

# *e*-Distance in Menger PGM Spaces with an Application

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**Abstract:** The main purpose of the present paper is to define the concept of an *e*-distance (as a generalization of *r*-distance) on a Menger PGM space and to introduce some of its properties. Moreover, some coupled fixed point results, in terms of this distance on a complete PGM space, are proved. To support our definitions and main results, several examples and an application are considered.

**Keywords:** *e*-distance; Menger PGM space; coupled fixed point

**MSC:** JPrimary 47H10; Secondary 47S50



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## 1. Introduction and Preliminaries

In 1942, Menger [1] introduced Menger probabilistic metric spaces as an extension of metric spaces. After that, Sehgal and Bharucha-Reid [2,3] studied some fixed point results for different classes of probabilistic contractions (also, see and references in the citation). Moreover, in 2009, Saadati et al. [4] introduced the concept of *r*-distance on this space.

Throughout this paper, the set of all Menger distance distribution functions are denoted by  $D^+$ .

**Definition 1** ([5], page 1). A binary mapping  $\mathcal{T} : [0, 1] \times [0, 1] \rightarrow [0, 1]$  is called *t*-norm if the following properties are held:

- (a)  $\mathcal{T}$  is commutative and associative;
- (b)  $\mathcal{T}$  is continuous;
- (c)  $\mathcal{T}(a, 1) = a$  if  $a \in [0, 1]$ ;
- (d)  $\mathcal{T}(a, b) \leq \mathcal{T}(c, d)$  if  $a \leq c$  and  $b \leq d$  for every  $a, b, c, d \in [0, 1]$ .

**Definition 2** ([4]). A *t*-norm  $\mathcal{T}$  is called an *H*-type I if for  $\epsilon \in (0, 1)$ , there exist  $\delta \in (0, 1)$  so that  $\mathcal{T}^m(1 - \delta, \dots, 1 - \delta) > 1 - \epsilon$  for each  $m \in \mathbb{N}$ , where  $\mathcal{T}^m$  recursively defined by  $\mathcal{T}^1 = \mathcal{T}$  and  $\mathcal{T}^m(t_1, t_2, \dots, t_{m+1}) = \mathcal{T}(\mathcal{T}^{m-1}(t_1, t_2, \dots, t_m), t_{m+1})$  for  $m = 2, 3, \dots$  and  $t_i \in [0, 1]$ .

All *t*-norms in the sequel are from class of *H*-type I.

From another point of view, Mustafa and Sims [6] defined *G*-metric spaces as another extension of metric spaces, analyzed the structure of this space, and continued the theory of fixed point in such spaces. In 2014, Zhou et al. [7], by combining Menger *PM*-spaces and *G*-metric spaces, defined Menger probabilistic generalized metric space (shortly, Menger PGM space). Other researchers extended several fixed point theorems in [8–10] and references contained therein.

**Definition 3** ([7]). Assume that  $\mathcal{X}$  is a nonempty set,  $\mathcal{T}$  is a continuous *t*-norm and  $G : \mathcal{X}^3 \rightarrow D^+$  is a mapping satisfying the following properties for all  $x, y, z, a \in \mathcal{X}$  and  $s, t > 0$ :

- (PG1)  $G_{x,y,z}(t) = 1$  if and only if  $x = y = z$ ;
- (PG2)  $G_{x,x,y}(t) \geq G_{x,y,z}(t)$ , where  $z \neq y$ ;
- (PG3)  $G_{x,y,z}(t) = G_{x,z,y}(t) = G_{y,x,z}(t) = \dots$ ;
- (PG4)  $G_{x,y,z}(t+s) \geq \mathcal{T}(G_{x,a,a}(s), G_{a,y,z}(t))$ .

Then  $(\mathcal{X}, G, \mathcal{T})$  is named a Menger PGM space.

For the definitions of convergent, completeness, closedness and some theorems by regarding these concepts in such spaces, one can see [7]. In 2004, Ran and Reurings [11] discussed on fixed point results for comparable elements of a metric space  $(\mathcal{X}, d)$  provided with a partial order. Then, Bhaskar and Lakshmikantham [12] presented several fixed point results for a mapping having mixed monotone property in such spaces (see [13,14]).

**Definition 4** ([12]). Consider a ordered set  $(\mathcal{X}, \preceq)$  and a mapping  $F : \mathcal{X}^2 \rightarrow \mathcal{X}$ . The mapping  $F$  is told to be have mixed monotone property if

$$\begin{aligned} x_1 \preceq x_2 \text{ implies that } F(x_1, y) \preceq F(x_2, y) & \quad \forall x_1, x_2 \in \mathcal{X}, \\ y_1 \preceq y_2 \text{ implies that } F(x, y_1) \succeq F(x, y_2) & \quad \forall y_1, y_2 \in \mathcal{X}. \end{aligned}$$

for every  $x, y \in \mathcal{X}$ .

Here we introduce an  $e$ -distance on Menger PGM spaces and some of its properties. Then we obtain some coupled fixed point results in the quasi-ordered version of such spaces. The subject of the paper offers novelties compared to the related background literature since a new distance in Menger spaces is defined while some of its properties are revisited and extended.

## 2. Main Results

Here, we consider an  $e$ -distance on a Menger PGM space, which is an extension of  $r$ -distance introduced by Saadati et al. [4].

**Definition 5.** Consider a Menger PGM space  $(\mathcal{X}, G, \mathcal{T})$ . Then the function  $g : \mathcal{X}^3 \times [0, \infty] \rightarrow [0, 1]$  is called an  $e$ -distance, if for all  $x, y, z, a \in \mathcal{X}$  and  $s, t \geq 0$  the following are held:

- (r1)  $g_{x,y,z}(t+s) \geq \mathcal{T}(g_{x,a,a}(s), g_{a,y,z}(t))$ ;
- (r2)  $g_{x,y,\cdot}(t)$  and  $g_{x,\cdot,y}(t)$  are continuous;
- (r3) for each  $\epsilon > 0$ , there exists  $\delta > 0$  provided that  $g_{a,y,z}(t) \geq 1 - \delta$  and  $g_{x,a,a}(s) \geq 1 - \delta$  conclude that  $G_{x,y,z}(t+s) \geq 1 - \epsilon$ .

**Lemma 1.** Each Menger PGM is an  $e$ -distance on  $\mathcal{X}$ .

**Proof.** Clearly, (r1) and (r2) are true. Only, we prove that (r3) is true. Assume  $\epsilon > 0$  and select  $\delta > 0$  so that  $\mathcal{T}(1 - \delta, 1 - \delta) \geq 1 - \epsilon$ . Then, for  $G_{a,y,z}(t) \geq 1 - \delta$  and  $G_{x,a,a}(s) \geq 1 - \delta$ , we get

$$G_{x,y,z}(t+s) \geq \mathcal{T}(G_{a,y,z}(t), G_{x,a,a}(s)) \geq \mathcal{T}(1 - \delta, 1 - \delta) \geq 1 - \epsilon.$$

□

**Example 1.** Assume  $(\mathcal{X}, G, \mathcal{T})$  is a Menger PGM space. Define a function  $g : \mathcal{X}^3 \times [0, \infty] \rightarrow [0, 1]$  by  $g_{x,y,z}(t) = 1 - c$  for each  $x, y, z \in \mathcal{X}$  and  $t > 0$  with  $c \in (0, 1)$ . Then  $g$  is an  $e$ -distance.

**Lemma 2.** Consider a Menger PGM space with a continuous mapping  $A$  on  $\mathcal{X}$  and a function  $g : \mathcal{X}^3 \times [0, \infty] \rightarrow [0, 1]$  by  $g_{x,y,z}(t) = \min\{G_{x,y,z}(t), G_{Ax,Ay,Az}(t)\}$  for each  $x, y, z \in \mathcal{X}$  and  $t > 0$ . Then  $g$  is an  $e$ -distance on  $\mathcal{X}$ .

**Proof.** The condition (r2) is clearly established. To prove (r1), consider  $x, y, z, a \in \mathcal{X}$  and  $t, s > 0$ . Then, we have two following cases:

**Case 1:** if  $G_{x,y,z}(t) = \min\{G_{x,y,z}(t), G_{Ax,Ay,Az}(t)\}$ , then

$$\begin{aligned} g_{x,y,z}(t+s) &= G_{x,y,z}(t+s) \\ &\geq \mathcal{T}(G_{x,a,a}(t), G_{a,y,z}(s)) \\ &\geq \mathcal{T}(\min\{G_{x,a,a}(t), G_{Ax,Aa,Aa}(t)\}, \min\{G_{a,y,z}(s), G_{Aa,Ay,Az}(s)\}) \\ &\geq \mathcal{T}(g_{x,a,a}(t), g_{a,y,z}(s)). \end{aligned}$$

**Case 2:** if  $G_{Ax,Ay,Az}(t) = \min\{G_{x,y,z}(t), G_{Ax,Ay,Az}(t)\}$ , then

$$\begin{aligned} g_{x,y,z}(t+s) &= G_{Ax,Ay,Az}(t+s) \\ &\geq \mathcal{T}(G_{Ax,Aa,Aa}(t), G_{Aa,Ay,Az}(s)) \\ &\geq \mathcal{T}(\min\{G_{x,a,a}(t), G_{Ax,Aa,Aa}(t)\}, \min\{G_{a,y,z}(s), G_{Aa,Ay,Az}(s)\}) \\ &\geq \mathcal{T}(g_{x,a,a}(t), g_{a,y,z}(s)). \end{aligned}$$

Therefore, (r1) is established. Now, assume  $\epsilon > 0$  and select  $\delta > 0$  so that  $\mathcal{T}(1 - \delta, 1 - \delta) \geq 1 - \epsilon$ . Using  $g_{x,a,a}(t) \geq 1 - \delta$  and  $g_{a,y,z}(s) \geq 1 - \delta$ , we get

$$\begin{aligned} \min\{G_{x,a,a}(t), G_{Ax,Aa,Aa}(t)\} &= g_{x,a,a}(t) \geq 1 - \delta, \\ \min\{G_{a,y,z}(s), G_{Aa,Ay,Az}(s)\} &= g_{a,y,z}(s) \geq 1 - \delta, \end{aligned}$$

which induces that

$$\begin{aligned} G_{x,y,z}(t+s) &\geq \mathcal{T}(G_{x,a,a}(t), G_{a,y,z}(s)) \\ &\geq \mathcal{T}(\min\{G_{x,a,a}(t), G_{Ax,Aa,Aa}(t)\}, \min\{G_{a,y,z}(s), G_{Aa,Ay,Az}(s)\}) \\ &= \mathcal{T}(g_{x,a,a}(t), g_{a,y,z}(s)) \geq \mathcal{T}(1 - \delta, 1 - \delta) \geq 1 - \epsilon. \end{aligned}$$

Thus, (r3) is established. This completes the proof.  $\square$

**Lemma 3.** Consider an  $e$ -distance  $g$  on  $(\mathcal{X}, G, \mathcal{T})$  with two sequences  $\{x_n\}$  and  $\{y_n\}$  in  $\mathcal{X}$ . Suppose that  $\{\alpha_n\}$  and  $\{\beta_n\}$  are two non-negative sequences converging to 0. Then for  $x, y, z \in \mathcal{X}$  and  $t, s > 0$  the following assertions are established:

- (i)  $g_{z,y,x_n}(t) \geq 1 - \alpha_n$  and  $g_{x,x_n,x_n}(t) \geq 1 - \beta_n$  for any  $n \in \mathbb{N}$  imply  $x = y = z$ . Specially,  $g_{x,a,a}(t) = 1$  and  $g_{a,y,z}(s) = 1$  imply  $x = y = z$ ;
- (ii)  $g_{y_n,x_n,x_n}(t) \geq 1 - \alpha_n$  and  $g_{x_n,y_m,z}(t) \geq 1 - \beta_n$  for all  $m > n$  with  $m, n \in \mathbb{N}$  imply  $G_{y_n,y_m,z}(t+s) \rightarrow 1$  as  $n \rightarrow \infty$ ;
- (iii) let  $g_{x_n,x_m,x_l}(t) \geq 1 - \alpha_n$  for all  $n, m, l \in \mathbb{N}$ , where  $l > m > n$ . Then  $\{x_n\}$  is a Cauchy sequence;
- (iv) let  $g_{y,y,x_l}(t) \geq 1 - \alpha_n$  for all  $n \in \mathbb{N}$ . Then  $\{x_n\}$  is a Cauchy sequence.

**Proof.** To prove (ii), assume  $\epsilon > 0$ . By applying the definition of  $e$ -distance, there exists  $\delta > 0$  so that  $g_{a,y,z}(t) \geq 1 - \delta$  and  $g_{x,a,a}(s) \geq 1 - \delta$  induce  $G_{x,y,z}(t+s) \geq 1 - \epsilon$ . Select  $n_0 \in \mathbb{N}$  provided that  $\alpha_n \leq \delta$  and  $\beta_n \leq \delta$  for each  $n \geq n_0$ . Then  $g_{y_n,x_n,x_n}(t) \geq 1 - \alpha_n \geq 1 - \delta$  and  $g_{x_n,y_m,z}(t) \geq 1 - \beta_n \geq 1 - \delta$  for any  $n \geq n_0$  and hence  $G_{y_n,y_m,z}(t+s) \geq 1 - \epsilon$ . Therefore,  $\{y_n\}$  converges to  $z$ . Now, using (ii), (i) is established. To prove (iii), assume  $\epsilon > 0$ . Similar to the proof of (ii), select  $\delta > 0$  and  $n_0 \in \mathbb{N}$ . Then, for all  $n, m, l \geq n_0 + 1$ , we get  $g_{x_n,x_{n_0},x_{n_0}}(t) \geq 1 - \alpha_{n_0} \geq 1 - \delta$  and  $g_{x_{n_0},x_l,x_m}(t) \geq 1 - \alpha_{n_0} \geq 1 - \delta$ . Therefore,  $G_{x_n,x_m,x_l}(t) \geq 1 - \epsilon$ . Hence,  $\{x_n\}$  is a Cauchy sequence. Now, it follows from (iii) that (iv) is true.  $\square$

**Lemma 4.** Consider an  $e$ -distance  $g$  on  $(\mathcal{X}, G, \mathcal{T})$ . Suppose that  $E_{\lambda,g} : \mathcal{X}^3 \rightarrow \mathbb{R}^+ \cup \{0\}$  is introduced by  $E_{\lambda,g}(x, y, z) = \inf\{t > 0 : g_{x,y,z}(t) > 1 - \lambda\}$  for any  $x, y, z \in \mathcal{X}$  and  $\lambda \in (0, 1)$ . Then

(1) for all  $\mu \in (0, 1)$ , there exists  $\lambda \in (0, 1)$  so that

$$E_{\mu,g}(x_1, x_1, x_n) \leq E_{\lambda,g}(x_1, x_1, x_2) + E_{\lambda,g}(x_2, x_2, x_3) + \dots + E_{\lambda,g}(x_{n-1}, x_{n-1}, x_n)$$

for each  $x_1, \dots, x_n \in \mathcal{X}$ ;

(2) for every sequence  $\{x_n\}$  in  $\mathcal{X}$ ,  $g_{x_n, x, x}(t) \rightarrow 1$  iff  $E_{\lambda,g}(x_n, x, x) \rightarrow 0$ . Further, the sequence  $\{x_n\}$  is Cauchy w.r.t.  $g$  iff it is Cauchy with  $E_{\lambda,g}$ .

**Proof.**

(1) For every  $\mu \in (0, 1)$ , we can gain  $\lambda \in (0, 1)$  provided that  $\mathcal{T}^{n-1}(1 - \lambda, \dots, 1 - \lambda) \geq 1 - \mu$ . Now, for every  $\delta > 0$ , we have

$$\begin{aligned} &g_{x_1, x_1, x_n}(E_{\lambda,g}(x_1, x_1, x_2) + E_{\lambda,g}(x_2, x_2, x_3) + \dots + E_{\lambda,g}(x_{n-1}, x_{n-1}, x_n) + n\delta) \\ &\geq \mathcal{T}^{n-1}(g_{x_1, x_1, x_2}(E_{\lambda,g}(x_1, x_1, x_2) + \delta), g_{x_2, x_2, x_3}(E_{\lambda,g}(x_2, x_2, x_3) + \delta) \\ &\quad, \dots, g_{x_{n-1}, x_{n-1}, x_n}(E_{\lambda,g}(x_{n-1}, x_{n-1}, x_n) + \delta)) \\ &\geq \mathcal{T}^{n-1}(1 - \lambda, \dots, 1 - \lambda) \geq 1 - \mu \end{aligned}$$

which induces that

$$E_{\mu,g}(x_1, x_1, x_n) \leq E_{\lambda,g}(x_1, x_1, x_2) + E_{\lambda,g}(x_2, x_2, x_3) + \dots + E_{\lambda,g}(x_{n-1}, x_{n-1}, x_n) + n\delta.$$

Since  $\delta > 0$  is optional, we obtain

$$E_{\mu,g}(x_1, x_1, x_n) \leq E_{\lambda,g}(x_1, x_1, x_2) + E_{\lambda,g}(x_2, x_2, x_3) + \dots + E_{\lambda,g}(x_{n-1}, x_{n-1}, x_n).$$

(2) Note that  $g_{x_n, x, x}(\eta) \rightarrow 1 - \lambda$  as  $n \rightarrow \infty$  iff  $E_{\lambda,g}(x_n, x, x) < \eta$  for each  $n \in \mathbb{N}$  and  $\eta > 0$ .  $\square$

In the sequel, we establish some coupled fixed point theorems by regarding an  $e$ -distance on a quasi-ordered complete PGM space.

**Theorem 1.** Let  $(\mathcal{X}, G, \mathcal{T}, \preceq)$  be a quasi-ordered complete Menger PGM space with  $\mathcal{T}$  of Hadzić-type I,  $g$  be an  $e$ -distance and  $f : \mathcal{X}^2 \rightarrow \mathcal{X}$  be a mapping having the mixed monotone property on  $\mathcal{X}$ . Assume that there exists a  $k \in [0, 1)$  such that

$$g_{f(x,y), f(u,v), f(w,z)}(t) \geq \frac{1}{2}(g_{x,u,w}(\frac{t}{k}) + g_{y,v,z}(\frac{t}{k})) \tag{1}$$

for all  $x, y, z, u, v, w \in \mathcal{X}$  with  $x \succeq u \succeq w$  and  $y \preceq v \preceq z$ , where either  $u \neq w$  or  $v \neq z$  and

$$\sup\{\mathcal{T}(g_{x,y,z}(t), g_{x,y,f(x,y)}(t)) : x, y \in \mathcal{X}\} < 1. \tag{2}$$

for all  $z \in \mathcal{X}$ , where  $z \neq f(z, q)$  for all  $q \in \mathcal{X}$ . If there exist  $x_0, y_0 \in \mathcal{X}$  so that  $x_0 \preceq f(x_0, y_0)$  and  $y_0 \succeq f(y_0, x_0)$ , then  $f$  have a coupled fixed point in  $\mathcal{X}^2$ .

**Proof.** Since there exist  $x_0, y_0 \in \mathcal{X}$  with  $x_0 \preceq f(x_0, y_0)$  and  $y_0 \succeq f(y_0, x_0)$ , and  $f$  has the mixed monotone property, we can construct Bhaskar-Lakshmikantham type iterative as follow:

$$x_0 \preceq x_1 \preceq x_2 \preceq \dots \preceq x_{n+1} \preceq \dots, \quad y_0 \succeq y_1 \succeq y_2 \succeq \dots \succeq y_{n+1} \succeq \dots$$

for all  $n \geq 0$ , where

$$\begin{aligned} x_{n+1} &= f^{n+1}(x_0, y_0) = f(f^n(x_0, y_0), f^n(y_0, x_0)), \\ y_{n+1} &= f^{n+1}(y_0, x_0) = f(f^n(y_0, x_0), f^n(x_0, y_0)). \end{aligned}$$

If  $(x_{n+1}, y_{n+1}) = (x_n, y_n)$ , then  $f$  has a coupled fixed point. Otherwise, assume  $(x_{n+1}, y_{n+1}) \neq (x_n, y_n)$  for each  $n \geq 0$ ; that is, either  $x_{n+1} = f(x_n, y_n) \neq x_n$  or  $y_{n+1} = f(y_n, x_n) \neq y_n$ . Now, by induction and (1), we obtain

$$g_{x_n, x_n, x_{n+1}}(t) \geq \frac{1}{2} \left( g_{x_0, x_0, x_1} \left( \frac{t}{k^n} \right) + g_{y_0, y_0, y_1} \left( \frac{t}{k^n} \right) \right),$$

$$g_{y_n, y_n, y_{n+1}}(t) \geq \frac{1}{2} \left( g_{y_0, y_0, y_1} \left( \frac{t}{k^n} \right) + g_{x_0, x_0, x_1} \left( \frac{t}{k^n} \right) \right),$$

for each  $n \geq 0$  which induces that  $g_{x_n, x_n, x_{n+1}}(t) \geq \frac{1}{2} g_{x_0, x_0, x_1} \left( \frac{t}{k^n} \right)$  and  $g_{y_n, y_n, y_{n+1}}(t) \geq \frac{1}{2} g_{y_0, y_0, y_1} \left( \frac{t}{k^n} \right)$ . Therefore,

$$\begin{aligned} E_{\lambda, g}(x_n, x_n, x_{n+1}) &= \inf \{ t > 0 : g_{x_n, x_n, x_{n+1}}(t) > 1 - \lambda \} \\ &\leq \inf \{ t > 0 : \frac{1}{2} g_{x_0, x_0, x_1} \left( \frac{t}{k^n} \right) > 1 - \lambda \} \\ &= 2k^n E_{\lambda, g}(x_0, x_0, x_1). \end{aligned}$$

Thus, for  $m > n$  and  $\lambda \in (0, 1)$ , there exists  $\gamma \in (0, 1)$  so that

$$E_{\lambda, g}(x_n, x_n, x_m) \leq E_{\gamma, g}(x_n, x_n, x_{n+1}) + \dots + E_{\gamma, g}(x_{m-1}, x_{m-1}, x_m) \leq \frac{2k^n}{1-k} E_{\gamma, g}(x_0, x_0, x_1).$$

Now, there exists  $n_0 \in \mathbb{N}$  so that for each  $n > n_0$ ,  $E_{\lambda, g}(x_n, x_n, x_m) \rightarrow 0$ . By Lemmas 3 and 4,  $\{x_n\}$  is a Cauchy sequence. Thus, using Lemma 4 (ii), there exist  $n_1 \in \mathbb{N}$  and a sequence  $\delta_n \rightarrow 0$  so that  $g_{x_n, x_n, x_m}(t) \geq 1 - \delta_n$  for  $n \geq \max\{n_0, n_1\}$ . Since  $\mathcal{X}$  is complete,  $\{x_n\}$  converges to a point  $p \in \mathcal{X}$ . Similarly,  $\{y_n\}$  is convergent to a point  $q \in \mathcal{X}$ . By (r2), we obtain  $g_{x_n, x_n, p}(t) = \lim_{m \rightarrow \infty} g_{x_n, x_n, x_m}(t) \geq 1 - \delta_n$  for  $n \geq \max\{n_0, n_1\}$ . Moreover, we get  $g_{x_n, x_{n+1}, x_{n+1}}(t) \geq 1 - \delta_n$ . Now, we show that  $f$  has a coupled fixed point. Let  $p \neq f(p, q)$ . Then, by (2), we obtain

$$\begin{aligned} 1 &> \sup \{ \mathcal{T}(g_{x, y, p}(t), g_{x, y, f(x, y)}(t)) : x, y \in \mathcal{X} \} \\ &\geq \sup \{ \mathcal{T}(g_{x_n, x_n, p}(t), g_{x_n, x_{n+1}, x_{n+1}}(t)) : n \in \mathbb{N} \} \\ &\geq \sup \{ \mathcal{T}(1 - \delta_n, 1 - \delta_n) : n \in \mathbb{N} \} = 1, \end{aligned}$$

which is a contradiction. Consequently, we get  $p = f(p, q)$ . Similarly, we obtain  $f(q, p) = q$ . Here, the proof ends.  $\square$

**Theorem 2.** Assume the assumptions of Theorem 1 are held and consider the continuity of  $f$  instead of relation (2). Then  $f$  has a coupled fixed point.

**Proof.** As in the proof of Theorem 1, construct  $\{x_n\}$  and  $\{y_n\}$ , where  $x_n \rightarrow p, y_n \rightarrow q, x_{n+1} = f(x_n, y_n)$ . Now, by the continuity of  $f$  and by taking the limit as  $n \rightarrow \infty$ , we get  $f(p, q) = p$ . Analogously, we can obtain  $f(q, p) = q$ . Therefore,  $(p, q)$  is a coupled fixed point of  $f$ .  $\square$

**Example 2.** Assume that  $\mathcal{X} = [0, \infty)$ , " $\preceq$ " is a quasi-ordered on  $\mathcal{X}$  and  $\mathcal{T}(a, b) = \min\{a, b\}$ . Define a constant function  $f : \mathcal{X}^2 \rightarrow \mathcal{X}$  by  $f(a, b) = p$  and  $G : \mathcal{X}^3 \rightarrow D^+$  by  $G_{x, y, z}(t) = \frac{t}{t + G^*(x, y, z)}$  with  $G^*(x, y, z) = |x - y| + |x - z| + |y - z|$  for each  $x, y, z \in \mathcal{X}$ . Clearly,  $G$  satisfies (PG1)-(PG4). Consider  $g_{x, y, z}(t) = 1 - c$ , where  $c \in (0, 1)$ . Then  $g$  is an  $e$ -distance on  $\mathcal{X}$ . Clearly, for all  $x, y, z, u, v, w \in \mathcal{X}$  and for any  $t > 0$ , we have  $g_{f(x, y), f(u, v), f(w, z)}(t) \geq \frac{1}{2} (g_{x, u, w}(\frac{t}{k}) + g_{y, v, z}(\frac{t}{k}))$ . Moreover, there exist  $x_0 = 0$  and  $y_0 = 1$  so that  $0 = x_0 \preceq f(x_0, y_0)$  and  $1 = y_0 \succeq f(y_0, x_0) = 1$ . Therefore, all of the hypothesis of Theorem 2 are held. Clearly,  $(p, p)$  is a coupled fixed point the function  $f$ .

### 3. Application

Consider the following system of integral equations:

$$\begin{cases} x(t) = \int_a^b M(t,s)K(s,x(s),y(s))ds, \\ y(t) = \int_a^b M(t,s)K(s,y(s),x(s))ds, \end{cases} \tag{3}$$

for all  $t \in I = [a, b]$ , where  $b > a$ ,  $M \in C(I \times I, [0, \infty))$  and  $K \in C(I \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ .

Let  $C(I, \mathbb{R})$  be the Banach space of every real continuous functions on  $I$  with  $\|x\|_\infty = \max_{t \in I} |x(t)|$  for all  $x \in C(I, \mathbb{R})$  and  $C(I \times I \times C(I, \mathbb{R}), \mathbb{R})$  be the space of every continuous functions on  $I \times I \times C(I, \mathbb{R})$ . Define a mapping  $G : C(I, \mathbb{R}) \times C(I, \mathbb{R}) \rightarrow D^+$  by  $G_{x,y,z}(t) = \chi(\frac{t}{2} - (\|x - y\|_\infty + \|x - z\|_\infty + \|y - z\|_\infty))$  for all  $x, y, z \in C(I, \mathbb{R})$  and  $t > 0$ , where

$$\chi(t) = \begin{cases} 0 & \text{if } t \leq 0 \\ 1 & \text{if } t > 0 \end{cases}$$

Then,  $(C(I, \mathbb{R}), G, \mathcal{T})$  with  $\mathcal{T}(a, b) = \min\{a, b\}$  is a complete Menger PGM space ([7]). Consider an  $e$ -distance on  $\mathcal{X}$  by  $g_{x,y,z}(t) = \min\{G_{x,y,z}(t), G_{Ax,Ay,Az}(t)\}$ , where  $A : C(I, \mathbb{R}) \rightarrow C(I, \mathbb{R})$  and  $Ax = \frac{x}{2}$ . Moreover, we define the relation " $\preceq$ " on  $C(I, \mathbb{R})$  by  $x \preceq y \Leftrightarrow \|x\|_\infty \leq \|y\|_\infty$  for all  $x, y \in C(I, \mathbb{R})$ . Clearly the relation " $\preceq$ " is a quasi-order relation on  $C(I, \mathbb{R})$  and  $(C(I, \mathbb{R}), G, \mathcal{T}, \preceq)$  is a quasi-ordered complete PGM space.

**Theorem 3.** Let  $(C(I, \mathbb{R}), G, \mathcal{T}, \preceq)$  be a quasi-ordered complete Menger PGM space and  $f : C(I, \mathbb{R}) \times C(I, \mathbb{R}) \rightarrow C(I, \mathbb{R})$  be a operator defined by  $f(x, y)(t) = \int_a^b M(t,s)K(s,x(s),y(s))ds$ , where  $M \in C(I \times I, [0, \infty))$  and  $K \in C(I \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$  are two operators. Assume the following properties are held:

- (i)  $\|K\|_\infty = \sup_{s \in I, x, y \in C(I, \mathbb{R})} |K(s, x(s), y(s))| < \infty$ ;
- (ii) for every  $x, y \in C(I, \mathbb{R})$  and every  $t, s \in I$ , we have

$$\|K(s, x(s), y(s)) - K(s, u(s), v(s))\|_\infty \leq \frac{1}{4}(\max |x(s) - u(s)| + \max |y(s) - v(s)|);$$

- (iii)  $\max_{t \in I} \int_a^b M(t,s)ds < 1$ .

Then, the system (3) have a solution in  $C(I, \mathbb{R}) \times C(I, \mathbb{R})$ .

**Proof.** For all  $x, y \in C(I, \mathbb{R})$ , let  $\|x - y\|_\infty = \max_{t \in I} (|x(t) - y(t)|)$ . Then, for all  $x, y, z, u, v, w \in C(I, \mathbb{R})$ , we have

$$\begin{aligned} \|f(x, y) - f(u, v)\|_\infty &\leq \max_{t \in I} \int_a^b M(t,s) |K(s, x(s), y(s)) - K(s, u(s), v(s))| ds \\ &\leq \max(\frac{1}{4}(\|x - u\|_\infty + \|y - v\|_\infty)) \max_{t \in I} \int_a^b M(t,s) ds \\ &\leq \max(\frac{1}{4}(\|x - u\|_\infty + \|y - v\|_\infty)). \end{aligned}$$

We consider two following cases:

**Case 1.** Let

$$\begin{aligned} g_{f(x,y), f(u,v), f(w,z)}(t) &= \min\{G_{f(x,y), f(u,v), f(w,z)}(t), G_{Af(x,y), Af(u,v), Af(w,z)}(t)\} \\ &= G_{f(x,y), f(u,v), f(w,z)}(t). \end{aligned}$$

Then, we obtain

$$\begin{aligned}
 \mathcal{G}_{f(x,y),f(u,v),f(w,z)}(t) &= G_{f(x,y),f(u,v),f(w,z)}(t) \\
 &= \chi\left(\frac{t}{2} - (\|f(x,y) - f(u,v)\|_\infty + \|f(x,y) - f(w,z)\|_\infty + \|f(u,v) - f(w,z)\|_\infty)\right) \\
 &\geq \chi\left(\frac{t}{2} - \left(\max\left(\frac{1}{4}(|x(s) - u(s)| + |y(s) - v(s)|)\right)\right.\right. \\
 &\quad \left.\left. + \max\left(\frac{1}{4}(|x(s) - w(s)| + |y(s) - z(s)|)\right)\right.\right. \\
 &\quad \left.\left. + \max\left(\frac{1}{4}(|u(s) - w(s)| + |v(s) - z(s)|)\right)\right)\right) \\
 &= \chi\left(t - \frac{1}{2}(\max(|x(s) - u(s)| + |y(s) - v(s)|)\right.\right. \\
 &\quad \left.\left. + \max(|x(s) - w(s)| + |y(s) - z(s)|) + \max(|u(s) - w(s)| + |v(s) - z(s)|))\right) \\
 &\geq \frac{1}{2}(\chi(t - (\max(|x(s) - u(s)| + |x(s) - w(s)| + |u(s) - w(s)|))) \\
 &\quad + \chi(t - (\max(|y(s) - v(s)| + |y(s) - z(s)| + |v(s) - z(s)|)))) \\
 &= \frac{1}{2}(G_{x,u,w}(2t) + G_{y,v,z}(2t)) \geq \frac{1}{2}(g_{x,u,w}(2t) + g_{y,v,z}(2t)).
 \end{aligned}$$

Case 2. Let

$$\begin{aligned}
 \mathcal{G}_{f(x,y),f(u,v),f(w,z)}(t) &= \min\{G_{f(x,y),f(u,v),f(w,z)}(t), G_{Af(x,y),Af(u,v),Af(w,z)}(t)\} \\
 &= G_{Af(x,y),Af(u,v),Af(w,z)}(t).
 \end{aligned}$$

By  $Ax = \frac{x}{2}$ , we have

$$\begin{aligned}
 \mathcal{G}_{f(x,y),f(u,v),f(w,z)}(t) &= G_{Af(x,y),Af(u,v),Af(w,z)}(t) \\
 &= \chi\left(\frac{t}{2} - \frac{1}{2}(\|f(x,y) - f(u,v)\|_\infty + \|f(x,y) - f(w,z)\|_\infty + \|f(u,v) - f(w,z)\|_\infty)\right) \\
 &\geq \chi\left(\frac{t}{2} - (\|f(x,y) - f(u,v)\|_\infty + \|f(x,y) - f(w,z)\|_\infty + \|f(u,v) - f(w,z)\|_\infty)\right) \\
 &\geq \chi\left(\frac{t}{2} - \left(\max\left(\frac{1}{4}(|x(s) - u(s)| + |y(s) - v(s)|)\right)\right.\right. \\
 &\quad \left.\left. + \max\left(\frac{1}{4}(|x(s) - w(s)| + |y(s) - z(s)|)\right)\right.\right. \\
 &\quad \left.\left. + \max\left(\frac{1}{4}(|u(s) - w(s)| + |v(s) - z(s)|)\right)\right)\right) \\
 &= \chi\left(t - \frac{1}{2}(\max(|x(s) - u(s)| + |y(s) - v(s)|)\right.\right. \\
 &\quad \left.\left. + \max(|x(s) - w(s)| + |y(s) - z(s)|) + \max(|u(s) - w(s)| + |v(s) - z(s)|))\right) \\
 &\geq \frac{1}{2}(\chi(t - (\max(|x(s) - u(s)| + |x(s) - w(s)| + |u(s) - w(s)|))) \\
 &\quad + \chi(t - (\max(|y(s) - v(s)| + |y(s) - z(s)| + |v(s) - z(s)|)))) \\
 &= \frac{1}{2}(G_{x,u,w}(2t) + G_{y,v,z}(2t)) \geq \frac{1}{2}(g_{x,u,w}(2t) + g_{y,v,z}(2t))
 \end{aligned}$$

for all  $x, y, z, u, v, w \in C(I, \mathbb{R})$ . Therefore, by Theorem 2 with  $k = \frac{1}{2}$  for all  $x, y, z, u, v, w \in C(I, \mathbb{R})$  and  $t > 0$ , we deduce that the operator  $f$  has a coupled fixed point which is the solution of the system of the integral equations.  $\square$

#### 4. Conclusions

The new concept of  $e$ -distance, which is a generalization of  $r$ -distance in PGM space has been introduced. Moreover, some of properties of  $e$ -distance have been discussed. In addition, we obtained several new coupled fixed point results. Ultimately, to illustrate the

usability of the main theorem, the existence of a solution for a system of integral equations is proved.

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