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Fuzzy Reasoning for Mixture of Fuzzy/Intuitionistic Fuzzy Information Based on Triple I Method

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Abstract: Generalized modus ponens (GMP) is a basic model of approximate reasoning. GMP in fuzzy propositions is called fuzzy modus ponens (FMP) and it is called intuitionistic fuzzy modus ponens (IFMP) when fuzzy propositions are generalized to intuitionistic fuzzy propositions. In this paper, we aim to investigate fuzzy reasoning methods for GMP with mixture of fuzzy/intuitionistic fuzzy information. For mixed types of GMP, we present two basic methods to solve GMP problems based on the triple I method (TIM). One is to transform the GMP problem into two FMP problems by decomposition and aggregate the solutions of TIM for FMP problems to obtain the solution for GMP problem. The other is to transform the GMP problem into the IFMP problem by expansion and aggregate the solutions of TIM for the IFMP problem to obtain the solution for the GMP problem. These two methods are called the decomposition triple I method (DTIM) and expansion triple I method (ETIM), respectively. We analyze the relationship between DTIM and ETIM. Furthermore, we discuss the reversibility of DTIM and ETIM.

Keywords: fuzzy reasoning; generalized modus ponens; intuitionistic fuzzy sets; triple I method; reversibility



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1. Introduction

Since the concept of fuzzy sets (FSs) proposed by Zadeh [1] is quite powerful in expressing and dealing with imprecise and uncertain information, there are fruitful research results both in theory and application. It is well known that fuzzy modus ponens (FMP) and fuzzy modus tollens (FMT) are the two basic inference models of fuzzy approximate reasoning. The composition rule of inference (CRI) introduced by Zadeh [2] is a very widespread and important reasoning principle for the basic models FMP and FMT.

Although the CRI of approximate reasoning has been successfully applied in many fields [3–6], it should be admitted that CRI method lacks a logical foundation as Wang pointed out in [7]. Wang proposed the triple I method (TIM) to provide a logical principle of reasonableness for fuzzy inference [7,8]. TIM soon attracted the attention of researchers and became an significant method to deal with the issues related to FMP and FMT [8–18]. Liu and Wang [9] studied the properties of TIM concerning sustaining degrees. Pei [11] proposed a first order logic deduce system based on the unified TIM. Tang generalized TIM to the symmetric implication method in [13] and advanced a novel symmetric implication method on the strength of two-dimensional sustaining degree [14]. Zhou gave a new solution formula of TIM based on law of importation and flexible ordering property in [18].

The concept of interval valued fuzzy sets (IVFSs) presented by Zadeh [19] is a generalization of fuzzy sets. It generalizes the membership degree from a singleton to an interval in the unit interval, which represent unknown or ill-known information. The concept of intuitionistic fuzzy sets (IFSs) proposed by Atanassov [20] is another generalization of fuzzy sets. It is given by a pair of fuzzy sets, which provides the membership degree and the non-membership degree, respectively. They represent validity and falsity of the given

information. IVFSs and IFSs are isomorphic in math, but their motivations and circumstances are different. They provide more possible semantic interpretations for uncertain information, so the theory of IFSs has been applied in wide fields, such as approximate reasoning, decision making, clustering analysis, data mining, and so on [21–28].

IFMP (intuitionistic fuzzy modus ponens) and IFMT (intuitionistic fuzzy modus tollens) are the extensions of FMP and FMT in the intuitionistic fuzzy environment, respectively. The essential principles of the CRI method and TIM have been used to solve IFMP and IFMT problems of intuitionistic fuzzy reasoning. The CRI method for intuitionistic fuzzy reasoning was explored in [29]. Zheng et al. [30] extended TIM for intuitionistic fuzzy reasoning and explored the reversibility of TIM for IFMP and IFMT. Concerning the issue on the deficiency of reversibility for TIM in IFMT, Liu and Zheng [31] presented a dual approximate reasoning method of TIM for IFMT. Zheng and Liu [32] advanced TIM for multiple-rules systems with intuitionistic fuzzy information.

For FMP and IFMP problems, the reasoning models coincide as follows:

$$\begin{array}{rcccl}
 \text{Given} & \text{If} & u \text{ is } P & \text{then} & v \text{ is } Q & \cdots & \text{major premise} \\
 \text{input} & & u \text{ is } P^* & & & \cdots & \text{minor premise} \\
 \hline
 \text{output} & & & & v \text{ is } Q^* & \cdots & \text{conclusion}
 \end{array} \tag{1}$$

The fuzzy propositions are represented by the fuzzy sets. The type of sets P, P^*, Q, Q^* is unitary, i.e., they are all FSs and IFSs in FMP and IFMP, respectively. In the process of fuzzy inference, “if-then” rule can be identified as a fuzzy implication operator and an intuitionistic fuzzy implication operator in FMP and IFMP, respectively.

That is to say, model (1) can be considered as a generalized modus ponens (GMP) model. The solution Q^* is determined by the information P, Q, P^* . In fact, the real world is full of all kinds of information, even heterogeneous information. Moreover, the variability of information will lead to confounding of inference rules. How can we represent the mechanism of our reasoning and decision-making in a mixed information environment? It is always a very valuable and challenging topic. Our motivation is to explore fuzzy reasoning in a kind of mixed information environment under the frame of GMP.

From the perspective of information diversity, we suppose that P, Q, P^* are alternative in fuzzy sets or intuitionistic fuzzy sets separately rather than simultaneously. Obviously, by listing all possible types of P, Q, P^* we can obtain eight possibilities, according to Table 1 (F denotes fuzzy set, IF denotes intuitionistic fuzzy set).

Table 1. Types of GMP in fuzzy/intuitionistic fuzzy environment.

Type	P	Q	P^*	Q^*
1	F	F	F	F
2	IF	IF	IF	IF
3	F	F	IF	?
4	IF	IF	F	?
5	F	IF	F	?
6	IF	F	IF	?
7	F	IF	IF	?
8	IF	F	F	?

As can be seen in Table 1, type 1 of GMP is FMP and type 2 of GMP is IFMP. In these two cases, the former P and the rear Q coincide in the type of information, as well as the two formers P and P^* . In type 3 and type 4 of GMP, the former P and the rear Q coincide, but the two formers P and P^* do not. In type 5 and type 6 of GMP, the two formers P and P^* coincide, but the former P and the rear Q do not. In type 7 and type 8 of GMP, the former P and the rear Q do not coincide, neither do the two formers P and P^* . The aim of our paper is how to obtain the solutions of the rest six types of GMP by selecting the solving models based on basic models FMP and IFMP.

2. Preliminaries

Here we review the main concepts and results, which are necessary for our subsequent developments.

Definition 1 ([33]). A *t*-norm is a binary operation $\otimes : [0, 1]^2 \rightarrow [0, 1]$ such that \otimes is commutative, associative, monotonic and has the identity 1. A *t*-conorm is a binary operation $\oplus : [0, 1]^2 \rightarrow [0, 1]$ such that \oplus is commutative, associative, monotonic, and has the identity 0.

A pair (\otimes, \oplus) is called a dual pair of *t*-norm \otimes and *t*-conorm if $x \oplus y = 1 - (1 - x) \otimes (1 - y), \forall x, y \in [0, 1]$. Analogously, $x \otimes y = 1 - (1 - x) \oplus (1 - y)$.

Definition 2 ([8,30,33]). Let \otimes, \rightarrow be two binary operation on $[0,1]$, (\otimes, \rightarrow) is called an adjoint pair if the residual principle holds

$$x \otimes y \leq z \text{ iff } x \leq y \rightarrow z, \forall x, y, z \in [0, 1]$$

\rightarrow is called the residuum of \otimes .

Let \oplus, \ominus be a two binary operation on $[0,1]$, (\oplus, \ominus) is called a co-adjoint pair if the co-residual principle holds,

$$x \leq y \oplus z \text{ iff } x \ominus z \leq y, \forall x, y, z \in [0, 1]$$

\ominus is called the residuum of \oplus .

Proposition 1 ([8,33]). If \otimes is a left-continuous *t*-norm then the residuum \rightarrow of \otimes is derived from

$$x \rightarrow y = \vee \{z \in [0, 1] \mid z \otimes x \leq y\} \tag{2}$$

and \rightarrow is called a residual implication (R-implication) induced by \otimes .

Proposition 2 ([30,31]). If \oplus is a right-continuous *t*-conorm, then the co-residuum \ominus of \oplus is derived from

$$x \ominus y = \wedge \{z \in [0, 1] \mid x \leq z \oplus y\} \tag{3}$$

and \ominus is called fuzzy difference operator induced by \oplus .

Theorem 1 ([10]). Let \rightarrow be an R-implication induced by a left-continuous *t*-norm \otimes in FMP, then the solution Q^* of TIM for FMP is given by the following formula

$$Q^*(v) = \vee_{u \in U} \{P^*(u) \otimes (P(u) \rightarrow Q(v))\}, v \in V \tag{4}$$

Definition 3 ([20]). An intuitionistic fuzzy set A is given by two functions

$$A_t, A_f : U \longrightarrow [0, 1]$$

which satisfy the condition

$$0 \leq A_t(u) + A_f(u) \leq 1, \forall u \in U$$

$A_t(u)$ and $A_f(u)$, respectively, denote the degree of membership and the degree of non-membership of the element u to the set A . An intuitionistic fuzzy set A on the nonempty universe U can be denoted as

$$A = \{ \langle u, A_t(u), A_f(u) \rangle \mid u \in U \}$$

The set of all fuzzy subsets/intuitionistic fuzzy subsets on U is denoted as $F(U)/IF(U)$
 As a generalization of FSs, IFSS extend the range of character value from $[0, 1]$ to the triangle domain $D^* = \{(x, y) \in [0, 1]^2 \mid x + y \leq 1\}$. Let $A_{-t}(u) = 1 - A_t(u), A_{-f}(u) =$

$1 - A_f(u), \forall u \in U$, then IFSs degenerate into FSs if and only if $A_t(u) = A_{-f}(u)$ if and only if $A_f(u) = A_{-t}(u)$.

A partial order on D^* can be defined as follows

$$a, b \in D^*, a = (a_1, a_2), b = (b_1, b_2), a \preceq b \text{ if and only if } a_1 \leq b_1, a_2 \geq b_2.$$

Obviously, $a \wedge b = (a_1 \wedge b_1, a_2 \vee b_2), a \vee b = (a_1 \vee b_1, a_2 \wedge b_2)$. Denote $0^* = (0, 1)$ and $1^* = (1, 0)$. 0^* and 1^* are the bottom element and the top element of D^* , respectively. (D^*, \preceq) is a complete lattice.

Denote $\Box a = (a_1, 1 - a_1), \Diamond a = (1 - a_2, a_2)$. \Box, \Diamond are called the necessity operator and the possibility operator in D^* , respectively [21]. These two operators convert intuitionistic fuzzy numbers into fuzzy numbers.

If we denote an intuitionistic fuzzy set $A = (A_t, A_f)$ for short, then $\Box A = (A_t, 1 - A_t) = (A_t, A_{-t}), \Diamond A = (1 - A_f, A_f) = (A_{-f}, A_f)$. It is easy to find that the IFSs $\Box A, \Diamond A$ degenerate into FSs, i.e., $\Box A = A_t, \Diamond A = A_{-f}$. Obviously, $\Box A \preceq A \preceq \Diamond A$.

Definition 4 ([30]). \otimes_{D^*} is called an intuitionistic t-norm induced by t-norm \otimes if

$$a \otimes_{D^*} b = (a_1 \otimes b_1, a_2 \oplus b_2) \tag{5}$$

\oplus_{D^*} is called an intuitionistic t-conorm induced by t-norm \otimes if

$$a \oplus_{D^*} b = (a_1 \oplus b_1, a_2 \otimes b_2) \tag{6}$$

where \oplus is the dual t-conorm of the t-norm \otimes .

Theorem 2 ([30]). Let \otimes_{D^*} be an intuitionistic t-norm induced by a left-continuous t-norm \otimes , then there exists a binary operation \rightarrow_{D^*} on D^* satisfying the residual principle, i.e.,

$$c \otimes_{D^*} a \preceq b \text{ iff } c \preceq a \rightarrow_{D^*} b \tag{7}$$

and \rightarrow_{D^*} is given by

$$a \rightarrow_{D^*} b = \vee \{d \in D^* \mid d \otimes_{D^*} a \preceq b\} \tag{8}$$

Definition 5 ([30]). $(\otimes_{D^*}, \rightarrow_{D^*})$ is called an intuitionistic adjoint pair if $(\otimes_{D^*}, \rightarrow_{D^*})$ satisfy (2.6) and \rightarrow_{D^*} is called an intuitionistic R-implication if \otimes_{D^*} is an intuitionistic t-norm induced by a left-continuous \otimes .

Theorem 3 ([30]). Let $a, b \in D^*, a = (a_1, a_2), b = (b_1, b_2), \otimes_{D^*}$ be an intuitionistic t-norm induced by a left-continuous t-norm \otimes , then

$$a \rightarrow_{D^*} b = ((a_1 \rightarrow b_1) \wedge (1 - b_2 \ominus a_2), b_2 \ominus a_2) \tag{9}$$

Theorem 4 ([30]). Let \rightarrow_{D^*} be an intuitionistic R-implication in IFMP, then the solution Q^* of TIM for IFMP is given by the following formula

$$Q^*(v) = \vee_{u \in U} \{P^*(u) \otimes_{D^*} (P(u) \rightarrow_{D^*} Q(v))\}, v \in V \tag{10}$$

Corollary 1 ([30]). Let \rightarrow_{D^*} be an intuitionistic R-implication in IFMP, then the triple I solution $Q^*(v) = (Q_t^*(v), Q_f^*(v))$ where

$$\begin{aligned} Q_t^*(v) &= \vee_{x \in U} \{P_t^*(u) \otimes ((P_t(u) \rightarrow Q_t(v)) \wedge (P_{-f}(u) \rightarrow Q_{-f}(v)))\} \\ Q_f^*(v) &= \wedge_{u \in U} \{P_f^*(u) \oplus (1 - P_{-f}(u) \rightarrow Q_{-f}(v))\} \end{aligned} \tag{11}$$

3. Solving Type 3 and Type 4 of GMP Based on the Principle of Major Premise Precedence

The basic character of type 3 and type 4 of GMP is that the former P and the rear Q coincide as information type in the major premise. It is a natural ideal that the selected

solving model should be either FMP or IFMP according to the condition that P, Q are either FSs or IFSs—this is called the principle of major premise precedence.

3.1. Decomposition Triple I Method (DTIM) for Solving Type 3 of GMP

In this subsection, we consider inference methods of type 3 of GMP. The inference model is as follows:

$$\begin{array}{rcl}
 \text{Given} & \text{If } u \text{ is } P & \text{then } v \text{ is } Q \quad \dots \text{ major premise} \\
 \text{input} & u \text{ is } P^* & \dots \text{ minor premise} \\
 \hline
 \text{output} & & v \text{ is } Q^* \quad \dots \text{ conclusion}
 \end{array} \tag{12}$$

where $P \in F(U), Q \in F(V), P^* \in IF(U), u \in U, v \in V$. Q^* , as unknown information, is either a fuzzy set or an intuitionistic fuzzy set.

Because P and Q are FSs, “if-then” rule can be taken as fuzzy inference. We should solve Q^* by converting the intuitionistic fuzzy set P^* into fuzzy sets based on fuzzy inference model FMP. We denote

$$\square P^* = (P_t^*, 1 - P_t^*) = (P_t^*, P_{-t}^*), \diamond P^* = (1 - P_f^*, P_f^*) = (P_{-f}^*, P_f^*).$$

Obviously, $\square P^* = P_t^*, \diamond P^* = P_{-f}^*. \square P^* \preceq P^* \preceq \diamond P^*$.

Therefore, firstly, we decompose the model (12) to two FMP models in which P_t^*, P_{-f}^* are the formers, respectively. Secondly, we obtain the solutions of FMP problems by TIM. Finally, we aggregate the two solutions to obtain Q^* .

Step1: We decompose the model (12) into two FMP models as follows:

$$\begin{array}{rcl}
 \text{Given} & P(u) & \rightarrow Q(v) \\
 \text{input} & P_t^*(u) & \\
 \hline
 \text{output} & & Q_1^*(v)
 \end{array} \tag{13}$$

$$\begin{array}{rcl}
 \text{Given} & P(u) & \rightarrow Q(v) \\
 \text{input} & P_{-f}^*(u) & \\
 \hline
 \text{output} & & Q_2^*(v)
 \end{array} \tag{14}$$

where \rightarrow is an R-implication.

Step2: We use TIM to solve the models (13) and (14), respectively. According to Theorem 1, we obtain the solutions as follows:

$$Q_1^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P(u) \rightarrow Q(v))\}$$

$$Q_2^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P(u) \rightarrow Q(v))\}$$

Since $P_t^*(u) + P_{-f}^*(u) \leq 1$, i.e., $P_t^*(u) \leq P_{-f}^*(u), \forall u \in U$, it follows from the properties of fuzzy operators that, $Q_1^*(v) \leq Q_2^*(v), \forall v \in V$. Now, we obtain the solutions Q_1^*, Q_2^* of model (13) and model (14), respectively. How can we obtain the solutions Q^* of model (12) from Q_1^*, Q_2^* ? The core of the question is which information type of Q^* it is. Obviously, it depends on what kind of information type of Q^* we want to obtain. So we have two choices, either a fuzzy set or an intuitionistic fuzzy set.

Step3: Presenting the solution Q^* of model (12).

Case1: If we suppose that $Q^* \in F(V)$, then it is reasonable that any $Q^* \in [Q_1^*, Q_2^*]$ can be the solution of model (12).

Case2: If we suppose that $Q^* \in IF(V)$, then we can aggregate Q_1^*, Q_2^* to be the following intuitionistic fuzzy set as the solution of model (12).

$$Q^* = (Q_1^*, 1 - Q_2^*)$$

Example 1. Let $U = \{u_1, u_2, u_3\}, V = \{v_1, v_2, v_3\}$

$P = \{ \langle u_1, 0.5 \rangle, \langle u_2, 0.7 \rangle, \langle u_3, 0.9 \rangle \},$
 $Q = \{ \langle v_1, 0.6 \rangle, \langle v_2, 0.8 \rangle, \langle v_3, 0.7 \rangle \},$
 $P^* = \{ \langle u_1, 0.6, 0.3 \rangle, \langle u_2, 0.5, 0.2 \rangle, \langle u_3, 0.8, 0.1 \rangle \},$
 $\rightarrow, \rightarrow_{D^*}$ are R-implications induced by Lukasiewicz t-norm \otimes_{Lu} . Now we derive the solution Q^* of type 3 GMP by DTIM.

$\forall x, y \in [0, 1], x \otimes_{Lu} y = (x + y - 1) \vee 0, x \rightarrow_{Lu} y = (1 - x + y) \wedge 1$
 It follows from

$$Q_1^*(v) = \vee_{u \in U} \{ P_t^*(u) \otimes (P(u) \rightarrow Q(v)) \}$$

that

$$\begin{aligned}
 Q_1^*(v_1) &= \vee_{u \in U} \{ P_t^*(u) \otimes (P(u) \rightarrow Q(v_1)) \} = 0.6 \\
 Q_1^*(v_2) &= \vee_{u \in U} \{ P_t^*(u) \otimes (P(u) \rightarrow Q(v_2)) \} = 0.7 \\
 Q_1^*(v_3) &= \vee_{u \in U} \{ P_t^*(u) \otimes (P(u) \rightarrow Q(v_3)) \} = 0.6
 \end{aligned}$$

Thus, $Q_1^* = \{ \langle v_1, 0.6 \rangle, \langle v_2, 0.7 \rangle, \langle v_3, 0.6 \rangle \}$

Similarly, $Q_2^* = \{ \langle v_1, 0.7 \rangle, \langle v_2, 0.8 \rangle, \langle v_3, 0.8 \rangle \}$

Therefore, if Q^* is a fuzzy set, then $Q^* \in [Q_1^*, Q_2^*]$. That is, the membership degree of v_1, v_2, v_3 is a value in interval $[0.6, 0.7], [0.7, 0.8],$ and $[0.6, 0.8],$ respectively. If Q^* is an intuitionistic fuzzy set, then $Q^* = (Q_1^*, 1 - Q_2^*),$ i.e.,

$$Q^* = \{ \langle v_1, 0.6, 0.3 \rangle, \langle v_2, 0.7, 0.2 \rangle, \langle v_3, 0.6, 0.2 \rangle \}$$

3.2. Expansion Triple I Method (ETIM) for Solving Type 4 of GMP

The solving method of type 4 GMP is similar to that of type 3. The model of type 4 is as follows:

Given input	If u is P u is P^*	then v is Q	... major premise ... minor premise	(15)
output	v is Q^* ... conclusion			

where $P \in IF(U), Q \in IF(V), P^* \in F(U), u \in U, v \in V.$ Denote $P = (P_t, P_f), Q = (Q_t, Q_f).$

“If-then” rule could be taken as an intuitionistic fuzzy implication relation because P, Q are IFs. The fuzzy set P^* as a degenerated intuitionistic fuzzy set, can be denoted as $P'^* = (P^*, 1 - P^*).$ Based on the principle of major premise precedence, we could transform the model (15) into an IFMP model to obtain the solution by TIM of intuitionistic fuzzy reasoning.

Step1: The model (15) is transformed into the following IFMP model:

Given input	$P(u)$ $P'^*(u)$	\rightarrow_{D^*}	$Q(v)$	(16)
output	$Q'^*(v)$			

where $P = (P_t, P_f), Q = (Q_t, Q_f), P'^* = (P^*, 1 - P^*), Q'^* = (Q_t^*, Q_f^*),$ and \rightarrow_{D^*} is an intuitionistic R-implication.

Step2: Solving the model (16). Since the model (16) is an IFMP problem, we can obtain the output $Q'^*(v) = (Q_t'^*(v), Q_f'^*(v))$ by TIM. According to Corollary 1

$$\begin{aligned}
 Q_t'^*(v) &= (\vee_{u \in U} \{ P^*(u) \otimes (P_t(u) \rightarrow Q_t(v)) \wedge (P_{-f}(u) \rightarrow Q_{-f}(v)) \}) \\
 Q_f'^*(v) &= \wedge_{u \in U} \{ (1 - P^*(u) \oplus (1 - P_{-f}(u) \rightarrow Q_{-f}(v))) \} \\
 &= 1 - \vee_{u \in U} \{ P^*(u) \otimes (P_{-f}(u) \rightarrow Q_{-f}(v)) \}
 \end{aligned}$$

Step3: Presenting the solution Q^* of model (15). As we explain in the previous subsection, the form of Q^* depends on the type of solution we want.

Case1: If we suppose that $Q^* \in IF(V),$ then $Q^* = Q'^*.$

Case2: If we suppose that $Q^* \in F(V),$ then $Q^* \in [Q_t'^*, 1 - Q_f'^*].$

Example 2. Let $U = \{u_1, u_2, u_3\}, V = \{v_1, v_2, v_3\}$
 $P = \{ \langle u_1, 0.5, 0.3 \rangle, \langle u_2, 0.7, 0.2 \rangle, \langle u_3, 0.9, 0.1 \rangle \},$
 $Q = \{ \langle v_1, 0.6, 0.2 \rangle, \langle v_2, 0.8, 0.1 \rangle, \langle v_3, 0.6, 0.3 \rangle \},$
 $P^* = \{ \langle u_1, 0.6 \rangle, \langle u_2, 0.7 \rangle, \langle u_3, 0.9 \rangle \},$
 $\rightarrow, \rightarrow_{D^*}$ are R-implications induced by Lukasiewicz t-norm \otimes_{Lu} . Now, we derive the solution Q^* of type 4 GMP by ETIM.

It follows from

$$Q_i^*(v) = \bigvee_{u \in U} \{ P^*(u) \otimes ((P_t(u) \rightarrow Q_t(v)) \wedge (P_{-f}(u) \rightarrow Q_{-f}(v))) \}$$

that $Q_t^*(v_1) = 0.6, Q_t^*(v_2) = 0.8, Q_t^*(v_3) = 0.6$. Thus

$$Q_t^* = \{ \langle v_1, 0.6 \rangle, \langle v_2, 0.8 \rangle, \langle v_3, 0.6 \rangle \}.$$

$$\text{Similarly, } Q_f^* = \{ \langle v_1, 0.2 \rangle, \langle v_2, 0.1 \rangle, \langle v_3, 0.3 \rangle \}.$$

Therefore, if Q^* is an intuitionistic fuzzy set, then

$$Q^* = (Q_t^*, Q_f^*) = \{ \langle v_1, 0.6, 0.2 \rangle, \langle v_2, 0.8, 0.1 \rangle, \langle v_3, 0.6, 0.3 \rangle \}.$$

If Q^* is a fuzzy set, then $Q^* \in [Q_t^*, Q_{-f}^*]$. That is, the membership degree of v_1, v_2, v_3 is a value in interval $[0.6, 0.8], [0.8, 0.9],$ and $[0.6, 0.7],$ respectively.

4. Two Basic Methods for Solving Type 3 and Type 4 of GMP Again

It is reasonable to adopt different methods to solve the type 3 and type 4 of GMP models based on the principle of major premise precedence. In fact, the decomposition method and expansion method reflect two basic ideas of transformation to deal with mixed information models of GMP. So these two basic methods can be used to solve any model in type 3–8 of the GMP models.

4.1. ETIM for Solving Type 3 of GMP

In this subsection, we will approach the type 3 of GMP again by the expansion method. If we take this method, then we should take the fuzzy sets P and Q in model (12) as the degenerated intuitionistic fuzzy sets. The model (12) is transformed into the following IFMP model:

Given	$P'(u)$	\rightarrow_{D^*}	$Q'(v)$	(17)
input	$P'^*(u)$			
output			$Q'^*(v)$	

where $P' = (P'_t, P'_f) = (P, 1 - P), Q' = (Q'_t, Q'_f) = (Q, 1 - Q), P'^* = (P'^*_t, P'^*_f), Q'^* = (Q'^*_t, Q'^*_f)$. Obviously, $P'_t = P, P'_{-f} = P, Q'_t = Q, Q'_{-f} = Q$

According to Corollary 1, we obtain that

$$\begin{aligned} Q'^*_t(v) &= \bigvee_{u \in U} \{ P'^*_t(u) \otimes ((P'_t(u) \rightarrow Q'_t(v)) \wedge (P'_{-f}(u) \rightarrow Q'_{-f}(v))) \} \\ &= \bigvee_{u \in U} \{ P'^*_t(u) \otimes (P(u) \rightarrow Q(v)) \} \\ Q'^*_f(v) &= \bigwedge_{u \in U} \{ P'^*_f(u) \oplus (1 - (P'_{-f}(u) \rightarrow Q'_{-f}(v))) \} \\ &= \bigwedge_{u \in U} \{ P'^*_f(u) \oplus (1 - (P(u) \rightarrow Q(v))) \} \\ Q'^*_{-f}(v) &= \bigvee_{u \in U} \{ P'^*_{-f}(u) \otimes (P(u) \rightarrow Q(v)) \} \end{aligned}$$

It is easy to obtain the output Q'^* of model (17). The solution Q^* of model (12) is consequently derived from Q'^* .

If $Q^* \in IF(V)$, then $Q^* = Q'^*$.

If $Q^* \in F(V)$, then $Q^* \in [Q'^*_t, 1 - Q'^*_f] = [Q'^*_t, Q'^*_{-f}]$.

Comparing the solution of ETIM with the solution of DTIM for the type 3 of GMP, we can find the following conclusion.

Theorem 5. ETIM is equivalent to DTIM for model (12).

4.2. DTIM for Solving Type 4 of GMP

The major premise of type 4 of GMP can be represented as an intuitionistic fuzzy proposition “ $P(u) \rightarrow_{D^*} Q(v)$ ” where $P = (P_t, P_f), Q = (Q_t, Q_f)$. How could we transfer model (15) of type 4 into FMP problems when the minor premise is a fuzzy proposition? In fact, Formula (9) explicates the relationship between intuitionistic fuzzy implication and fuzzy operators, so the argument formula of the triple I solution for IFMP is represented by Formula (11). According to Formula (11), a decomposition method for IFMP is proposed in the paper [34]. Naturally, Formula (11) also tells us the approach of transformation.

The model (15) is transformed into the two following FMP problems:

$$\begin{array}{lcl}
 \text{Given} & P_t(u) \rightarrow & Q_t(v) \\
 \text{input} & P^*(u) & \\
 \hline
 \text{output} & & Q_1^*(v)
 \end{array} \tag{18}$$

$$\begin{array}{lcl}
 \text{Given} & P_{-f}(u) \rightarrow & Q_{-f}(v) \\
 \text{input} & P^*(u) & \\
 \hline
 \text{output} & & Q_2^*(v)
 \end{array} \tag{19}$$

According to Theorem 1, we obtain

$$Q_1^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P_t(u) \rightarrow Q_t(v))\}$$

$$Q_2^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P_{-f}(u) \rightarrow Q_{-f}(v))\}$$

If $Q^* \in F(V)$, then it is appropriate that $Q^* = Q_1^* \wedge Q_2^*$ considering the condition that Q_1^* and Q_2^* do not constitute a partial order relation in the sense of fuzzy sets. If $Q^* \in IF(V)$, we can obtain $Q^* = (Q_1^* \wedge Q_2^*, 1 - Q_2^*)$ by aggregating Q_1^*, Q_2^* .

5. Relationship between DTIM and ETIM

For the types 3 and 4 of GMP, we show the concrete solution steps and obtain their solution by using DTIM and ETIM, respectively, in Sections 3 and 4. It is similar to obtaining the solutions of type 5–8 of GMP by DTIM and ETIM. According to the results of Sections 3 and 4, we could provide the following tables (Tables 2 and 3) to show their solutions for types 3–4 of GMP, and do so for types 5–8 of GMP (Tables 4–7).

Remark 1. For each type of GMP, the solutions Q_1^*, Q_2^* of DTIM and the solutions Q_t^*, Q_f^*, Q_{-f}^* of ETIM are derived from Formula (4) and Formula (11), respectively. Different types can lead to differences in formula form. In Sections 3 and 4, we have a specific interpretation to how to obtain the form of these solutions for type 3 and type 4 of GMP. Once we have properly represented the information P, Q, P^* in the different types of model, the process of obtaining the solutions of the remaining types (types 3–8) GMP is trivial. In the calculation of some formulas, we need to use the results of preliminaries and the properties of fuzzy operators. These details are also trivial.

Theorem 6. DTIM is equivalent to ETIM for the mixed types of GMP models if P is a fuzzy set.

Proof. In fact, the mixed types of GMP are type 3–8 of GMP. If P is a fuzzy set, they are type 3, 5, and 7 of GMP. It is valid for type 3 of GMP from Theorem 5 and types 5 and 7 of GMP from Tables 4 and 5. □

Remark 2. Obviously, DTIM is not equivalent to ETIM when $P \in IF(V)$, but the intuitionistic fuzzy solution Q^* of DTIM is equivalent to that of ETIM for types 4 and 8 of GMP. From Tables 2–7, we can find that the second argument of intuitionistic fuzzy solution Q^* by DTIM is equal to that by ETIM for all types of GMP. That is, the second argument of intuitionistic fuzzy solution has invariance property by the two basic methods for all types of GMP.

Table 2. Solutions of type 3 of GMP based on DTIM and ETIM.

Type 3	F/IF	DTIM	ETIM
P	F	P	$(P, 1 - P)$
Q	F	Q	$(Q, 1 - Q)$
P^*	IF	(P_t^*, P_f^*)	(P_t^*, P_f^*)
		$Q_1^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P(u) \rightarrow Q(v))\}$ $Q_2^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P(u) \rightarrow Q(v))\}$	$Q_t^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P(u) \rightarrow Q(v))\}$ $Q_f^*(v) = \bigwedge_{u \in U} \{P_f^*(u) \otimes (P(u) \rightarrow Q(v))\}$ $Q_{-f}^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P(u) \rightarrow Q(v))\}$
Q^*	F	$Q^* \in [Q_1^*, Q_2^*]$	$Q^* \in [Q_t^*, Q_{-f}^*]$
Q^*	IF	$Q^* = (Q_1^*, 1 - Q_2^*)$	$Q^* = (Q_t^*, Q_f^*)$

Table 3. Solutions of type 4 of GMP based on DTIM and ETIM.

Type 4	F/IF	DTIM	ETIM
P	IF	(P_t, P_f)	(P_t, P_f)
Q	IF	(Q_t, Q_f)	(Q_t, Q_f)
P^*	F	P^*	$(P^*, 1 - P^*)$
		$Q_1^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P_t(u) \rightarrow Q_t(v))\}$ $Q_2^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P_{-f}(u) \rightarrow Q_{-f}(v))\}$	$Q_t^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes ((P_t(u) \rightarrow Q_t(v)) \wedge (P_{-f}(u) \rightarrow Q_{-f}(v)))\}$ $Q_f^*(v) = \bigwedge_{u \in U} \{(1 - P^*(u)) \oplus (1 - P_{-f}(u) \rightarrow Q_{-f}(v))\}$ $Q_{-f}^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P_{-f}(u) \rightarrow Q_{-f}(v))\}$
Q^*	F	$Q^* = Q_1^* \wedge Q_2^*$	$Q^* \in [Q_t^*, Q_{-f}^*]$
Q^*	IF	$Q^* = (Q_1^* \wedge Q_2^*, 1 - Q_2^*)$	$Q^* = (Q_t^*, Q_f^*)$

Table 4. Solutions of type 5 of GMP based on DTIM and ETIM.

Type 5	F/IF	DTIM	ETIM
P	F	P	$(P, 1 - P)$
Q	IF	(Q_t, Q_f)	(Q_t, Q_f)
P^*	F	P^*	$(P^*, 1 - P^*)$
		$Q_1^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P(u) \rightarrow Q_t(v))\}$ $Q_2^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P(u) \rightarrow Q_{-f}(v))\}$	$Q_t^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P(u) \rightarrow Q_t(v))\}$ $Q_f^*(v) = \bigwedge_{u \in U} \{(1 - P^*(u)) \oplus (1 - P(u) \rightarrow Q_{-f}(v))\}$ $Q_{-f}^*(v) = \bigvee_{u \in U} \{P^*(u) \otimes (P(u) \rightarrow Q_{-f}(v))\}$
Q^*	F	$Q^* \in [Q_1^*, Q_2^*]$	$Q^* \in [Q_t^*, Q_{-f}^*]$
Q^*	IF	$Q^* = (Q_1^*, 1 - Q_2^*)$	$Q^* = (Q_t^*, Q_f^*)$

Table 5. Solutions of type 6 of GMP based on DTIM and ETIM.

Type 6	F/IF	DTIM	ETIM
P	IF	(P_t, P_f)	(P_t, P_f)
Q	F	Q	$(Q, 1 - Q)$
P^*	IF	(P_t^*, P_f^*)	(P_t^*, P_f^*)
		$Q_1^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P_t(u) \rightarrow Q(v))\}$ $Q_2^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$	$Q_t^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$ $Q_f^*(v) = \bigwedge_{u \in U} \{P_f^*(u) \oplus (1 - P_{-f}(u) \rightarrow Q(v))\}$ $Q_{-f}^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$
Q^*	F	$Q^* = Q_1^* \wedge Q_2^*$	$Q^* \in [Q_t^*, Q_{-f}^*]$
Q^*	IF	$Q^* = (Q_1^* \wedge Q_2^*, 1 - Q_2^*)$	$Q^* = (Q_t^*, Q_f^*)$

Table 6. Solutions of type 7 of GMP based on DTIM and ETIM.

Type 7 F/IF DTIM			ETIM
P	F	P	$(P, 1 - P)$
Q	IF	(Q_t, Q_f)	(Q_t, Q_f)
P^*	IF	(P_t^*, P_f^*)	(P_t^*, P_f^*)
		$Q_1^*(v) = \forall_{u \in U} \{P_t^*(u) \otimes (P(u) \rightarrow Q_t(v))\}$ $Q_2^*(v) = \forall_{u \in U} \{P_{-f}^*(u) \otimes (P(u) \rightarrow Q_{-f}(v))\}$	$Q_t^*(v) = \forall_{u \in U} \{P_t^*(u) \otimes (P(u) \rightarrow Q_t(v))\}$ $Q_f^*(v) = \wedge_{u \in U} \{P_f^*(u) \oplus (1 - P(u) \rightarrow Q_{-f}(v))\}$ $Q_{-f}^*(v) = \forall_{u \in U} \{P_{-f}^*(u) \otimes (P(u) \rightarrow Q_{-f}(v))\}$
Q^*	F	$Q^* \in [Q_1^*, Q_2^*]$	$Q^* \in [Q_t^*, Q_{-f}^*]$
Q^*	IF	$Q^* = (Q_1^*, 1 - Q_2^*)$	$Q^* = (Q_t^*, Q_f^*)$

Table 7. Solutions of type 8 of GMP based on DTIM and ETIM.

Type 8 F/IF DTIM			ETIM
P	IF	(P_t, P_f)	(P_t, P_f)
Q	F	Q	$(Q, 1 - Q)$
P^*	F	P^*	$(P^*, 1 - P^*)$
		$Q_1^*(v) = \forall_{u \in U} \{P^*(u) \otimes (P_t(u) \rightarrow Q(v))\}$ $Q_2^*(v) = \forall_{u \in U} \{P^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$	$Q_t^*(v) = \forall_{u \in U} \{P^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$ $Q_f^*(v) = \wedge_{u \in U} \{(1 - P^*(u)) \oplus (1 - P_{-f}(u) \rightarrow Q(v))\}$ $Q_{-f}^*(v) = \forall_{u \in U} \{P^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$
Q^*	F	$Q^* \in [Q_2^*, Q_1^*]$	$Q^* = Q_t^* = Q_{-f}^*$
Q^*	IF	$Q^* = (Q_2^*, 1 - Q_2^*)$	$Q^* = (Q_t^*, Q_f^*)$

Figure 1 shows the core process of solving the mixture type of GMP problem by DTIM and ETIM.

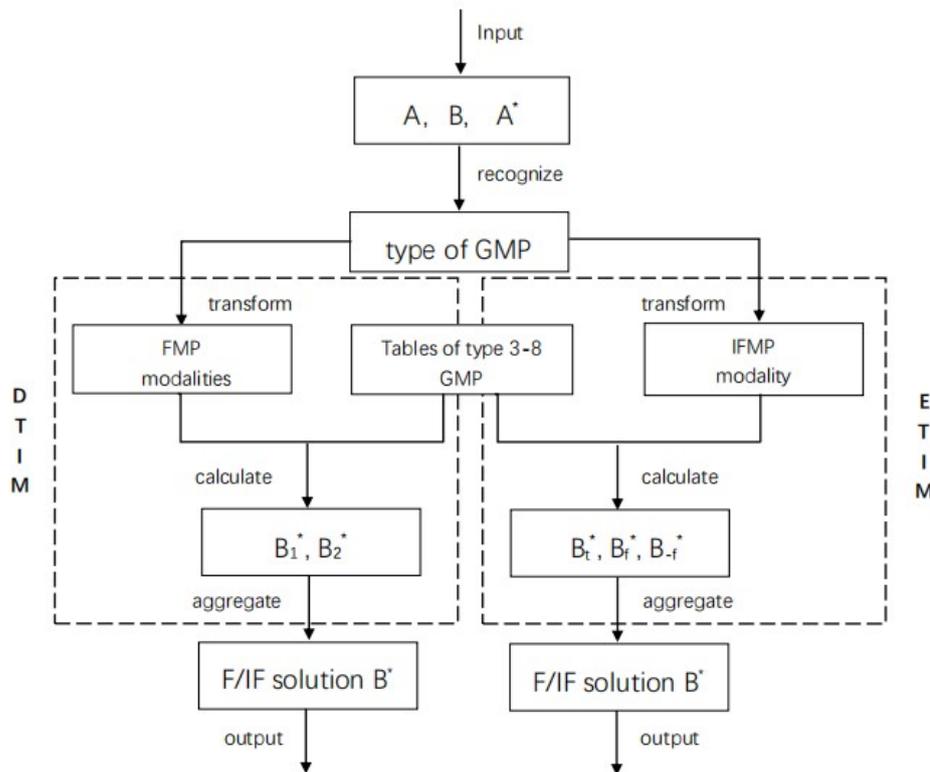


Figure 1. Flow diagram for solving the mixture type of GMP.

6. Reversibility of DTIM and ETIM

As we all know, the reversibility of inference methods is an important issue in fuzzy reasoning. The TIM of FMP and IFMP is reversible. It is interesting to explore whether DTIM and ETIM satisfy the reversibility, i.e., $P^* = P$ implies $Q^* = Q$.

Definition 6. In FMP/IFMP, a method is called C-reversible if $P^* = P$ implies $Q^* = Q$ whenever condition (C) is satisfied.

In particular, if the condition (C) is: P is normal, i.e., $\exists u_0$ such that $P(u_0) = 1$ (or $P(u_0) = 1^*$) then the prefix C- can be omitted. TIM possesses virtue of reversibility compared with CRI.

Theorem 7 ([8,30]). TIM of FMP/IFMP is reversible, i.e., $Q^* = Q$ whenever $P^* = P$ is normal.

Corollary 2. If there exists u_0 such that $P(u_0) = 1$, then

$$\bigvee_{u \in U} \{P(u) \otimes (P(u) \rightarrow Q(v))\} = Q(v), v \in V$$

In any mixed type of GMP, we provide the two alternatives for Q^* , a fuzzy set or an intuitionistic fuzzy set. When we mention the reversibility of a method to solve a mixed type of GMP, it means that an alternative Q^* satisfies $Q^* = Q$ if $P^* = P$. Of course, we realize that the assumption $P^* = P$ is not always satisfied. When $P \in F(U)$, $P^* \in IF(U)$, the assumption can be satisfied, but in the reverse, when $P \in IF(U)$, $P^* \in F(U)$, the assumption can not be guaranteed. Types 3–8 of GMP are concerned except type 4 and type 8.

Theorem 8. For types 3, 5, and 7 of GMP, DTIM and ETIM are reversible, i.e., $Q^* = Q$ whenever $P^* = P$ is normal.

Proof. In types 3, 5, and 7 of GMP, P is a fuzzy set. According to Theorem 6, DTIM is equivalent to ETIM for these types of GMP. So we only need prove that DTIM is reversible. By DTIM, type 3 of GMP is transformed into two FMP problems and the two solutions of FMP problems are given, respectively, as follows,

$$Q_1^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P(u) \rightarrow Q(v))\}$$

$$Q_2^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P(u) \rightarrow Q(v))\}$$

If $P^* = P$, i.e., $(P_t^*, P_f^*) = (P, 1 - P)$, then $P_t^* = P$, $P_{-f}^* = P$. P is normal, i.e., $\exists u_0$ such that $P(u_0) = 1$, so

$$Q_1^* = \bigvee_{u \in U} \{P(u) \otimes (P(u) \rightarrow Q(v))\} = Q$$

$$Q_2^* = \bigvee_{u \in U} \{P(u) \otimes (P(u) \rightarrow Q(v))\} = Q$$

Therefore, if Q^* is a fuzzy set, then $Q^* = Q$. Meanwhile, if Q^* is an intuitionistic fuzzy set, then $Q^* = (Q, 1 - Q) = Q$. The proof for type 3 of GMP is completed. It is similar for types 5 and 7 of GMP. \square

Theorem 9. For type 6 of GMP, DTIM and ETIM are reversible, i.e., $Q^* = Q$ whenever $P^* = P$ is normal.

Proof. In type 6 of GMP, P and P^* are intuitionistic fuzzy sets and Q is a fuzzy set. Put $P = (P_t, P_f)$, $P^* = (P_t^*, P_f^*)$. By DTIM, we obtain

$$Q_1^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P_t(u) \rightarrow Q(v))\}$$

$$Q_2^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$$

Since $P^* = P$ is normal, we obtain

$$Q_1^* = \bigvee_{u \in U} \{P(u) \otimes (P(u) \rightarrow Q(v))\} = Q$$

$$Q_2^* = \bigvee_{u \in U} \{P(u) \otimes (P(u) \rightarrow Q(v))\} = Q$$

Therefore, if Q^* is a fuzzy set, then $Q^* = Q$. Thus, DTIM is reversible.

By ETIM,

$$Q_t^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$$

$$Q_{-f}^*(v) = \bigvee_{u \in U} \{P_{-f}^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$$

Obviously, when $P^* = P$, i.e., $(P_t^*, P_f^*) = (P_t, P_f)$ and P is normal,

$$Q_{-f}^*(v) = \bigvee_{u \in U} \{P_{-f}(u) \otimes (P_{-f}(u) \rightarrow Q(v))\} = Q(v)$$

$$\begin{aligned} Q_t^*(v) &= \bigvee_{u \in U} \{P_t(u) \otimes (P_{-f}(u) \rightarrow Q(v))\} \\ &\leq \bigvee_{u \in U} \{P_{-f}(u) \otimes (P_{-f}(u) \rightarrow Q(v))\} \\ &= Q(v) \end{aligned}$$

P is normal. It is said that there exists u_0 such that $P(u_0) = 1$, i.e., $P_t(u_0) = 1$, $P_f(u_0) = 0$, $P_{-f}(u_0) = 1$. It follows from

$$Q_t^*(v) = \bigvee_{u \in U} \{P_t^*(u) \otimes (P_{-f}(u) \rightarrow Q(v))\}$$

that

$$Q_t^*(v) \geq 1 \otimes (1 \rightarrow Q(v)) = Q(v)$$

So $Q_t^* = Q$. Therefore, if Q^* is a fuzzy set, then $Q^* = Q$. Thus, ETIM is also reversible. \square

7. Conclusions

FMP and IFMP are the two representations of GMP in the fuzzy environment and intuitionistic fuzzy environment, respectively. They are basic and important problems in fuzzy reasoning. For a mix of fuzzy/intuitionistic fuzzy information, we discussed six mixed types of GMP in this paper. Based on TIM, we took two basic transformation patterns—decomposition and expansion—to solve each mixed type of GMP problem. By DTIM and ETIM, we transformed a mixed type of GMP problem into FMP problems and IFMP problems, respectively, gave the corresponding triple I solutions of FMP problems and IFMP problems, and composited these solutions to obtain the solution of the GMP problem. We obtained the solutions of DTIM and ETIM for six mixed types of GMP and presented the equivalence between DTIM and ETIM. Moreover, we investigated the reversibility of DTIM and ETIM and found that DTIM and ETIM were reversible except for types 4 and 8 of GMP. Our research proposes methods for fuzzy reasoning with specific types of mixed information. We are looking forward to this work supporting and aiding the wider application of fuzzy reasoning.

In the future, we will focus on the following issues: (1) It is interesting and valuable to generalize our methods or explore a novel method for the mixture of more general and complex fuzzy information. (2) The triple I method based on the flexible ordering property was proposed in [18]. The performance of DTIM and ETIM with the flexible ordering property deserves further study.

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