



Article Comparing Four Types Methods for Karst NDVI Prediction Based on Machine Learning

Yuju Ma¹, Liyuan Zuo^{2,3}, Jiangbo Gao^{2,*}, Qiang Liu¹ and Lulu Liu²

- ¹ College of Engineering, Ocean University of China, Qingdao 266100, China; mayuju@stu.ouc.edu.cn (Y.M.); liuqiang@ouc.edu.cn (Q.L.)
- ² Key Laboratory of Land Surface Pattern and Simulation, Institute of Geographic Sciences and Natural Resources Research, Chinese Academy of Sciences, Beijing 100101, China; zuoly.17s@igsnrr.ac.cn (L.Z.); liull.16b@igsnrr.ac.cn (L.L.)
- ³ University of Chinese Academy of Sciences, Beijing 100049, China
- * Correspondence: gaojiangbo@igsnrr.ac.cn

Abstract: As a link for energy transfer between the land and atmosphere in the terrestrial ecosystem, karst vegetation plays an important role. Karst vegetation is not only affected by environmental factors but also by intense human activities. The nonlinear characteristics of vegetation growth are induced by the interaction mechanism of these factors. Previous studies of this relationship were not comprehensive, and it is necessary to further explore it using a suitable method. In this study, we selected climate, human activities, topography, and soil texture as the response factors; a nonlinear relationship model between the karst normalized difference vegetation index (NDVI) and these factors was established by applying a back propagation neural network (BPNN), a radial basis function neural network (RBFNN), the random forest (RF) algorithm, and support vector regression (SVR); and then, the karst NDVI was predicted. The coefficient of determination (R^2), mean square error (MSE), root mean square error (RMSE), and mean absolute percentage error (MAPE) of the obtained results were calculated, and the mean R² values of the BPNN, RBFNN, RF, and SVR models were determined to be 0.77, 0.86, 0.89, and 0.91, respectively. Compared with the BPNN, RBFNN, and RF models, the SVR model had the lowest errors, with mean MSE, RMSE, and MAPE values of 0.001, 0.02, and 2.77, respectively. The results show that the BPNN, RBFNN, RF, and SVR models are within acceptable ranges for karst NDVI prediction, but the overall performance of the SVR model is the best, and it is more suitable for karst vegetation prediction.

Keywords: karst NDVI; natural and anthropogenic factors; BPNN; RBFNN; RF; SVR; prediction comparison

1. Introduction

The karst landscape in southwestern China developed on soluble carbonate bedrock, and it is one of the largest contiguous karst regions in the world [1–3]. The vegetation cover is relatively low because of the slow formation rate and shallow depth of the soil in the karst region [4]. However, karst vegetation is the most fundamental component of the terrestrial ecosystem, and it provides a great carbon sink function and a series of ecological services [5–7]. Therefore, it is necessary to monitor and predict the dynamic changes in karst vegetation.

Karst vegetation is not only affected by environmental factors (climate, soil, topography) but also by human activities. In particular, karst vegetation is highly sensitive to human activities and climate change [8]. The effects of human activities on karst vegetation have positive and negative impacts. With the rapid development of the economy, most farmers have reduced their dependence on cropland and reduced the impact of unreasonable human activities on the ecological environment; in addition, the government



Citation: Ma, Y.; Zuo, L.; Gao, J.; Liu, Q.; Liu, L. Comparing Four Types Methods for Karst NDVI Prediction Based on Machine Learning. *Atmosphere* **2021**, *12*, 1341. https:// doi.org/10.3390/atmos12101341

Academic Editors: Yaoping Cui and Abhnil Prasad

Received: 9 September 2021 Accepted: 10 October 2021 Published: 13 October 2021

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Copyright: © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). implements ecological environment treatment projects such as grain for green, these activities have promoted vegetation restoration. However, increased demand for construction land because of the intensified expansion of urbanization, resulting in a significant degradation trend of vegetation cover [9]. Tong et al. [10] revealed that the vegetation degradation is presumably induced by human activities in the central and eastern parts of Yunnan Province, while the conservation and restoration efforts in other regions of southwestern China may improve vegetation conditions. Climatically, the rising temperature has a positive effect on vegetation growth, but the continuously rising temperature may accelerate surface water evaporation, thus, affecting vegetation growth [11]. In Guizhou, the karst vegetation is strongly influenced by the increasing temperature, which has led to more drought stress than non-karst areas [12]. Precipitation is usually absorbed and used by vegetation after being converted into soil moisture [6]. Wang et al. [13] reported that there is a positive correlation between vegetation conditions and precipitation in most dry areas, while there is a negative correlation between vegetation conditions and heavy rainfall in most humid areas. Sunshine is a major driving factor in ecosystems, and it plays a role that is equally important as those of temperature and precipitation in vegetation growth [14]. Soil texture and topography are also important contributing factors to vegetation growth. Different soil textures (i.e., sand, silt, and clay) are characterized by different grain sizes, void ratios, and permeabilities, which can affect the resistance and resilience of vegetation to drought stress [15]. The relationship between vegetation and elevation does not monotonically increase [16]. At low elevations (0–500 m), human activities mainly include significant increases in the amount of build-up land, which results in sparse vegetation coverage [17]. Then, vegetation initially increases and then continuously decreases with increasing elevation [18].

To quantitatively analyze vegetation change, the normalized difference vegetation index (NDVI), one of the most important indicators for monitoring temporal changes in vegetation was used [19–21]. Many studies have discussed the response of the NDVI to various impact factors and have analyzed its changes at the regional and global scales. Linear analysis, correlation analysis, and residual analysis are the most commonly used methods. For instance, a multiple regression model has been used to construct an NDVI prediction model based on historical dynamic changes in the vegetation NDVI [22]. Under different climate change scenarios, a multiple linear regression has been utilized to predict future vegetation cover changes [23]. Least-squares linear regression has been employed to detect the variations in the NDVI and climate; however, a linear trend cannot accurately represent the actual temporal patterns of vegetation growth [24]. Correlation analysis and residual analysis perform well in revealing linear relationships, but they are not suitable for exploring nonlinear relationships [25]. It is imperative to reveal that the response of vegetation to climate change is a nonlinear process and has compound effects, and it is necessary to explore the pattern of the temporal variations in vegetation growth based on comprehensive analysis with multiple factors [26]. Several studies have reported that an appropriate nonlinear method could be conducive to explaining the nonlinear relationship between the NDVI and climate [27].

Machine learning has the advantages of effectively handling multidimensional and multi-variety data in a dynamic or uncertain environment [28], and it has been commonly utilized to explain complex nonlinear relationships in many fields, such as medicine [29,30], biology [31,32], and geology [33,34]. To reflect the nonlinear characteristics of vegetation coverage change, several scholars have used this method to construct vegetation prediction models through repeated training and verifying its feasibility for the validation period. For instance, it has been inferred that the relationship between vegetation greening and natural and human factors is nonlinear, so a nonlinear relationship model was constructed to predict the future changes in greening based on a boosted regression tree [25]. Based on the observation data, support vector regression, random forest, linear, and polynomial regression are employed to predict the vegetation indices, including the NDVI and the enhanced vegetation index (EVI) [35]. Although some scholars have constructed nonlinear

vegetation prediction models, these studies of karst NDVI prediction are not comprehensive and it is necessary to further explore this topic using a suitable method.

The main objective of this study is to explore the best method for karst NDVI prediction by comparing the four machine learning methods prediction results. The methods including back propagation neural network (BPNN), radial basis function neural network (RBFNN), random forest (RF), and support vector regression (SVR) were used to construct the nonlinear relationship model between NDVI and impact factors, and then predicted NDVI based on the established model. We selected climate, nighttime light, topography, and soil texture as the input factors, and the karst NDVI was the predicted factor. Considering the effect of climate with time-lagged on vegetation, the Pearson correlation analysis was utilized to select climate factors with time-lagged as impact factors, which were inputted into the model.

2. Materials and Methods

2.1. Study Area

The study area is a typical karst landscape in Guizhou, Yunnan, Chongqing, and Guangxi provinces, southwestern China. It is mainly dominated by the karst plateau, karst basin, karst trough valley, and karst peak-cluster depression, respectively (Figure 1). The terrain is very complex, with average elevations of 400–1200 m. The mean annual precipitation is 1100 mm and the mean annual temperature is 20 °C, which is typical for a subtropical monsoon climate [25]. After launching the Grain for Green Project, general vegetation greening was observed in southwest China [11]. With the acceleration of urbanization, the speed of urbanization was greater than that of vegetation restoration.

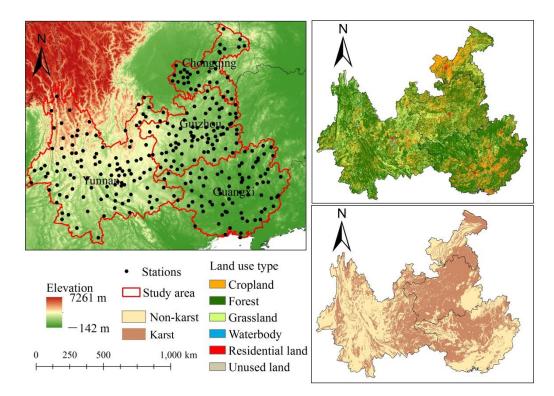


Figure 1. The distribution of the karst area and land use types in the study region.

2.2. Data

2.2.1. Modis NDVI Dataset

The selected normalized difference vegetation index (NDVI) dataset from 2000 to 2019 was obtained from the National Aeronautics and Space Administration (NASA) MOD13A3 product (https://ladsweb.modaps.eosdis.nasa.gov/search/ (accessed on 14 April 2021)), and it was utilized to describe the dynamic variations in the vegetation. The product, with

a spatial resolution of 1 km and a monthly temporal resolution, had been corrected for radiation, geometry, and atmosphere. To avoid interferences such as that of winter snow

on the NDVI images, we only studied the vegetation growing season (April to September). The preprocessing, including projection conversion and resampling, was conducted using the MODIS Reprojection Tool (MRT). Then, the monthly NDVI images of the study area were extracted in ArcGIS10.

2.2.2. Climate Data

The data for the climate factors during 2000–2019, including the maximum temperature, minimum temperature, mean temperature, mean relative humidity, mean land surface temperature, total precipitation, and total sunshine duration, were provided by the Institute of Geographic Sciences and Natural Resources of the Chinese Academy of Sciences, and there were 294 meteorological stations in total. After excluding the sites with missing data, the rest of the individual missing data were replaced using the mean values for the same period during an adjacent year [25]. We obtained the monthly climate data using the statistical calculation method.

2.2.3. Human Activities Data

We used nighttime light to detect human activities. The nighttime light 2000–2019 time-series data were derived from the research results of Ma et al. [36]. This dataset overcomes the shortcomings that the original two types of nighttime light data (DMSP-OLS and VIIRS-SDR) cannot be used simultaneously. We processed and calculated the nighttime light values using ArcGIS 10.2.

2.2.4. Environmental Data

The digital elevation model (DEM) data, with a spatial resolution of 90 m, were downloaded from the Geospatial Data Cloud (http://www.gscloud.cn/ (accessed on 16 April 2021)), which was used to extract the elevation and slope data. The administrative boundary data were obtained from the National Basic Geographic Information System. We obtained the spatial distribution of the lithology from the Institute of Geographic Sciences and Natural Resources of the Chinese Academy of Sciences. The Harmonized World Soil Database contains worldwide soil composition information at a spatial resolution of 30 arcsec. Two soil parameters included the percentages of the clay soil and sandy soil components were extracted from the database using ArcGIS10.2 (http://www.fao.org/soils-portal/soilsurvey/soil-maps-and-databases/harmonized-world-soil-database-v12/en/ (accessed on 16 April 2021)).

2.3. Methods

2.3.1. Pearson Correlation Analysis

We used Pearson correlation analysis to analyze the time-lagged responses of the karst NDVI to the climatic factors. The correlation coefficients ranged from -1 to 1. The NDVI and climatic factor datasets from 2000 to 2019 were selected. We explored the correlation between the NDVI (current month) and the climatic factors (current month or previous month). When the correlation coefficient between the NDVI and climatic factors (previous month) was greater than the correlation coefficient between the NDVI and climatic factors (current month), we concluded that the climatic factors have a time-lagged effect on the NDVI, and these factors were selected as the input factors of the models.

2.3.2. Back Propagation Neural Network

A back propagation neural network (BPNN) used was a multi-layer feedforward neural network trained using an error back propagation algorithm, and it consisted of an input layer, hidden layer, and an output layer. The information was input into the input layer and was then treated in each successive layer and transmitted to the output layer. The error was calculated from the output layer and propagated to the input layer using a back propagation algorithm in order to adjust the weights and thresholds. A single hidden layer network structure was set up in the BPNN model. The optimal numbers of neurons in the hidden layer were determined through repeated training of the network. The numbers of neurons in the input layer and the output layer were determined by the numbers of input factors and output factor, respectively. There was a neural network toolbox in MATLAB2019b, which including BPNN we used. It involves three functions, parameter setting function 'newff', the training function 'train', and the prediction function 'sim' [37]. The input and output of the *k*th neuron were as follows [38]:

$$U_k = \sum_{i=1}^n u_{i,k} O_i \tag{1}$$

$$O_k = f(I_k + \vartheta_k) \tag{2}$$

where $u_{i,k}$ was the connection weight between the ith neuron and the kth neuron; $f(I_k + \vartheta_k)$ was the activation function; ϑ_k was the threshold; and I_k and O_k were the input and output of the kth neuron, respectively.

2.3.3. Radial Basis Function Neural Network

The radial basis function neural network (RBFNN) used was a feedforward neural network with a single hidden layer, and it was composed of an input layer, a hidden layer, and an output layer. Different from the BPNN, it used the radial basis function as the activation function in the hidden layer [39]. Functions such as newrbe and newrb were commonly used to build RBFNN models. Newrbe is characterized by fast neural network creation, and a zero-error radial basis network can be designed in order to improve the prediction accuracy [40]. In this paper, we utilized the newrbe function to build the RBFNN model to predict NDVI, and the spreading factor was adjusted to improve the model's performance. The output of neurons from the output layer was as follows:

$$\varphi(x) = \sum_{i=1}^{n} w_i \exp\left(-\beta_i \|x - c_i\|^2\right)$$
(3)

where *n* was the number of hidden layer neurons; c_i and w_i were the center and weight corresponding to the ith hidden layer neurons; and $\exp(-\beta_i ||x - c_i||^2)$ represented the radial basis functions.

2.3.4. Random Forest

The random forest (RF) algorithm was based on a decision tree. The principle of the RF was that each tree was composed of a random subset. In the splitting process, all of the features were not considered by the model, but the best feature was selected for the classification, which enriched the diversity of the decision trees in the model [41]. The algorithm was mainly divided into four steps. (1) The repeated sampling method was used to select a subset from all of the datasets as a training set. (2) The subset was used to build a decision tree. (3) The *k* decision trees were used to build the RF model by repeating the above steps k times. (4) The NDVI was predicted using the established RF model [41]. In this study, the RF model was developed using the treebagger function in regression model in MATLAB 2019b [42].

2.3.5. Support Vector Regression

Support vector regression (SVR) was developed by Vapnik in 1995, which was one of the most popular machine learning algorithms in capturing nonlinearity [43]. A kernel function was used to map the vectors into a higher dimensional feature space in the SVR model, and the model can be employed linear regression of the target variable in this space by introducing an alternative loss function and kernel function [44,45]. There were five commonly used kernel functions: the linear kernel function, the polynomial kernel function, the Gaussian kernel function is suitable for analyzing nonlinear relationships

between influencing factors and the predicted factor [45], so we selected the Gaussian kernel function as the kernel function of the SVR model. For detailed information on the SVR model as seen Refs. [43,46]. The libsvm-3.24 toolbox was developed by Chang et al. [47] in 2011, and we constructed the SVR model using this toolbox. The process of predicting karst NDVI by machine learning methods was shown in Figure 2.

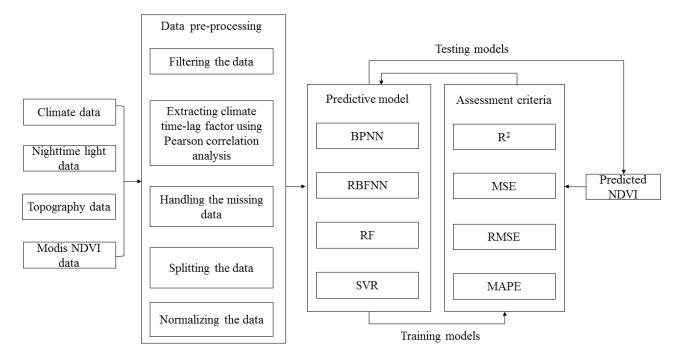


Figure 2. Architecture of the prediction framework using machine learning methods.

2.4. Assessment Criteria

To explore the prediction accuracy of the BPNN, RBFNN, RF, and SVR models, the statistical parameters including the coefficient of determination (R²), mean square error (MSE), root mean square error (RMSE), and mean absolute percentage error (MAPE) were used to calculate in different karst NDVI prediction results (Karst plateau, Karst basin, Karst trough valley, Karst peak-cluster depression). The higher the R² value and the lower the MSE, RMSE, and MAPE values were, the better the model's prediction performance was. The formulas for the assessment criteria were as follows:

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (Y_p - Y_o)^2$$
(4)

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (Y_p - Y_o)^2}$$
(5)

$$MAPE = \frac{100\%}{n} \sum_{i=1}^{n} \left| \frac{Y_p - Y_o}{Y_o} \right|$$
(6)

$$R^{2} = \frac{\left(n\sum_{i=1}^{n} Y_{p}Y_{o} - \sum_{i=1}^{n} Y_{p}\sum_{i=1}^{n} Y_{o}\right)^{2}}{\left[n\sum_{i=1}^{n} Y_{p}^{2} - \left(\sum_{i=1}^{n} Y_{p}\right)^{2}\right]\left[n\sum_{i=1}^{n} Y_{o}^{2} - \left(\sum_{i=1}^{n} Y_{o}\right)^{2}\right]}$$
(7)

where *n* was the sample number of validation period; and Y_p and Y_o were the predicted and observed NDVI, respectively.

2.5. Data Pre-Processing

The data were divided into training sets (from 2000 to 2011) and validation sets (from 2012 to 2019) using a ratio segmentation 6:4. Based on the MATLAB 2019b software, a

nonlinear relationship model between the NDVI and the response factors was built and the karst NDVI was predicted. To keep the different units and magnitude of the factors from affecting the model's performance, the input data were normalized to within a range of [0, 1] before being fed into the model [48].

$$X_n = \frac{X_i - X_{min}}{X_{max} - X_{min}} \tag{8}$$

where X_n was the normalized data; X_i was the observed data; and X_{min} and X_{max} were the minimum and maximum of the data, respectively.

3. Results

3.1. BPNN Model

We obtained the BPNN network structures of the NDVI prediction models (the number of neurons in the input layer—the number of neurons in the hidden layer—the number of neurons in the output layer) in the karst plateau, karst basin, karst trough valley, and karst peak-cluster depression areas, which were 18-1-1, 29-4-1, 22-1-1, and 23-3-1, respectively. The R² values of the results ranged from 0.6327 to 0.8713, with an average of 0.7744 (Table 1). The ranges of the MSE, RMSE, and MAPE values were 0.0007–0.0022, 0.0241–0.0452, and 2.4604–5.6112, respectively, with averages of 0.0017, 0.0384, and 4.4570, respectively, which indicate that the BPNN model is acceptable for karst NDVI prediction. In the NDVI model prediction of karst trough valley, the model's generalization performance was better than those of the other karst NDVI prediction models (Figure 3).

Table 1. The prediction accuracy of the BPNN model.

Karst Regions	R ²	MSE	RMSE	MAPE
Karst plateau	0.7547	0.0021	0.0442	5.1697
Karst basin	0.8389	0.0022	0.0452	5.6112
Karst trough valley	0.8713	0.0007	0.0241	2.4604
Karst peak-cluster depression	0.6327	0.0017	0.0400	4.5865

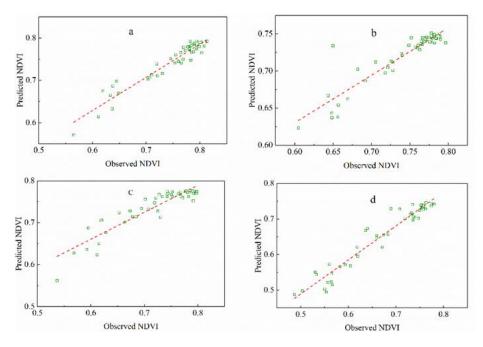


Figure 3. Comparison of the observed and BPNN predicted NDVI in the (**a**) karst trough valley, (**b**) karst peak-cluster depression, (**c**) karst plateau, and (**d**) karst basin.

3.2. RBFNN Model

The R² values were 0.7201–0.9516, with an average of 0.8563 (Table 2). The ranges of the MSE, RMSE, and MAPE values were 0.0006–0.0027, 0.0238–0.0520, and 2.6835–6.1581, respectively, with averages of 0.0014, 0.0356, and 4.1107, respectively. In the karst trough valley NDVI prediction, the model's accuracy had a better performance than the other karst NDVI predictions (Figure 4). By comparing the R², MSE, RMSE, and MAPE values to those of the BPNN, we concluded that the prediction accuracy of the RBFNN was higher than that of the BPNN.

Table 2. The prediction accuracy of the RBFNN model.

Karst Regions	R ²	MSE	RMSE	MAPE
Karst plateau	0.9087	0.0008	0.0282	3.2034
Karst basin	0.8447	0.0027	0.0520	6.1581
Karst trough valley	0.9516	0.0006	0.0238	2.6835
Karst peak-cluster depression	0.7201	0.0015	0.0383	4.3979

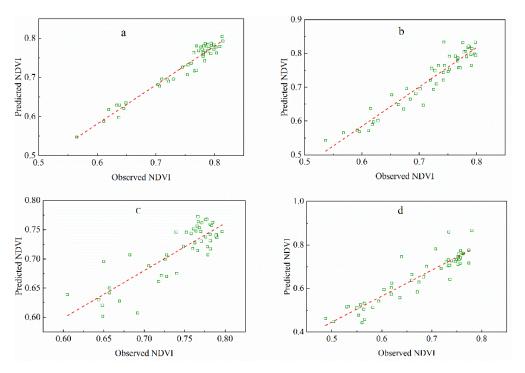


Figure 4. Comparison of the observed and RBFNN predicted NDVI in the (**a**) karst trough valley, (**b**) karst plateau, (**c**) karst peak-cluster depression, and (**d**) karst basin.

3.3. RF Model

The optimal numbers of leaf nodes and trees (5 and 1000, respectively) were determined to achieve the best prediction accuracy of the RF model. The R² values were 0.8136–0.9422, with an average of 0.8919 (Table 3). The MSE, RMSE, and MAPE values were 0.0012–0.0030, 0.0346–0.0546, and 4.3629–6.8243, respectively, with averages of 0.0023, 0.0468, and 5.8686, respectively. In the karst basin and karst trough valley NDVI predictions, the R² values were up to 0.9422 and 0.9329, respectively, indicating that the model performed better in these regions than in the other karst NDVI predictions (Figure 5). The errors of the validation period were lower, and the prediction accuracy of the RF was good.

Karst Regions	R ²	MSE	RMSE	MAPE
Karst plateau	0.8790	0.0030	0.0546	6.8243
Karst basin	0.9422	0.0012	0.0346	4.3629
Karst trough valley	0.9329	0.0028	0.0525	6.6639
Karst peak-cluster depression	0.8136	0.0021	0.0453	5.6231

Table 3. The prediction accuracy of the RF model.

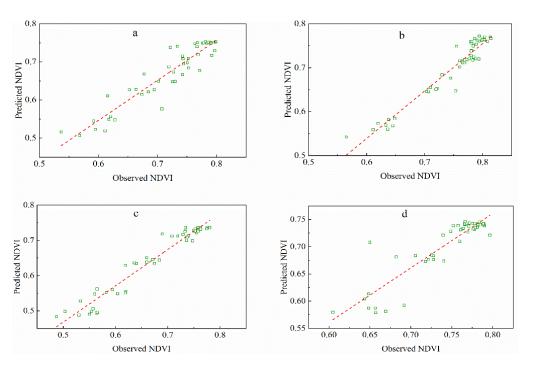


Figure 5. Comparison of the observed and RF predicted NDVI in the (**a**) karst plateau, (**b**) karst trough valley, and (**c**) karst basin, (**d**) karst peak-cluster depression.

3.4. SVR Model

The R^2 values were 0.8427–0.9564, with an average of 0.9128 (Table 4). The model prediction accuracy was greater than 0.9 in the study area, except for the karst peak-cluster depression NDVI prediction. The MSE, RMSE, and MAPE values were 0.0002–0.0011, 0.0154–0.0336, and 1.6700–4.2682, respectively, with averages of 0.0006, 0.0239, and 2.7732, respectively. The model performed the best overall in the karst trough valley NDVI prediction compared to in the other regions. This shows that the SVR model had a higher accuracy in the karst NDVI prediction (Figure 6).

Table 4. The prediction accuracy of the SVR model.

Karst Regions	R ²	MSE	RMSE	MAPE
Karst plateau	0.9150	0.0005	0.0218	2.4420
Karst basin	0.9370	0.0011	0.0336	4.2682
Karst trough valley	0.9564	0.0002	0.0154	1.6700
Karst peak-cluster depression	0.8427	0.0006	0.0248	2.7124

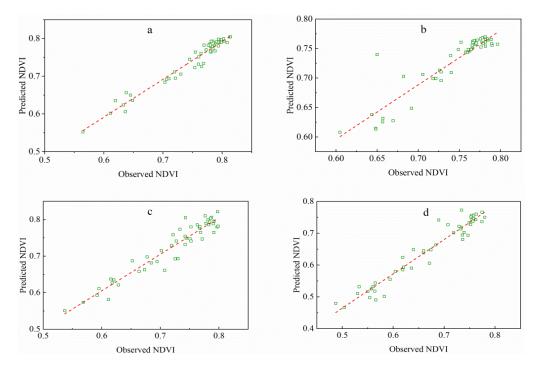


Figure 6. Comparison of the observed and SVR predicted NDVI in the (**a**) karst trough valley, (**b**) karst peak-cluster depression, (**c**) karst plateau, (**d**) and karst basin.

3.5. Comparison of Prediction Results

The comparison of the karst NDVI prediction results of the different models is shown in Figures 7 and 8. In the karst trough valley NDVI prediction, the R² values were SVR > RBFNN > RF > BPNN, and the MSE and RMSE values were SVR < RBFNN < BPNN < RF, while the MAPE values were SVR < BPNN < RBFNN < RF. In the karst peak-cluster depression NDVI prediction, the R² values were SVR > RF > RBFNN > BPNN, and the errors were SVR < RBFNN < BPNN < RF. In the karst plateau NDVI prediction, the R² values were SVR > RBFNN > RF > BPNN, and the errors were SVR < RBFNN < BPNN < RF. In the karst basin NDVI prediction, the R² values were RF > SVR > RBFNN > BPNN, and the errors were SVR < RF < BPNN < RBFNN. The prediction accuracy of the SVR was higher than those of the other models, while its MSE, RMSE, and MAPE values were lower than those of the other models. Thus, we conclude that the SVR model is more suitable for karst NDVI prediction.

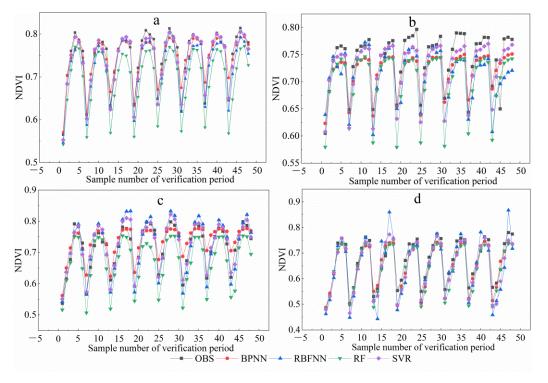


Figure 7. Comparison of the observed and BPNN, RBFNN, RF, and SVR predicted NDVI in the (**a**) karst trough valley, (**b**) karst peak-cluster depression, (**c**) karst plateau, and (**d**) karst basin.

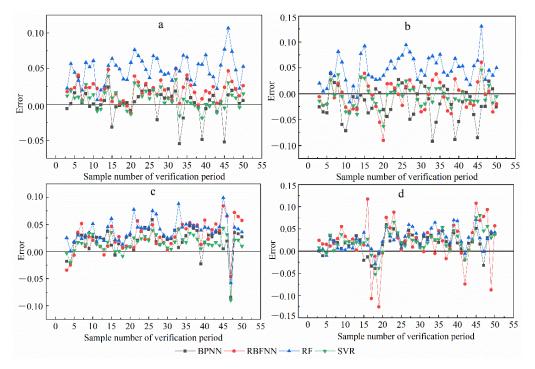


Figure 8. Error of the BPNN, RBFNN, RF, and SVR for the predicted NDVI in the (**a**) karst trough valley, (**b**) karst plateau, (**c**) karst peak-cluster depression, and (**d**) karst basin.

4. Discussion

Several scholars have studied the response of the vegetation NDVI to impact factors and have analyzed its changes in southwestern China. However, they did not distinguish between karst vegetation and non-karst vegetation, resulting in inadequately reflecting the nonlinear relationship between the karst vegetation and the impact factors in this special geologic environment. Vegetation growth is not affected by a single factor but is the result of the combined effect of multiple factors. Compared to non-karst vegetation, karst vegetation is more affected by topography, climate, and human activity factors [9]. Karst vegetation is significantly affected by both climate and non-climate factors, and the response of vegetation to climate exhibits nonlinear characteristics and compound effects [26]. Previous studies have concluded that the relationship between the land surface temperature and the NDVI has opposite spatial distribution patterns in typical karst regions at the macroscopic and microscopic levels [49]. Vegetation activities can be regulated by moisture changes, but increased moisture may inhibit vegetation activities due to increased cloud cover and relative humidity [26]. Wang et al. [13] found that temperature and precipitation have larger impacts on the NDVI than the annual sunshine duration. The present climatic conditions may not be the primary driving factor of vegetation growth, and the earlier climatic conditions may be the most important factors affecting vegetation growth. By determining the time-lag effect, we can better predict and evaluate vegetation dynamics under the background of global climate change [50]. Thus, the time-lag effects of the climate factors on vegetation play a non-negligible role in vegetation prediction. The topography can explain the spatial distribution characteristics of the vegetation cover to a certain extent. Different soil textures have a significant effect on karst vegetation. Increasing the percentage of the sandy soil component will progressively improve the direct response of the vegetation to drought, while increasing the percentage of the clay soil component will have the opposite effect [15]. Therefore, using a suitable nonlinear method to predict karst vegetation based on multiple factors could enhance the explanation of the nonlinear process of vegetation growth.

Linear methods are currently the most commonly used methods of analyzing karst vegetation changes, but the variable interactions are hard to be considered, resulting in difficulty revealing the nonlinear relationships between predict and response factors [25]. The response of vegetation to the influencing factors is complex and nonlinear. Machine learning methods are very effective in dealing with nonlinear relationships between the system's inputs and outputs. They can speculate and improve algorithms independently and enhance the accuracy and efficiency by obtaining experience [28]. With machine learnings, we can better reveal the nonlinear relationship of vegetation greening with natural and human activities factors and for better prediction. The karst NDVI prediction results of the BPNN, RBFNN, RF, and SVR models are presented in Tables 1–4. The mean R² values were 0.7744, 0.8563, 0.8919, and 0.9128, respectively. Based on the assessment of errors, the models were within the acceptable ranges. Wu et al. [16] have employed four modeling approaches: linear regression, generalized additive models, support vector machine, and RF to fit vegetation cover change, the results obtained that the RF model produced the highest accuracy and lowest error. Four supervised machine algorithms: SVR, RF, linear and polynomial regression were used to predict NDVI and EVI, the results showed that the RF model for NDVI and EVI prediction have high levels of accuracy [35]. Different from the above research, our research found the SVR model has the lowest errors and the highest accuracy compared with the BPNN, RBFNN, and RF models, which was indicating that the SVR model was the best for karst vegetation prediction.

From the perspective of the principle of these models, the gradient descent method is widely used to adjust the weights of the BPNN neurons, but its limitations are a slow convergence speed and being easy to fall to a local optimum [39], which result in a relatively poor prediction accuracy. The ability of the RBFNN model to produce global approximations could solve the local optimum problem of the BPNN model, so its vegetation prediction approximation accuracy is obviously higher than that of the BP [39]. The data input into the RF model was divided into intervals to yield the mean results for each interval, which makes the RF model very flexible [51]. The advantages of the SVR model are the uniqueness and global optimality of the generated solution [52] and it determines the maximum-margin hyperplane [53], which improves the prediction accuracy and reduces the prediction error. However, the interpretation of most machine learning algorithms is often considered hard, similar to a black box [54]. Without an explicit regression equation for the final model, the resulting input-output relationships from the black box model cannot be provided good interpretability [25]. However, machine learning algorithms still have powerful functions in dealing with complex nonlinear relationships. In this study, the RBFNN and RF models had relatively higher accuracies, but they were significantly biased compared to the performance of the SVR model.

In this study, we only predicted the NDVI in the growing season in typical karst regions and discussed the optimal machine learning method for karst NDVI prediction. It is relatively rough to extract data, such as topography and soil texture data, from on the regional scale because of the strong landscape heterogeneity in karst areas. In addition, MODIS NDVI time-series data have a relatively low spatial resolution. The karst region is characterized by a high bedrock exposure and low vegetation coverage. The prediction results may be influenced by the spectral response of the ground. In the future, we will explore the dynamic changes in the karst vegetation on multiple time scales and grid-ingrid distribution scales. Applying machine learning methods to accurately predict karst vegetation at multiple temporal and spatial scales in order to provide a scientific basis for karst vegetation restoration and environmental governance is very important.

5. Conclusions

In this study, we selected relevant climate, human activity, soil texture, and topography factors. The BPNN, RBFNN, RF, and SVR methods were employed to construct a nonlinear relationship model between the karst NDVI and these factors and then to predict the karst NDVI. Pearson correlation analysis was used to analyze and select the climate factors, which had a time-lagged effect on the NDVI, influencing the NDVI as inputs of the model. By assessing the model performance, we determined the best model for vegetation prediction.

By assessing the models using the mean R² values as the criteria, it was found that the observed values agree well with the predicted values for the BPNN, RBFNN, RF, and SVR models (R²: 0.77, 0.86, 0.89, and 0.91, respectively). Based on the mean MSE, RMSE, and MAPE values (MSE: 0.002, 0.001, 0.002, and 0.001; RMSE: 0.04, 0.04, 0.05, and 0.02; MAPE: 4.46, 4.11, 5.87, and 2.77, respectively), the models are within the acceptable range.

By comparing the models' results (R², MSE, RMSE, and MAPE), it was determined that the models are acceptable for karst NDVI prediction. Although the prediction accuracy of the RF model for the karst basin NDVI was higher than that of the SVR model, the overall errors of the SVR model were lower than those of the RF model. The results show that the SVR model significantly outperformed the BPNN, RBFNN, and RF models in terms of the standard statistical indexes, and thus, it is more suitable for karst NDVI prediction. The accuracy of the SVR model is affected by the different parameters; and a well-trained SVR model is a useful tool for predicting karst vegetation. Our results can provide references for vegetation prediction in karst areas and more accurate predictions for the assessment of ecological evolution.

Author Contributions: Conceptualization, Y.M., J.G. and L.Z.; methodology, Y.M. and Q.L.; software, Y.M.; validation, Y.M.; formal analysis, Y.M., J.G. and L.Z.; investigation, Y.M. and Q.L.; resources, L.Z., L.L., Y.M. and J.G.; data curation, Y.M., L.Z., L.L. and J.G.; writing—original draft preparation, Y.M.; writing—review and editing, Y.M. and L.Z.; visualization, Y.M., J.G. and L.Z.; supervision, J.G.; project administration, J.G.; funding acquisition, J.G. All authors have read and agreed to the published version of the manuscript.

Funding: This research was funded by the National Natural Science Foundation of China, grant number 42071288 and 41671098; the Programme of Kezhen-Bingwei Excellent Young Scientists of the Institute of Geographic Sciences and Natural Resources Research, Chinese Academy of Sciences, grant number 2020RC002; the National Key Research and Development Program of China, grant number 2018YFC1509002.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: Not applicable.

Conflicts of Interest: The authors declare no conflict of interest.

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