network-based sparse Bayesian machine for pathway-driven drug response prediction 

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## 1 Approximate Bayesian Inference for parameter estimation in NBSBM using Expectation Propagation (EP) algorithm

Considering the labeling errors $\varepsilon$, given $\boldsymbol{X}=\left(\boldsymbol{x}_{1}, \cdots, \boldsymbol{x}_{n}\right), \boldsymbol{y}=\left(y_{1}, \cdots, y_{n}\right)$ and $\varepsilon$, the likelihood can be written as (1)

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\(p(\boldsymbol{y} \mid \beta, \varepsilon, \boldsymbol{X})=\prod_{i=1}^{n} p\left(y_{i} \mid \beta, \varepsilon, x_{i}\right)=\prod_{i=1}^{n}\left[\varepsilon\left(1-\Phi\left(y_{i} \beta^{T} x_{i}\right)\right)+(1-\varepsilon) \Phi\left(y_{i} \beta^{T} x_{i}\right)\right]=\)
\(\prod_{i=1}^{n}\left[\varepsilon+(1-2 \varepsilon) \Phi\left(y_{i} \beta^{T} x_{i}\right)\right]\)
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Where $\boldsymbol{\Phi}$ is the Heaviside step function and it is defined by equation (2)

$$
\begin{equation*}
\Phi\left(y_{i} \beta^{T} x_{i}\right)=\lim _{k \rightarrow \infty} \frac{1}{1+e^{-2 k\left(y_{i} \beta^{T} x_{i}\right)}} \tag{2}
\end{equation*}
$$

If we only consider the sparse solution for $\beta$. Herein we introduce a new binary hidden variable $\boldsymbol{z}=\left\{z_{0}, z_{1}, z_{2}, \cdots, z_{d}\right\} \in\{0,1\}^{d} . z_{i}$ takes 0 if the $i^{\text {th }}$ component of $\beta_{\text {true }}$ is 0 and $z_{i}$ takes 1 otherwise. Assuming $\mathbf{z}$ is given, the probability density of $\beta$ is shown in equation (3)

$$
\begin{equation*}
p(\beta \mid \mathbf{z})=\prod_{i=1}^{d} p\left(\beta_{i} \mid z_{i}\right)=\prod_{i=0}^{d}\left[\mathcal{N}\left(\beta_{i}, 0, \sigma_{i}^{2}\right)^{z_{i}}\left(\delta\left(\beta_{i}\right)\right)^{\left(1-z_{i}\right)}\right] \tag{3}
\end{equation*}
$$

where $p\left(\beta_{i} \mid z_{i}\right)$ is a Spike and Slab prior. $\mathcal{N}\left(\beta_{i}, 0, \sigma_{i}^{2}\right)$ represents Gaussian density function with 0 mean and $\sigma_{i}^{2}$ variance, $\delta\left(\beta_{i}\right)$ is an impulse function which has a probability of 1 on $\beta_{i}$ and 0 elsewhere. To complete the specification of the prior for $\boldsymbol{\beta}$ at zero, we assume that a network that encodes the dependencies between the gene features are known. Given a specific cancer signaling network $G=(V, E)$ whose vertices $V=\{0,1, \cdots, d\}$ correspond to the proteins and whose edges, E Equation (4) shows the prior probability for $\mathbf{z}$ given $G$ which is given by a Markov random field (MRF) model

$$
\begin{gather*}
p(z \mid G, \lambda, \gamma)=\frac{1}{z} \exp \left(c z_{0}+\lambda \sum_{i=1}^{d} z_{i}+\gamma \sum_{\{u, v\} \in E}\left(\frac{z_{u}}{\sqrt{d_{u}}}-\frac{z_{v}}{\sqrt{d_{v}}}\right)^{2} w(u, v)\right)=\frac{1}{z} \exp \left(c z_{0}+\right. \\
\left.\lambda \sum_{i=1}^{d} z_{i}\right) \exp \left(\gamma \sum_{\{u, v\} \in E}\left(\frac{z_{u}}{\sqrt{d_{u}}}-\frac{z_{v}}{\sqrt{d_{v}}}\right)^{2} w(u, v)\right) \tag{4}
\end{gather*}
$$

In equation (2), $\mathbf{Z}$ is a normalization constant and $\lambda \in \mathbb{R}$ controls the sparsity. $\gamma \geq 0$ determines the sum of square difference between $z_{u}$ and $z_{v}$ that are linked in the input network $G, \omega(u, v)$ is the weight between proteins $z_{u}$ and $z_{v}$. In fact, if we assume,

$$
L(u, v)=\left\{\begin{array}{c}
1-\frac{w(u, v)}{d_{u}}, \text { if } u=v \text { and } d_{u} \neq 0,  \tag{5}\\
\frac{-w(u, v)}{\sqrt{d_{u} d_{v}}}, \text { if } u \text { and } v \text { are adjacent }, \\
0, \\
\text { othersize. }
\end{array}\right.
$$

then

$$
\begin{equation*}
p(\mathbf{z} \mid G, \lambda, \gamma)=\frac{1}{z} \exp \left(c z_{0}+\lambda|\boldsymbol{z}|\right) \exp \left(\gamma \mathbf{z}^{T} L \boldsymbol{z}\right) \tag{6}
\end{equation*}
$$

Furthermore, we assume the prior of $\varepsilon$ as

$$
\begin{equation*}
p(\varepsilon)=\operatorname{Beta}\left(\varepsilon, a_{0}, b_{0}\right)=\frac{1}{B\left(a_{0}, b_{0}\right)} \varepsilon^{a_{0}-1}(1-\varepsilon)^{b_{0}-1} \tag{7}
\end{equation*}
$$

where $B\left(a_{0}, b_{0}\right)$ represents beta function with parameters $a_{0}$ and $b_{0}$. Under the assumption above, we can use Bayesian theorem to compute the posterior distribution of the model parameters $\boldsymbol{\beta}$ and $\varepsilon$ given the training data $\boldsymbol{X}$ and $\boldsymbol{y}$. Given the specific cancer signaling network $G$ and the model hyper-parameters $\lambda$ and $\gamma$, the posterior is given by

$$
\begin{equation*}
p(\beta, \varepsilon \mid y, X, G, \lambda, \gamma)=\frac{\sum_{z} p(y \mid \beta, \varepsilon, X) p(\beta \mid z) p(z \mid G, \lambda, \gamma) p(\varepsilon)}{p(y \mid X, G, \lambda, \gamma)} \tag{8}
\end{equation*}
$$

If given a new unclassified sample $x^{\text {test }}$, we can determine its classification labels $y^{\text {test }}$ by probability as shown in equation (9)

$$
\begin{equation*}
p\left(y^{\text {test }} \mid X^{\text {test }}, y, \boldsymbol{X}, G, \lambda, \gamma\right)=\iint p\left(y^{\text {test }} \mid \boldsymbol{\beta}, \varepsilon, x^{\text {test }}\right) p(\boldsymbol{\beta}, \varepsilon \mid y, \boldsymbol{X}, G, \lambda, \gamma) d \boldsymbol{\beta} d \varepsilon \tag{9}
\end{equation*}
$$

Then the relevance of the features can be quantified by the posterior of $\boldsymbol{z}$,

$$
\begin{equation*}
p(\boldsymbol{z} \mid \boldsymbol{y}, \mathbf{X}, G, \lambda, \gamma)=\frac{\sum_{z} \sum_{\varepsilon} p(\boldsymbol{y} \mid \boldsymbol{\beta}, \varepsilon, \mathbf{X}) p(\boldsymbol{\beta} \mid \mathbf{z}) p(\mathbf{z} \mid G, \lambda, \gamma) p(\varepsilon)}{p(\boldsymbol{y} \mid \mathbf{X}, G, \lambda, \gamma)} \tag{10}
\end{equation*}
$$

In specific, the relevance of the $i$-th feature to the classification result is a value between 0 and 1 and is given by the marginal probability $p(\mathbf{z} \mid \boldsymbol{y}, \mathbf{X}, G, \lambda, \gamma)$ with $\mathbf{z}=1$. The higher the value, the more relevant of this gene with respect to the classification result. The joint probability distributions of model parameters and hidden variables are given as follows:

$$
\begin{equation*}
p(\beta, \varepsilon, \mathbf{z}, \boldsymbol{y} \mid \mathbf{X}, G, \lambda, \gamma)=p(y \mid \beta, \varepsilon, \mathbf{X}) p(\beta \mid \mathbf{z}) p(\mathbf{z} \mid G, \lambda, \gamma) p(\varepsilon) \tag{11}
\end{equation*}
$$

It can be written as the product of $N+|E|+3$ probabilities in equation (11) according to the assumption of independence.

$$
p(\beta, \varepsilon, \mathbf{z}, \mathbf{y} \mid \mathbf{X}, G, \lambda, \gamma)=\left[\prod_{i=1}^{n} p\left(y_{i} \mid \beta, \varepsilon, \mathbf{x}_{i}\right)\right]\left[\prod_{i=0}^{d} p\left(\beta_{i} \mid z_{i}\right)\right] p(\mathbf{z} \mid G, \lambda, \gamma) p(\varepsilon)=\prod_{i=1}^{n+|E|+3} t_{i}(\beta, \varepsilon, \mathbf{z})=
$$

Where $|E|$ refers to the number of edges in graph $G$. The first $n$ terms of $t_{i}(\beta, \varepsilon, z)$ denote the likelihood $p\left(y_{i} \mid \beta, \varepsilon, x_{i}\right)$, while $t_{n+1}(\beta, \varepsilon, z), \prod_{i=n+2}^{n+|E|+2} t_{i}(\beta, \varepsilon, z)$ and $t_{n+|E|+3}(\beta, \varepsilon, z)$ represent $p(\beta \mid \mathbf{z}), p(\mathbf{z} \mid G, \lambda, \gamma)$ and $p(\varepsilon)$ respectively. According to the expectation propagation algorithm, we use $\widetilde{t_{l}}$ as the estimation of $t_{i}$ and get (13)

$$
\begin{equation*}
\prod_{i=1}^{n+|E|+3} t_{i}(\beta, \varepsilon, \mathbf{z}) \approx \prod_{i=1}^{n+|E|+3} \tilde{t}_{l}(\beta, \varepsilon, \mathbf{z})=Q(\beta, \varepsilon, \mathbf{z}) \tag{13}
\end{equation*}
$$

It is restricted that all $\tilde{t}_{l}$ belong to the same exponential family of distributions, and $Q(\beta, \varepsilon, \mathbf{z})$ have the same expression with $\tilde{t}_{l}(\beta, \varepsilon, \mathbf{z})$ because the product of functions belonging to the same exponential family of distributions is a closure. Assume that the density function of $Q$ after normalization is $\mathcal{Q}$, which is also the approximation of the posterior distribution $p(\beta, \varepsilon, \mathbf{z}, \boldsymbol{y} \mid \mathbf{X}, G, \lambda, \gamma)$, and use $\mathcal{Q}^{\backslash i}(\beta, \varepsilon, \mathbf{z})$ to denote the approximation of $\mathcal{Q}(\beta, \varepsilon, z)$ without the term $t_{i}$ as shown in (8)

$$
\begin{equation*}
\mathcal{Q}^{\backslash i}(\beta, \varepsilon, \mathbf{z})=\prod_{j \neq i} \widetilde{t_{l}}(\beta, \varepsilon, \mathbf{z})=\frac{Q(\beta, \varepsilon, \mathbf{z})}{\widetilde{t_{l}}(\beta, \varepsilon, \mathbf{z})} \tag{14}
\end{equation*}
$$

a general workflow of the expectation propagation algorithm for the sparse Bayesian classifier can be given as follows,

1. Initialize all $\tilde{t}_{l}$ and posterior distribution $\mathcal{Q}$;
2. Repeat the following steps until all $\tilde{t_{l}}$ converge.
(a) Select one $\tilde{t}_{l}$ that needs to be changed and calculate $\mathcal{Q}^{\backslash i}: \mathcal{Q}^{\backslash i}=\mathcal{Q} / \widetilde{t_{l}}$
(b) Update the value of $Q$ to minimize the Kullback-Leibler(KL) divergence between $t_{i} \mathcal{Q}^{\backslash i}$ and $\widetilde{t}_{l} Q^{\backslash i}$.
(c) Recalculate $\widetilde{t_{l}}=\mathcal{Q}^{\text {new }} / Q^{\backslash i}$.

## 3. Estimate model parameters.

In fact, according to (1), (3), (4) and (5), we can approximate $\tilde{t}_{l}$ based on function (14)

$$
\begin{equation*}
\widetilde{t_{l}}(\beta, \varepsilon, \mathbf{z})=\widetilde{s_{l}} \varepsilon^{\widetilde{a_{l}}}(1-\varepsilon)^{\widetilde{b_{l}}} \prod_{j=0}^{d} \exp \left(-\frac{1}{2 \widetilde{v_{l \jmath}}}\left(\beta_{j}-\widetilde{m_{l \jmath}}\right)^{2}\right)\left(z_{i} \widetilde{c_{l \jmath}}+\left(1-z_{i}\right) \widetilde{d_{l \jmath}}\right) \tag{15}
\end{equation*}
$$

Where $\widetilde{\boldsymbol{m}_{\boldsymbol{l}}}=\left(\widetilde{m_{l 0}}, \ldots \widetilde{m_{l d}}\right)^{T}, \widetilde{\boldsymbol{v}_{\boldsymbol{t}}}=\left(\widetilde{v_{l 0}}, \ldots \widetilde{v_{l d}}\right)^{T}, \widetilde{\boldsymbol{c}_{\boldsymbol{t}}}=\left(\widetilde{c_{l 0}}, \ldots \widetilde{c_{l d}}\right)^{T}, \widetilde{\boldsymbol{d}_{\boldsymbol{l}}}=\left(\widetilde{d_{l 0}}, \ldots \widetilde{d_{l d}}\right)^{T}$ and $\widetilde{\boldsymbol{c}_{\boldsymbol{l}}}=1-\widetilde{\boldsymbol{d}_{\boldsymbol{l}}} \cdot \widetilde{\boldsymbol{a}_{\boldsymbol{l}}}$ and $\widetilde{\boldsymbol{b}_{\boldsymbol{l}}}$ are free parameters and $\widetilde{s_{l}}$ is a constant to ensure that $\widetilde{t_{l}} Q^{\backslash i}$ and $t_{i} Q^{\backslash i}$ get the same value when integrating. According to the previous assumption that all $\widetilde{t_{l}}$ belong to the same exponential family of distributions, $\mathcal{Q}$ and $\tilde{t}_{l}$ have the same form and we can assume that $\mathcal{Q}$ can be expressed as shown in (15).

$$
\begin{equation*}
\mathcal{Q}(\beta, \varepsilon, \mathbf{z})=\operatorname{Beta}(\varepsilon \mid a, b) \prod_{j=0}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}, v_{j}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{i}\right) \tag{16}
\end{equation*}
$$

Formula (15) has the same form as (16), and

$$
\begin{equation*}
\operatorname{Bern}\left(z_{i} \mid \rho_{i}\right)=z_{i} \rho_{i}+\left(1-z_{i}\right)\left(1-\rho_{i}\right) \tag{17}
\end{equation*}
$$

Where $z_{i} \in\{0,1\}$ and $\rho_{i}$ is the probability of $z_{i}=1 . \mathbf{m}=\left(m_{0}, \ldots, m_{d}\right)^{T}, \mathbf{v}=\left(v_{0}, \ldots, v\right)^{T}, \boldsymbol{\rho}=$ $\left(\rho_{0}, \ldots, \rho_{d}\right)^{T}$. Firstly, we initialize $\mathcal{Q}$ and $\widetilde{t}_{l}$ by setting $\mathrm{a}=\mathrm{b}=1, m_{i}=0, v_{i}=+\infty, \rho_{i}=0.5, \widetilde{m_{l j}}=$ $0, \widetilde{v_{l j}}=+\infty$ and $\widetilde{c_{l j}}=\widetilde{d_{l j}}=1$ for $i$ in range $[1, n+|E|+3]$ and $j$ in range $[0, d]$. Besides, as $Q$ and $Q^{\backslash i}$ has the same form without approximation term $\tilde{t}_{\nu}$ we can make following assumption

$$
\begin{aligned}
& Q^{\backslash i}(\beta, \varepsilon, \mathbf{z})=\operatorname{Beta}\left(\varepsilon \mid a^{\backslash i}, b^{\backslash i}\right) \prod_{j=0}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{\backslash i}, v_{j}{ }^{\backslash i}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{i}{ }^{\backslash i}\right) \\
& \boldsymbol{m}^{\backslash i}=\left(m_{0}{ }^{\backslash i}, \ldots m_{d} \backslash i\right)^{T}, \boldsymbol{v}^{\backslash i}=\left(v_{0}{ }^{\backslash i}, \ldots v_{d} \backslash i\right)^{T}, \boldsymbol{\rho}^{\backslash i}=\left(\rho_{0}{ }^{\backslash i}, \ldots \rho_{d} \backslash i\right)^{T}, a^{\backslash i} \text { and } b^{\backslash i} \text { can be }
\end{aligned}
$$ calculated based on $Q^{\backslash i}=Q / \widetilde{t_{l}}$ and formula (15), (16).

$$
\begin{gather*}
\boldsymbol{v}^{\backslash i}=\left(\boldsymbol{v}^{-1}-\widetilde{\boldsymbol{v}}_{l}^{-1}\right)^{-1}  \tag{19}\\
\boldsymbol{m}{ }^{i i}=\boldsymbol{m}+\boldsymbol{v}^{\backslash i} \circ \widetilde{\boldsymbol{v}}_{l}^{-1} \circ\left(\boldsymbol{m}-\widetilde{\boldsymbol{m}}_{\boldsymbol{l}}\right)  \tag{20}\\
\boldsymbol{\rho}^{\backslash i}=\boldsymbol{\rho} \circ \widetilde{\boldsymbol{c}}_{\boldsymbol{\imath}}  \tag{21}\\
a^{-1} \circ\left(\boldsymbol{\rho} \circ \widetilde{\boldsymbol{c}}_{\boldsymbol{\imath}}\right.  \tag{22}\\
\left.a^{-1}+(1-\boldsymbol{\rho}) \circ \widetilde{\boldsymbol{d}}_{\boldsymbol{l}}^{-1}\right)^{-1}  \tag{23}\\
b^{\backslash i}=b-{\widetilde{a_{\imath}}}_{\imath}
\end{gather*}
$$

Where' $\circ$ ' denotes the Hadamard production and the inverse of a vector means the inverse of each component of the vector. Meanwhile we have $\widetilde{t}_{l}$ satisfying (24)-(28) which can be used to update the value of $\tilde{t}_{l}$ according to the property of the exponential family functions

$$
\begin{gather*}
\mathbb{E}_{\tilde{t}_{l} Q^{\backslash i}}[\beta]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta]  \tag{24}\\
\mathbb{E}_{\tilde{\tau}_{l} Q^{\backslash i}}[\beta \circ \beta]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta \circ \beta]  \tag{25}\\
\mathbb{E}_{\tilde{t}_{Q^{Q}} Q^{\backslash i}}[\mathbf{z}]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\mathbf{z}]  \tag{26}\\
\mathbb{E}_{\tilde{\tau}_{Q_{Q}} Q^{\backslash i}}[\log (\varepsilon)]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\log (\varepsilon)]  \tag{27}\\
\mathbb{E}_{\tilde{\tau}_{l} Q^{\backslash i}}[\log (1-\varepsilon)]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\log (1-\varepsilon)] \tag{28}
\end{gather*}
$$

We need to update the parameters in $\tilde{t}_{l}$ according to $p\left(y_{i} \mid \beta, \varepsilon, x_{i}\right)$ so that $\tilde{t}_{l}$ match the constraints in (24)-(28) while minimizing the KL-divergence between $\tilde{\tau}_{l} Q^{\backslash i}$ and $t_{i} Q^{\backslash i}$. We can get (29) (30) based on (1), (18), (24), (25)

$$
\begin{gather*}
\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta]=\boldsymbol{m}^{\backslash i}+\boldsymbol{v}^{\backslash i} \nabla_{m} \log Z_{i}  \tag{29}\\
\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta \circ \beta]-\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta] \mathbb{E}_{t_{i} Q^{\backslash i}}[\beta]^{T}=\boldsymbol{v}^{\backslash i}-\boldsymbol{v}^{\backslash i} \boldsymbol{v}^{\backslash i}\left(\nabla_{m}{ }^{T} \nabla_{m}-2 \nabla_{v} \log Z_{i}\right)  \tag{30}\\
Z_{i}=\int\left(\varepsilon+(1-2 \varepsilon) \Phi\left(y_{i} \beta^{T} \boldsymbol{x}_{i}\right)\right) \operatorname{Beta}\left(\varepsilon \mid a^{\backslash i}, b^{\backslash i}\right) \prod_{j=1}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{\backslash i}, v_{j} \backslash i\right) \operatorname{Bern}\left(z_{j} \mid \rho_{j} \backslash i\right) d \beta \tag{31}
\end{gather*}
$$

By substituting (29), (30) and (31) into (24) and (25), we can get

$$
\begin{align*}
& \boldsymbol{m}^{\text {new }}=\boldsymbol{m}^{\backslash i}+\boldsymbol{v}^{\backslash i} \circ \frac{\left(1-2 \bar{\varepsilon}^{\backslash i}\right) \mathcal{N}\left(\lambda_{i}, 0,1\right)}{\bar{\varepsilon}^{i}+\left(1-\bar{\varepsilon} \backslash^{i}\right) \Phi\left(\lambda_{i}\right)} \frac{y_{i} x_{i}}{\sqrt{x_{i}^{T} \boldsymbol{v}^{i} x_{i}}}  \tag{32}\\
& \boldsymbol{v}^{n e w}=\boldsymbol{v}^{\backslash i}-\boldsymbol{v}^{\backslash i} \boldsymbol{v}^{\backslash i}\left(\left(\frac{(1-2 \bar{\varepsilon}) \mathcal{N}\left(\lambda_{i}, 0,1\right)}{\bar{\varepsilon}^{\backslash i}+\left(1-2 \bar{\varepsilon}^{\backslash i}\right) \Phi\left(\lambda_{i}\right)}\right)^{2} \frac{\left(y_{i} \boldsymbol{x}_{i}\right) \circ\left(y_{i} \boldsymbol{x}_{i}\right)}{\boldsymbol{x}_{\boldsymbol{i}}^{T} \backslash^{i} \boldsymbol{x}_{i}}-2 \frac{\left(1-2 \bar{\varepsilon}^{i}\right) \mathcal{N}\left(\lambda_{i}, 0,1\right)}{\bar{\varepsilon}^{i}+\left(1-2 \bar{\varepsilon}^{i}\right) \Phi\left(\lambda_{i}\right)}-\frac{y_{i}(\boldsymbol{m} \backslash i)^{T} \boldsymbol{x}_{i}}{2} \frac{\boldsymbol{x}_{i} \circ \boldsymbol{x}_{i}}{\boldsymbol{x}_{i}^{T} \boldsymbol{v} \backslash i \boldsymbol{x}_{i} \sqrt{\boldsymbol{x}_{\boldsymbol{i}}^{T} v^{i} \boldsymbol{x}_{\boldsymbol{i}}}}\right. \tag{33}
\end{align*}
$$

After simplifying (33), we get (34)

$$
\begin{equation*}
\boldsymbol{v}^{\text {new }}=\boldsymbol{v}^{\backslash i}-\left(\boldsymbol{v}^{\backslash i} \circ \boldsymbol{x}_{i}\right)\left(\boldsymbol{v}^{\backslash i} \circ \boldsymbol{x}_{i}\right)=\frac{y_{i} \alpha_{i} \boldsymbol{x}_{i}^{T} \boldsymbol{m}^{\text {new }}}{\boldsymbol{x}_{i}^{T} \boldsymbol{v}^{i} \boldsymbol{x}_{i} \sqrt{\boldsymbol{x}_{i}^{T} \boldsymbol{v}^{\backslash i} \boldsymbol{x}_{i}}} \tag{34}
\end{equation*}
$$

In equations (32), (33) and (34), we have the following

$$
\begin{gather*}
\alpha_{i}=\frac{(1-2 \bar{\varepsilon}) \mathcal{N}\left(\lambda_{i}, 0,1\right)}{\overline{\bar{\varepsilon}^{\backslash i}+(1-2 \bar{\varepsilon} \backslash i) \Phi\left(\lambda_{i}\right)}}  \tag{35}\\
\lambda_{i}=\frac{y_{i}\left(\boldsymbol{m}^{\backslash i}\right)^{T} x_{i}}{\sqrt{x_{i}^{T} \boldsymbol{v}^{i} \boldsymbol{x}_{i}}}  \tag{36}\\
\bar{\varepsilon}^{\backslash i}=\frac{a^{\backslash i}}{a^{\backslash i}+b^{\backslash i}}  \tag{37}\\
Z_{i}=\bar{\varepsilon}^{\backslash i}+\left(1-2 \bar{\varepsilon}^{\backslash i}\right) \Phi\left(\lambda_{i}\right) \tag{38}
\end{gather*}
$$

Here $\Phi$ is the cumulative distribution function of the standard normal distribution. According to formulas (27) and (28), we can obtain the following updating rules for $a$ and $b$.

$$
\begin{align*}
& \Psi\left(a^{\text {new }}\right)-\Psi\left(a^{n e w}+b^{n e w}\right) \frac{\bar{\varepsilon}^{\backslash i}\left(1-\Phi\left(\lambda_{i}\right)\right)}{a^{\backslash i}\left[\bar{\varepsilon} \backslash i+(1-2 \bar{\varepsilon} \backslash i) \Phi\left(\lambda_{i}\right)\right]}+\Psi\left(a^{\backslash i}\right)-\Psi\left(a^{\backslash i}+b^{\backslash i}+1\right)  \tag{39}\\
& \Psi\left(b^{n e w}\right)-\Psi\left(a^{n e w}+b^{n e w}\right) \frac{\bar{\varepsilon}^{\backslash i}\left(1-\Phi\left(\lambda_{i}\right)\right)}{b^{\backslash i}\left[\bar{\varepsilon} \backslash^{i}+\left(1-2 \bar{\varepsilon}^{i}\right) \Phi\left(\lambda_{i}\right)\right]}+\Psi\left(b^{\backslash i}\right)-\Psi\left(a^{\backslash i}+b^{\backslash i}+1\right) \tag{40}
\end{align*}
$$

Where $\Psi(x)=d \log (\Gamma(x))$ and $\Gamma$ is the gamma function. As for the fact that $\Psi(x)$ is a nonlinear function, we can only use numerical solution to update $a^{\text {new }}$ and $b^{\text {new }}$. In order to avoid the computational complexity, the expectation propagation of $\varepsilon$ and $\varepsilon^{2}$ are used instead of the expectation propagation of $\log (\varepsilon)$ and $\log (1-\varepsilon)$. Although it is not guaranteed to minimize the KL divergence, the results are still accurate according to (Hernández-Lobato and Hernández-Lobato, 2008) and (Miguel Hernández-Lobato, et al., 2011). In other words, we can use (41) and (42) to update the value of $a^{\text {new }}$ and $b^{\text {new }}$

$$
\begin{align*}
\mathbb{E}_{\tilde{t}_{l} Q^{\backslash i}}[\varepsilon] & =\mathbb{E}_{t_{i} Q^{\backslash i}}[\varepsilon]  \tag{41}\\
\mathbb{E}_{\tilde{t}_{l} Q^{\backslash i}}[\varepsilon \circ \varepsilon] & =\mathbb{E}_{t_{i} Q^{\backslash i}}[\varepsilon \circ \varepsilon] \tag{42}
\end{align*}
$$

After simplifying the equations we get

$$
\begin{equation*}
b^{\text {new }}=\frac{\mathbb{E}_{t_{i} Q^{\backslash i}}[\varepsilon]-\mathbb{E}_{t_{i} Q^{\backslash i}}\left[\varepsilon^{2}\right]}{\mathbb{E}_{t_{i} Q^{\backslash i}}\left[\varepsilon^{2}\right]-\mathbb{E}_{t_{i} Q^{\backslash i}}[\varepsilon]^{2}}\left(1-\mathbb{E}_{t_{i} Q^{\backslash i}}[\varepsilon]\right) \tag{44}
\end{equation*}
$$

In the above two equations, we have

$$
\begin{gather*}
\mathbb{E}_{t_{i} Q^{\backslash i}[\varepsilon]=} \frac{1}{Z_{i}\left(a^{\backslash i}+b^{\backslash i}+1\right)}\left[\Phi\left(\lambda_{i}\right)\left(1-\bar{\varepsilon}^{\backslash i}\right) a^{\backslash i}+\left(1-\Phi\left(\lambda_{i}\right)\right) \bar{\varepsilon}^{\backslash i}\left(a^{\backslash i}+1\right)\right]  \tag{45}\\
\mathbb{E}_{t_{i} Q^{\backslash i}}\left[\varepsilon^{2}\right]=\frac{a^{\backslash i}+1}{Z_{i}\left(a^{\backslash i}+b^{\backslash i}+1\right)\left(a^{\backslash i}+b^{\backslash i}+2\right)}\left[\Phi\left(\lambda_{i}\right)\left(1-\bar{\varepsilon}^{\backslash i}\right) a^{\backslash i}+\left(1-\Phi\left(\lambda_{i}\right)\right) \bar{\varepsilon}^{\backslash i}\left(a^{\backslash i}+2\right)\right] \tag{46}
\end{gather*}
$$

As for the approximation of $t_{n+1}$, or namely $p(\beta \mid z)$, we have (24), (25) and (26) here according to the infer from the minimum $K L$ divergence between $t_{i} Q^{\backslash i}$ and $\tilde{t}_{i} \mathcal{Q}^{\backslash i}$

$$
\begin{gather*}
\mathbb{E}_{\widetilde{t}_{l} Q^{\backslash}}[\beta]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta]  \tag{47}\\
\mathbb{E}_{\tilde{t}_{l} Q^{\backslash i}}[\beta \circ \beta]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\beta \circ \beta]  \tag{48}\\
\mathbb{E}_{\tilde{t}_{l} Q^{\backslash i}}[\boldsymbol{z}]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\boldsymbol{z}] \tag{49}
\end{gather*}
$$

Based on the above three equations, the rules for updating $\boldsymbol{m}, \boldsymbol{v}$ and $\boldsymbol{\rho}$ can be derived as follows.

$$
\begin{align*}
& \boldsymbol{m}^{n e w}=\boldsymbol{m}^{\backslash i}+k^{\prime} \circ \boldsymbol{v}^{\backslash i}  \tag{50}\\
& \boldsymbol{v}^{n e w}=\boldsymbol{v}^{\backslash i}-k^{\prime \prime \prime} \circ \boldsymbol{v}^{\backslash i} \circ \boldsymbol{v}^{\backslash i}  \tag{51}\\
& \boldsymbol{\rho}^{n e w}=\boldsymbol{\rho}^{\backslash i}+\boldsymbol{\rho}^{\backslash i}(\boldsymbol{\rho} \backslash i) \nabla_{\boldsymbol{\rho}} \log Z_{i}  \tag{52}\\
& \boldsymbol{\rho}^{n e w}=\boldsymbol{\rho}^{\backslash i}+\frac{\left(g^{\prime \prime}-g^{\prime \prime \prime}\right) \boldsymbol{\rho}\left(1-\boldsymbol{\rho}^{\backslash i}\right)}{\boldsymbol{\rho}^{i_{\circ}} g^{\prime \prime}+\left(1-\boldsymbol{\rho}^{i}\right) \circ g^{\prime \prime \prime}}  \tag{53}\\
& \boldsymbol{\rho}^{n e w}=\boldsymbol{\rho} \backslash i \circ g^{\prime \prime} \circ\left(\boldsymbol{\rho} \backslash i \circ g^{\prime \prime}+\left(1-\boldsymbol{\rho}^{\backslash i}\right) g^{\prime \prime \prime}\right) \tag{54}
\end{align*}
$$

$k^{\prime}, k^{\prime \prime \prime}, g^{\prime \prime}$ and $g^{\prime \prime \prime}$ in above equations can be given as follows

$$
\begin{align*}
& g^{\prime \prime}=\mathcal{N}\left(0, \boldsymbol{m}^{\backslash i}, \boldsymbol{v}^{\backslash i}+\sigma^{2}\right)  \tag{55}\\
& g^{\prime \prime \prime}=\mathcal{N}\left(0, \boldsymbol{m}^{\backslash i}, \boldsymbol{v} \backslash i\right)  \tag{56}\\
& g^{\prime}=\boldsymbol{\rho}^{\backslash i} \circ g^{\prime \prime}+(1-\boldsymbol{\rho} \backslash i) \circ g^{\prime \prime \prime}  \tag{57}\\
& k^{\prime}=-\frac{\boldsymbol{\rho}^{\backslash i_{\circ}} g^{\prime \prime} \circ m^{\backslash i}}{g^{\prime} \circ\left(\boldsymbol{v}^{\backslash i}+\sigma^{2}\right)}-\frac{\left(1-\boldsymbol{\rho}^{\backslash i}\right) \circ g^{\prime \prime \prime} \circ m^{\backslash i}}{g^{\circ} \circ \boldsymbol{v}^{\backslash i}} \tag{58}
\end{align*}
$$

$$
\begin{gather*}
k^{\prime \prime}=\frac{\boldsymbol{\rho}^{\backslash i} \circ g^{\prime \prime} \circ m \backslash i \circ m \backslash i}{g^{\prime} \circ\left(\boldsymbol{v}^{i}+\sigma^{2}\right) \circ\left(\boldsymbol{v}^{\backslash i}+\sigma^{2}\right)}-\frac{\boldsymbol{\rho}^{\backslash i} \circ g^{\prime \prime}}{g^{\prime} \circ\left(\boldsymbol{v} \backslash^{i}+\sigma^{2}\right)}+\frac{\left(1-\boldsymbol{\rho}^{\backslash i}\right) \circ g^{\prime \prime \prime} \circ m \backslash i^{i} \circ \mathrm{~m}^{i i}}{g^{\prime} \circ \boldsymbol{v} \backslash^{i} \circ \boldsymbol{v} \backslash i}-\frac{\left(1-\boldsymbol{\rho}^{\backslash i}\right) \circ g^{\prime \prime \prime}}{g^{\prime} \circ \boldsymbol{v} \backslash i}  \tag{59}\\
k^{\prime \prime \prime}=k^{\prime} \circ k^{\prime}-k^{\prime \prime} \tag{60}
\end{gather*}
$$

$Z_{n+1}$ can be given as follows while Beta $\left(\varepsilon \mid a^{\backslash i}, b^{\backslash i}\right)$ does not contain $\beta$ and $Z_{i}$

$$
\begin{equation*}
Z_{i}=\int\left(\mathcal{N}\left(\beta_{i}, 0, \sigma_{i}^{2}\right)^{z_{i}} \delta\left(\beta_{i}\right)^{\left(1-z_{i}\right)}\right) \prod_{j=1}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{i i}, v_{j}{ }^{\backslash i}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{j}{ }^{\backslash i}\right) d \beta \mathrm{~d} \mathbf{z}=\prod_{j=0}^{d} g_{j}^{\prime} \tag{61}
\end{equation*}
$$

As for the approximation of $\widetilde{t}_{l}$ for $t_{i} \in \mathrm{p}(\mathbf{z} \mid \mathrm{G}, \lambda, \gamma)(i=n+2 \ldots, n+|E|+2)$, we have formula (4) here

$$
\begin{gather*}
p(\mathbf{z} \mid G, \lambda, \gamma)=\frac{1}{Z} \exp \left(c z_{0}\right) \exp \left(\lambda \sum_{i=1}^{d} z_{i}+\gamma \sum_{\{u, v\} \in E}\left(\frac{z_{u}}{\sqrt{d_{u}}}-\frac{z_{v}}{\sqrt{d_{v}}}\right)^{2} w(u, v)\right) \\
=\frac{1}{z} \exp \left(c z_{0}+\lambda \sum_{i=1}^{d} z_{i}\right) \exp \left(\gamma \sum_{\{u, v\} \in E}\left(\frac{z_{u}}{\sqrt{d_{u}}}-\frac{z_{v}}{\sqrt{d_{v}}}\right)^{2} w(u, v)\right) \tag{62}
\end{gather*}
$$

Firstly, we need to approximate the priori sparse term $\exp \left(c z_{0}+\lambda \sum_{i=1}^{d} z_{i}\right)$ and the following formula holds

$$
\begin{equation*}
\mathbb{E}_{\tilde{t}_{l} Q^{i}}[\mathbf{z}]=\mathbb{E}_{t_{i} Q^{\backslash i}}[\mathbf{z}] \tag{63}
\end{equation*}
$$

And $Z_{i}$ can be calculated by

$$
\begin{equation*}
Z_{i}=\int\left(\exp \left(h_{i} z_{i}\right) \operatorname{Beta}\left(\varepsilon \mid a^{\backslash i}, b^{\backslash i}\right)\right) \prod_{j=1}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{\backslash i}, v_{j} \backslash i\right) \operatorname{Bern}\left(z_{j} \mid \rho_{j} \backslash i\right) d \beta \mathrm{~d} \mathbf{z} \tag{64}
\end{equation*}
$$

As in the above equation, $\mathbf{h}=\left(h_{0}, h_{1}, \ldots, h_{d}\right)^{T}$ is a d+1-dimension vector of which the first component is 0 while the others are $\lambda$, we can do the simplification as follows:

$$
\begin{align*}
& Z_{i}=\exp \left(h_{i}\right) \boldsymbol{\rho}^{\backslash i} \int \prod_{j=0}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{\backslash i}, v_{j}{ }^{\backslash i}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{j}{ }^{\backslash i}\right) d \beta+\exp \left(-h_{i}\right)(1- \\
& \left.\boldsymbol{\rho}^{\backslash i}\right) \int \prod_{j=0}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{\backslash i}, v_{j}{ }^{\backslash i}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{j}{ }^{\backslash i}\right) d \beta  \tag{65}\\
& Z_{i}=\prod_{j=0}^{d}\left[\rho_{j}{ }^{\backslash i} \exp \left(h_{i}\right)+\left(1-\rho_{j}{ }^{\backslash i}\right) \exp \left(-h_{i}\right)\right] \tag{66}
\end{align*}
$$

According to (63), the updating rule for $\boldsymbol{\rho}$ is written as follows

$$
\begin{equation*}
\boldsymbol{\rho}^{\text {new }}=\boldsymbol{\rho}^{\backslash i}+\boldsymbol{\rho}^{\backslash i}\left(1-\boldsymbol{\rho}^{\backslash i}\right) \nabla_{\boldsymbol{\rho}} \log Z_{i} \tag{67}
\end{equation*}
$$

Combined with (66), we have

$$
\begin{equation*}
\boldsymbol{\rho}^{\text {new }}=\exp (\boldsymbol{h}) \circ \boldsymbol{\rho}^{\backslash i} \circ\left(\exp (\boldsymbol{h}) \circ \boldsymbol{\rho}^{\backslash i}+\boldsymbol{I}\left(1-\boldsymbol{\rho}^{\backslash i}\right)\right)^{-1} \tag{68}
\end{equation*}
$$

As for the approximation of $\widetilde{t}_{l}$ for $i$ in range $(n+3, n+|E|+2)$

$$
\begin{equation*}
Z_{i}=\int\left(\exp \left(\gamma\left(\frac{z_{u}}{\sqrt{d_{u}}}-\frac{z_{v}}{\sqrt{a_{v}}}\right)^{2}\right)\right) \operatorname{Beta}\left(\varepsilon \mid a^{\backslash i}, b^{\backslash i}\right) \prod_{j=1}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}{ }^{\backslash}, v_{j}{ }^{\backslash i}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{j} \backslash i\right) d \beta d \varepsilon \tag{69}
\end{equation*}
$$

Assume the $A_{i}, B_{i}, C_{i}, D_{i}$ can be given as follows

$$
\begin{align*}
A_{i} & =\rho_{u}^{\backslash i} \rho_{v}^{\backslash i} \exp \left(\gamma\left(\frac{1}{\sqrt{d_{u}}}-\frac{1}{\sqrt{d_{v}}}\right)^{2}\right)  \tag{70}\\
B_{i} & =\rho_{u}^{\backslash i}\left(1-\rho_{v}^{\backslash i}\right) \exp \left(\frac{\gamma}{d_{u}}\right) \tag{71}
\end{align*}
$$

$$
\begin{align*}
& C_{i}=\left(1-\rho_{u}^{\backslash i}\right) \rho_{v}^{\backslash i} \exp \left(\frac{\gamma}{d_{v}}\right)  \tag{72}\\
& D_{i}=\left(1-\rho_{u}^{\backslash i}\right)\left(1-\rho_{v}^{\backslash i}\right) \tag{73}
\end{align*}
$$

The updating rule of $\rho$ can be obtained as follows

$$
\begin{align*}
\rho_{u}^{\text {new }} & =\frac{A_{i}+B_{i}}{A_{i}+B_{i}+C_{i}+D_{i}}  \tag{74}\\
\rho_{v}^{\text {new }} & =\frac{A_{i}+C_{i}}{A_{i}+B_{i}+C_{i}+D_{i}} \tag{75}
\end{align*}
$$

Lastly, as for the approximation of $\widetilde{t_{n+|E|+3}}$

$$
\begin{equation*}
Z_{i}=B(a, b) B\left(a_{0}, b_{0}\right)^{-1} B\left(a^{\backslash i}, b^{\backslash i}\right)^{-1} \tag{76}
\end{equation*}
$$

According to the rules of propagating the expectation of $\varepsilon$ and $\varepsilon^{2}$, we have.

$$
\begin{align*}
& a^{\text {new }}=a_{0}+a^{\backslash i}-1 \\
& b^{\text {new }}=b_{0}+b^{\backslash i}-1 \tag{77}
\end{align*}
$$

We can get the following updating rules based on the above expectation propagation algorithm.

$$
\begin{gather*}
\widetilde{\boldsymbol{v}}_{l}^{\text {new }}=\left(\boldsymbol{v}^{-1}-\left(\boldsymbol{v}^{\backslash i}\right)^{-1}\right)^{-1} \\
{\widetilde{\mathbf{m}_{l}}}^{\text {new }}=\widetilde{\boldsymbol{v}}_{l}^{\text {new }} \circ \boldsymbol{v}^{-1} \circ m-\widetilde{\boldsymbol{v}}_{l}^{\text {new }} \circ\left(\boldsymbol{v}^{\backslash i}\right)^{-1} \circ \boldsymbol{m}^{\backslash i} \\
{\widetilde{c_{l}}}^{\text {new }}=\rho \circ\left(\rho^{\backslash i}\right)^{-1} \\
\widetilde{d}_{l}^{\text {new }}=(1-\rho)\left(1-\rho^{\backslash i}\right)^{-1}  \tag{78}\\
{\widetilde{a_{l}}}^{\text {new }}=a-a^{\backslash i} \\
{\widetilde{b_{l}}}^{\text {new }}=b-b^{\backslash i}
\end{gather*}
$$

$\widetilde{s}_{l}$ is a constant and its updating rule is derived from $\widetilde{t_{l}}$. When $i=1,2 \ldots, n$

$$
\begin{equation*}
{\widetilde{s_{l}}}^{\text {new }}=Z_{i} \sqrt{\prod_{j=0}^{d} \frac{{\widetilde{l_{l j}}}^{\text {new }}+v_{j}^{\backslash i}}{{\widetilde{v_{l j}}}^{\text {new }}}} \exp \left(\frac{1}{2} \sum_{j=0}^{d} \frac{\left.{\widetilde{\left(m_{l l}\right.}}^{\text {new }}-m_{j}^{i j}\right)^{2}}{{\widetilde{v_{l ı}}}^{\text {new }}+v_{j}^{i j}} \frac{B\left(a^{\backslash i}, b^{i i}\right)}{B(a, b)}\right. \tag{79}
\end{equation*}
$$

When $i=n+2, \ldots, n+|E|+2$, the updating rule of $\widetilde{s_{l}}$ becomes

$$
\begin{equation*}
\widetilde{s}_{l}^{\text {new }}=Z_{i} \prod_{j=0}^{d} \sqrt{\frac{{\widetilde{v_{l}}}^{\text {new }}+v_{j}^{\backslash i}}{{\widetilde{v_{l}}}^{\text {new }}}} \exp \left(\frac{1}{2} \frac{\left(k_{j}^{\prime}\right)^{2}}{k_{j}^{\prime \prime \prime}}\right) \tag{80}
\end{equation*}
$$

When $i=n+2, \ldots, n+|E|+2$, the updating rule of $\widetilde{s_{l}}$ becomes

$$
\begin{equation*}
{\widetilde{s_{l}}}^{\text {new }}=Z_{i} \tag{81}
\end{equation*}
$$

When $i=n+|E|+3$, the updating rule becomes

$$
\begin{equation*}
{\widetilde{s_{l}}}^{\text {new }}=B\left(a_{0}, b_{0}\right)^{-1} \tag{82}
\end{equation*}
$$

Once the expectation propagation algorithm converges, we can approximate it according to the following formula

$$
\begin{equation*}
p(y \mid \mathbf{x}, G, \lambda, \gamma) \approx \int \sum_{z} \prod_{i=1}^{n+|E|+3} \widetilde{t}_{l}(\beta, \varepsilon, z) d \beta d \varepsilon \approx \hat{\mathrm{Z}}^{-1} \mathrm{C}(2 \Pi)^{\frac{d}{2}} \exp \left(\frac{D}{2}\right) B(A, B)\left[\prod_{i=1}^{n+|E|+3} \widetilde{s}_{l}\right]\left[\prod_{j=0}^{d} \sqrt{v_{j}}\right] \tag{83}
\end{equation*}
$$

Where as

$$
\begin{gather*}
\mathrm{A}=\sum_{i=1}^{n+|E|+3} \widetilde{a_{l}}+1  \tag{84}\\
\mathrm{~B}=\sum_{i=1}^{n+|E|+3} \widetilde{b_{l}}+1  \tag{85}\\
C=\prod_{j=0}^{d}\left(\prod_{i=1}^{n+|E|+3} \widetilde{c_{l j}}+\prod_{i=1}^{n+|E|+3} \widetilde{d_{l \jmath}}\right)  \tag{86}\\
D=\boldsymbol{m}^{T}\left(\boldsymbol{v}^{-\mathbf{1}} \circ \boldsymbol{m}\right)-\sum_{i=1}^{n+|E|+3} \widetilde{\boldsymbol{m}}_{l}{ }^{T}\left({\widetilde{v_{l}}}^{-1} \circ \widetilde{\boldsymbol{m}_{l}}\right) \tag{87}
\end{gather*}
$$

$\hat{\mathrm{Z}}$ is the approximation of $Z$ in (3). Finally, we can predict the label of new samples according to the following formula

$$
\begin{gather*}
p\left(y^{\text {test }} \mid x^{\text {test }}, y, \boldsymbol{X}, G, \lambda, \gamma\right) \approx \iint p\left(y^{\text {test }} \mid x^{\text {test }}, \beta, \varepsilon, G, \lambda, \gamma\right) \sum_{z} p(\beta, \varepsilon, z \mid y, \boldsymbol{X}, G, \lambda, \gamma) d \beta d \varepsilon= \\
\iint\left[\varepsilon+(1-2 \varepsilon) \phi\left(y^{\text {test }} \beta x^{\text {test }}\right)\right] \sum_{z} Q(\beta, \varepsilon, z) d \beta d \varepsilon \tag{88}
\end{gather*}
$$

According to (14)

$$
\begin{gather*}
p\left(y^{\text {test }} \mid x^{\text {test }}, y, \boldsymbol{X}, G, \lambda, \gamma\right) \approx \iint[\varepsilon+(1- \\
\left.2 \varepsilon) \phi\left(y^{\text {test }} \beta x^{\text {test }}\right)\right] \sum_{z} \operatorname{Beta}(\varepsilon \mid a, b) \prod_{j=0}^{d} \mathcal{N}\left(\beta_{j} \mid m_{j}, v_{j}\right) \operatorname{Bern}\left(z_{j} \mid \rho_{i}\right) d \beta d \varepsilon \tag{89}
\end{gather*}
$$

After simplification, we have

$$
\begin{equation*}
p\left(y^{\text {test }} \mid x^{\text {test }}, y, \boldsymbol{X}, G, \lambda, \gamma\right) \approx \bar{\varepsilon}+(1-2 \bar{\varepsilon}) \phi\left(\frac{y^{\text {test }} \boldsymbol{m}^{T} x^{\text {test }}}{\sqrt{\left(\text { vox } x^{\text {test }}\right)^{T} x^{t e s t}}}\right) \tag{90}
\end{equation*}
$$

Where as

$$
\begin{equation*}
\bar{\varepsilon}=\frac{a}{a+b} \tag{91}
\end{equation*}
$$

## 2 Feature selection in NBSBM

A relevant score was defined by equation (10) to quantify the relevance of a feature to the classification results. We applied equation (10) on the first dataset to extract features that are most relevant to the prostate cancer cell responses to Dasatinib. Supplementary table 1 shows those top- 25 relevant genes that ranked by the relevant score. Among the top-ranked genes, CTNNB1, FGFR4, GRK6 and PHB2 are oncogenes that have been reported to play important role in prostate cancer development and progression (FitzGerald, et al., 2009; Linch, et al., 2017; Nakai, et al., 2019; Yang, et al., 2018). Then we did canonical
pathway enrichment analysis, those significantly enriched pathways were listed out in Supplementary table 2. MHC class II antigen presentation, Integration of energy metabolism, MAPK family signaling cascades, RAF/MAP kinase cascade, FLT3 Signaling pathways are top-enriched signaling pathways that correlated with the prostate cancer cell responses to Dasatinib, which was also reported by the literature(da Silva, et al., 2013; Mukherjee, et al., 2011; Younger, et al., 2007).

| Gene Entrez ID | Gene Symbol | Relevant Score |
| ---: | :--- | :--- |
| $\mathbf{1 4 9 9}$ | CTNNB1 | 0.9999 |
| $\mathbf{5 1 0 0 5}$ | AMDHD2 | 0.9999 |
| $\mathbf{2 2 6 4}$ | FGFR4 | 0.9998 |
| $\mathbf{2 8 7 0}$ | GRK6 | 0.9913 |
| $\mathbf{1 1 3 3 1}$ | PHB2 | 0.9913 |
| $\mathbf{8 5 0 4}$ | PEX3 | 0.9913 |
| $\mathbf{8 8 5 1}$ | CDK5R1 | 0.9913 |
| $\mathbf{8 0 7 0 0}$ | UBXN6 | 0.9913 |
| $\mathbf{8 0 7 8}$ | USP5 | 0.9913 |
| $\mathbf{9 4 0 9}$ | PEX16 | 0.9913 |
| $\mathbf{2 2 8 2 6}$ | DNAJC8 | 0.9913 |
| $\mathbf{7 3 1 7}$ | UBA1 | 0.9913 |
| $\mathbf{5 5 9 6 8}$ | NSFL1C | 0.9913 |
| $\mathbf{3 0 5 3}$ | SERPIND1 | 0.9913 |
| $\mathbf{5 7 5 9 1}$ | MRTFA | 0.9913 |
| $\mathbf{1 0 6 3 5}$ | RAD51AP1 | 0.9913 |
| $\mathbf{8 5 4 1}$ | PPFIA3 |  |
| $\mathbf{4 6 0 1}$ | MXI1 | 0.9913 |
| $\mathbf{5 5 8 4 4}$ | PPP2R2D |  |
| $\mathbf{5 5 2 6}$ | PPP2R5B |  |
| $\mathbf{5 1 4 0 0}$ | PPME1 |  |
| $\mathbf{3 0 0 9}$ | H1-5 |  |
| $\mathbf{9 9 8 9}$ | PPP4R1 |  |
| $\mathbf{5 7 7 1 8}$ | PPP4R4 |  |
| $\mathbf{~}$ |  | 0.9913 |
|  |  | 0.9913 |
|  |  | 0.9913 |
|  |  | 0.9913 |
|  |  | 0.9913 |
|  |  |  |

Supplemental Table 1 Top-25 most predictive genes for classifying prostate cancer cell responses to Dasatinib. Oncogenes such as CTNNB1, FGFR4, GRK6 and PHB2 are top-ranked.

| Enriched Pathways | p -value |
| :---: | :---: |
| MHC class II antigen presentation | $2.74 \mathrm{E}-06$ |
| Integration of energy metabolism | 0.002008 |
| MAPK family signaling cascades | 0.002191 |
| RAF/MAP kinase cascade | 0.006537 |
| FLT3 Signaling | 0.006955 |
| MAPK1/MAPK3 signaling | 0.009353 |
| interleukin signaling | 0.012823 |


| Rho GTPase cycle | 0.015637 |
| :---: | :---: |
| Downstream TCR signaling | 0.027074 |
| Signaling by Receptor Tyrosine Kinases | 0.028316 |
| RHO GTPases Activate Formins | 0.037878 |

Supplemental Table 2 The most enriched signaling pathways in those top-100 ranked genes that are most relevant to prostate cancer cell response to Dasatinib. P-value was estimated using the fisher's exact test.

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