



Review Silicon Integrated Nanophotonic Devices for On-Chip Multi-Mode Interconnects

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Abstract: Mode-division multiplexing (MDM) technology has drawn tremendous attention for its ability to expand the link capacity within a single-wavelength carrier, paving the way for large-scale on-chip data communications. In the MDM system, the signals are carried by a series of higher-order modes in a multi-mode bus waveguide. Hence, it is essential to develop on-chip mode-handling devices. Silicon-on-insulator (SOI) has been considered as a promising platform to realize MDM since it provides an ultra-high-index contrast and mature fabrication processes. In this paper, we review the recent progresses on silicon integrated nanophotonic devices for MDM applications. We firstly discuss the working principles and device configurations of mode (de)multiplexers. In the second section, we summarize the multi-mode routing devices, including multi-mode bends, multi-mode crossings and multi-mode splitters. The inverse-designed multi-mode devices are then discussed in the third section. We also provide a discussion about the emerging reconfigurable MDM devices in the fourth section. Finally, we offer our outlook of the development prospects for on-chip multi-mode photonics.

Keywords: integrated photonics; silicon photonics; mode-division multiplexing

1. Introduction

The modern micro-processors require an extremely large link capacity for data communications between multi-cores and local/distant caches [1]. However, it is becoming increasingly difficult to meet the ever-growing capacity requirement since the conventional electrical interconnects severely suffer from limited bandwidth and significant power consumption [2]. The on-chip optical-interconnect technology emerges as an attractive approach to break the bottleneck [2–4], taking advantage of its ultra-large bandwidth and ultra-low power consumption. Moreover, the link capacity can be further enhanced for the optical interconnects by utilizing novel multiplexing technologies, including wavelength-division multiplexing (WDM) [5–9], polarization-division multiplexing (PDM) [10] and mode-division multiplexing (MDM) [11–13]. WDM technology has been widely used in optical communication systems. For WDM, different signals are carried by different wavelengths, so WDMs always require a large number of laser diodes (LDs) each with an accurate temperature monitor, leading to complicated and expensive systems [11]. Therefore, it is necessary to expand the link capacity within a single-wavelength carrier by utilizing the cost-effective PDM and MDM technologies. Note that polarizations can only contribute two degrees of freedom, i.e., transverse electric (TE) and transverse magnetic (TM), so the PDM technology can only double the link capacity [10]. In contrast, the MDM system is much more scalable since the total mode capacity can be easily expanded by choosing a relatively wide multi-mode bus waveguide, showing enormous potential for achieving large-scale on-chip optical interconnects with great scalability.

In recent years, silicon-on-insulator (SOI) has been regarded as a promising platform to develop multi-mode photonics for its ultra-high-index contrast ($n_{Si} \approx 3.46$, $n_{SiO2} \approx 1.45$) and mature fabrication processes compatible with complementary metal oxide semiconductors (CMOS) [14–22]. Figure 1a shows the calculated effective indices for the higher-order modes in a SOI waveguide with varied core width (w_{wg}). Here, the waveguide thickness is chosen to be $h_{wg} = 220$ nm and the cladding material is chosen to be SiO2. Figure 1b shows the calculated mode profiles for the first four TE/TM modes with $w_{wg} = 2 \mu m$. From Figure 1a,b, one can observe the strong waveguide birefringence and mode dispersion, which makes it possible to realize selective mode handling without introducing much inter-modal crosstalk. Figure 1c shows the configuration for a typical MDM system (four channels with TE_{0-3} modes are considered here as an example). The fundamental TE mode (i.e., TE_0) from a single LD is firstly divided to four waveguide channels by power splitters. The waveguide channels are then independently modulated and converted/multiplexed to the higher-order modes (i.e., TE_{0-3}) in the multi-mode bus waveguide by using the mode multiplexer. At the receiver terminal, TE_{0-3} modes are reverted to TE₀ mode in different waveguide channels by the mode demultiplexer and received by the photodetectors (PDs). It can be seen from the configuration that the higher-order modes only exist in the multi-mode bus waveguide, while the other components (e.g., LDs, modulators and PDs) all work under the fundamental mode. Therefore, the basic MDM components could be classified into two categories:

- 1. The mode (de)multiplexers for interfacing single-mode input/output waveguides and multi-mode bus waveguide.
- 2. The multi-mode routing devices (e.g., bend, crossing and splitter) for transferring higher-order modes in the multi-mode bus waveguide.



Figure 1. (a) The calculated effective indices for the higher-order modes in a silicon-on-insulator (SOI) waveguide with varied waveguide width (w_{wg}). The inset shows the cross-section of a multi-mode SOI waveguide with some key parameters labeled. (b) The calculated field profiles for the first four transverse electric (TE) and transverse magnetic (TM) modes. (c) The configuration for a typical four-channel mode-division multiplexing (MDM) system.

Complex MDM systems can be built by simply combining these two kinds of basic MDM components with other conventional single-mode components.

In this paper, we review the recent progress on silicon integrated nanophotonic devices for on-chip multi-mode interconnects. In Section 2, we begin by reviewing silicon multi-dimensional (de)multiplexers, including silicon mode multiplexers in Section 2.1, silicon hybrid multiplexers in Section 2.2, and densely packed waveguide arrays in Section 2.3. In Section 3, we give a review on silicon multi-mode routing devices, including silicon multi-mode bends in Section 3.1, silicon multi-mode crossings in Section 3.2, and silicon multi-mode splitters in Section 3.3. In Section 4, we turn to the discussion of inverse-designed multi-mode devices. In Section 5, we give a review on reconfigurable MDM devices. In Section 6, we offer our outlook of the development prospects for silicon multi-mode photonics. Figure 2 illustrates the main topics that will be discussed in the following sections.



Figure 2. A table of contents: the main topics that will be discussed in the following sections.

2. Silicon Multi-Dimensional (De)Multiplexers

The mode (de)multiplexer is one of the most important elements in the MDM system, which is used to realize mode conversion and combine/separate signals carried by different modes. Over the recent years, various mode (de)multiplexers have been proposed and demonstrated on the SOI platform, which will be reviewed in Section 2.1. The link capacity can be further enhanced for multi-mode data communications by introducing some other dimensions, such as wavelengths and polarizations. The hybrid (de)multiplexer enables the simultaneous combination/separation of signals carried by multiple degrees of freedom, which is crucial in WDM/PDM/MDM hybrid systems. A review on silicon hybrid (de)multiplexers will be given in Section 2.2. The mode capacity can also be improved by employing spatially separated super-modes in the densely packed waveguide array (DPWA). Silicon–DPWA-based mode (de)multiplexers will be reviewed in Section 2.3.

2.1. Silicon Mode (De)Multiplexers

The mode (de)multiplexer enables mode conversion and signal (de)multiplexing. Such functionalities can be achieved by various different structures, e.g., multimode interference couplers (MMIs) [23–28], asymmetric Y-junctions [29–31] and asymmetric directional couplers (ADCs) [32–45], as summarized in Figure 3.



Figure 3. The schematics for the silicon few-mode (de)multiplexers based on (a) multimode interference couplers (MMI) [24], (b) asymmetric Y-junction [29] and (c) asymmetric directional coupler (ADC) [36].

The MMI is formed by an interference section and several input/output waveguides [46–55]. The multi-mode interference can be excited by the incident light from the input port, leading to a series

of self-images in the interference section [46]. The phase and modal distributions of the output field can be tailored at each output port by appropriately choosing the MMI length/width [56–59]. For example, the input even and odd modes can be separated into different output ports when the MMI length is set to $L_{MMI} = 3L_{\pi}/4$. In this way, the MMI can serve as a mode sorter [23]. Here, L_{π} can be derived as [46]:

$$L_{\pi} = \lambda / [2 \cdot (n_{\text{eff},0} - n_{\text{eff},1})] \approx 4 n_{\text{s}} W^2_{\text{eff}} / 3\lambda, \tag{1}$$

where $n_{eff,0}$ is the effective index for the fundamental mode, $n_{eff,1}$ is the effective index for the first higher-order mode, n_s is the slab effective index, w_{eff} is the effective MMI width, λ is the working wavelength. This novel property enables a novel design of four-channel mode (de)multiplexer by cascading numerous MMI-based mode sorters and phase shifters [23]. However, for such a design, the output signal is not carried by the fundamental mode when the TE_2 mode is demultiplexed from the multi-mode bus waveguide, which hinders the further applications. In [24], a two-channel mode (de)multiplexer was proposed by combining a 3-dB MMI coupler ($L_{MMI} = 3L_{\pi}/2$) with a MMI-based mode sorter ($L_{MMI} = 3L_{\pi}/4$), as shown in Figure 3a. The input TM₀ mode from the edge port can be evenly split by a 3-dB coupler. The phase inversion is then introduced to the split beams by utilizing a π phase shifter. Finally, the two beams are combined by a cascaded mode sorter. The TM₀-TM₁ conversion is also carried out in the meantime. On the other hand, the input TM_0 mode from the central port can directly propagate through the 3-dB coupler and mode sorter without mode conversion. This MMI-based structure can provide low insertion losses (IL < 1.8 dB), low crosstalk (XT < -20 dB) and a broad working bandwidth (BW > 60 nm) [25]. The major disadvantage is the relatively large device size (\approx 80 µm), which can be reduced by replacing the phase shifter with a tilted joint section [26]. The two-channel mode (de)multiplexer can also be realized by using a 2×2 MMI coupler (L_{MMI} = L_{π}/2) assisted with a symmetric Y-junction [27]. The designed 2×2 MMI coupler can evenly separate the input TE₀ mode with a phase difference of $-\pi/2$ or $+\pi/2$, which can be modified to 0 or π by inserting a $\pi/2$ phase shifter. The two beams with $0/\pi$ phase difference are then combined and converted to TE_0/TE_1 modes by a symmetric Y-junction. The simulation results show low losses (IL < 0.1 dB), low crosstalk (XT < -17 dB) and a broad bandwidth (BW > 100 nm). Compared with the previous MMI-based structures, this improved design can provide a simplified configuration as well as a better performance. However, the MMI/Y-junction structure still suffers from a relatively large footprint (\approx 50 µm). The device size can be effectively reduced to \approx 36 µm by using a subwavelength grating (SWG) metamaterial slab with engineered refractive index and mode dispersion [28]. Apart from the smaller footprint, this SWG-based structure also has a superior performance compared with the aforementioned MMI-based design. The working bandwidth can be as large as 300 nm, while low losses (IL < 0.84 dB) and low crosstalk (XT < -20 dB) can also be maintained.

The second type of silicon mode (de)multiplexer is based on the asymmetric Y-junction. The mostly commonly used Y-junctions are symmetric [60–63], which have been extensively applied for power splitting/combining and signal broadcasting. The asymmetric Y-junction is less common, which is usually characterized by the non-identical arms in term of the waveguide width. For the asymmetric Y-junction, the incident light from a single arm will be coupled into a higher-order mode with the closest effective index [64]. The mode conversion factor (MCF) can be used to determine the structural parameters of an asymmetric Y-junction [65]:

$$MCF = |\beta_a - \beta_b| / \theta_d \gamma_{ab}, \tag{2}$$

$$\gamma_{ab} = 0.5[(\beta_a + \beta_b)^2 - (2k_0n_c)^2]^{1/2},$$
(3)

where β_a/β_b is the propagation constant for the fundamental mode in the wider/narrower arm, θ_d is the divergence angle, k_0 is the free-space wavenumber, n_c is the cladding refractive index. The mode-selective coupling occurs when MCF > 0.43 [65]. This unique characteristic of asymmetric coupling offers a great opportunity for mode (de)multiplexing. The asymmetric Y-junctions are initially

studied on low-contrast material platforms, e.g., silica waveguide or silica fiber [64,66,67]. In [29], a two-channel silicon mode (de)multiplexer was demonstrated based on asymmetric Y-junctions, as shown in Figure 3b. For such a design, the input TM_0 mode in the wider/narrower arm excites the first even/odd mode in the "stem", i.e., TM₀/TM₁. The measurement results exhibit low losses (IL < 1.5 dB) and low crosstalk (XT < -30dB) for the fabricated asymmetric Y-junction. However, this Y-junction-based design is quite sensitive to the structural parameters, especially to the divergence angle (θ_d), since the mode-selective condition (MCF > 0.43) will no longer be satisfied when θ_d is changed. Another drawback is the relatively narrow working bandwidth caused by the coupling-induced interference between two arms. These problems could be solved by introducing the novel shortcut-to-adiabaticity (STA) method [68]. The parametric sensitivity and interference effect can be dramatically inhibited for the asymmetric Y-junction by varying waveguide widths and waveguide separation along the arm section [69], leading to a robust and broadband mode (de)multiplexing. As an alternative, the two-channel mode multiplexer can also be realized by exploiting a "two-step" strategy [30]. The TE_0 mode in the wide/narrow arm is first converted to the symmetric/asymmetric super-mode (i.e., TE_S/TE_{AS}) by using an adiabatic coupler [70,71]. Such TE_S/TE_{AS} super-modes are then injected into the "stem", which will directly excite TE_0/TE_1 modes in the multi-mode bus waveguide. Here, the super-modes are used as a transition between the input fundamental modes and the output higher-order modes, which prevents the undesired crosstalk caused by direct mode conversion. The mode (de)multiplexer with low losses (IL < 1 dB) and low crosstalk (XT < -20 dB) was experimentally achieved over a broad wavelength span from 1.525 μ m to 1.60 μ m (BW \approx 75 nm). Moreover, for this design, the high-performance can be preserved even if the structural parameters are deviated over a $>\pm 30$ nm range. There are also some other types of Y-junction-based MDMs, such as ones based on partially etched slab waveguides [31].

However, there are some clear disadvantages of the silicon mode (de)multiplexers based on MMIs or asymmetric Y-junctions. For instance, the MMI-based structures usually suffer from intrinsically high insertion losses due to the strong scattering at the input/output port, while for the Y-junction-based structures, a small feature size is usually required at the position where two arms are converged. The ADC has been widely considered as a better choice for realizing high-performance silicon mode (de)multiplexers, which is comprised of two closely placed waveguides with different core widths (see Figure 4c). Here, we show a design example for an ADC-based two-channel mode (de)multiplexer considering the first two TE modes (i.e., TE_0/TE_1). The input TE₀ mode in waveguide #0 can be coupled to the output TE₁ mode in waveguide #1 through evanescent coupling (see the inset of Figure 4a). The complete TE_0 - TE_1 coupling can be obtained only if the phase-matching and critical coupling conditions are simultaneously satisfied [72]. Figure 4a shows the calculated effective indices for TE_0 and TE_1 modes in a SOI waveguide with core width varying from 250 nm to 1 μ m. Here, we consider the 220-nm-thick SOI platform with a SiO₂ upper cladding. The core width is chosen to be $w_{wg,0} = 400$ nm for waveguide #0 to fulfill the single-mode condition operating at 1.55-μm wavelength. Thus, one can easily determine the core width for waveguide #1 as $w_{wg,1} = 835$ nm, so that the effective indices are matched between TE₀ and TE₁ (see the dashed lines in Figure 4a). After that, we calculate the TE₀–TE₁ coupling ratio with varied coupling length, as shown in the left panel of Figure 4c. Here, the gap width is chosen to be $w_{gap} = 200$ nm. It can be observed that the curve is sinusoid-like and the first critical coupling length is $\approx 18 \ \mu$ m. The light propagation profile is then calculated for the optimized ADC, as shown in the left panel of Figure 4d. From the profile, one can observe the efficient TE_0-TE_1 mode conversion and the complete power transfer from waveguide #0 to waveguide #1. Additionally, the phase-matching condition is satisfied only between TE_0 in waveguide #0 and TE_1 in waveguide #1, so TE_0 mode can directly inject into waveguide #1 without evanescent coupling or mode conversion (see the dashed lines in Figure 4a), enabling a dual-mode (de)multiplexing.



Figure 4. (a) The calculated effective indices for TE_0 and TE_1 modes in a SOI waveguide with varied waveguide width (w_{wg}). The inset shows the cross-section of an ADC with some key parameters labeled. (b) The calculated effective indices for TE_0 and TE_1 modes (solid lines) and TE_S/TE_{AS} super-modes (dashed lines) in an ADC with varied waveguide width ($w_{wg,0}$ and $w_{wg,1}$). The inset shows the mode profiles. (c) The calculated TE_0 – TE_1 coupling ratio for ADC (left panel) and adiabatic ADC (right panel) with varied coupling length. (d) The calculated light propagation profiles for ADC (left panel) and adiabatic ADC (right panel) when TE_0 mode is launched.

However, for the silicon ADCs, the phase-matching and critical coupling conditions can be perfectly fulfilled only at the central wavelength due to the strong waveguide dispersion, leading to a restricted working bandwidth. The bandwidth could be expanded by using SWGs [32–34] or hybrid plasmonics [35], but these structures are not easy to realize. Furthermore, a stringent fabrication is always required for ADCs since the mode conversion and light-coupling processes are quite sensitive to the parametric deviations, which could significantly increase the crosstalk [73]. These obstacles can be tackled by utilizing adiabatic ADCs [36,37]. The idea is to introduce an adiabatic mode evolution by gradually changing the core widths $(w_{wg,0}, w_{wg,1})$ along the coupling section. Here, we show a design example for an adiabatic TE₀-TE₁ ADC with linearly varied core widths. For waveguide #0, the core width is linearly varied from $w_{wg,0} = 350$ nm to $w_{wg,0} = 270$ nm, while for waveguide #1, the core width is linearly varied from $w_{wg,1} = 630$ nm to $w_{wg,1} = 810$ nm. Here, the gap width is set to be $w_{gap} = 200$ nm. Figure 4b shows the calculated effective indices for TE_0/TE_1 modes in waveguide #0/#1 (see the solid lines) and TE_S/TE_{AS} super-modes in the dual-core ADC (see the dashed lines). From the curves, one can find a critical point where the effective indices are matched between TE_0 and TE_1 (w_{c,0} = 325 nm, w_{c,1} = 690 nm). The TE_S effective index approaches the TE₀ effective index when $w_{wg,0} > w_{c,0}$ and $w_{wg,1} < w_{c,1}$, indicating that the light power is mainly supported by the TE₀ mode in waveguide #0, as shown in the inset of Figure 4b. Around the critical point, both TE_0 and TE_1 modes will be excited in waveguide #0/#1 (see the inset of Figure 4b), indicating the phase matching. The TEs effective index approaches the TE₁ effective index when $w_{wg,0} < w_{c,0}$ and $w_{wg,1} > w_{c,1}$, indicating that the light power is mainly supported by TE₁ mode in waveguide #1, as shown in the inset of Figure 4b. Thus, the input TE₀ mode in waveguide #0 can be gradually "pushed" into waveguide #1

by slowly varying the core widths. The TE_0 - TE_1 mode conversion is also attained in the meantime. To demonstrate this, we calculate the TE_0-TE_1 coupling ratio with various coupling lengths, as shown in the right panel of Figure 4c. For the conventional ADC, the coupling ratio periodically changes with the coupling length, while for the adiabatic ADC, the coupling ratio monotonically reaches 100% when the coupling length is long enough (>100 μ m), indicating that the mode conversion is an adiabatic process. One might find some ripples in the coupling-ratio curve, which is mainly induced by the slight interference effect. The light propagation profile is then calculated for the optimized adiabatic ADC, as shown in the right panel of Figure 4d. The complete mode conversion can be observed from the calculated profile. In [38], the silicon adiabatic ADC was demonstrated for the first time. The measurement results show low losses (IL < 0.3 dB) and low crosstalk (XT < -16 dB) over a 100-nm wavelength band. The counter-tapered ADC was proposed and demonstrated in [39] to further enhance the working bandwidth (BW >180 nm) and relax the fabrication stringency. Later, the taper-etched ADC was proposed as a highly efficient mode (de)multiplexer [40]. Low losses (IL < 1.3 dB) and low crosstalk (XT < -26 dB) were also experimentally demonstrated. However, adiabatic coupling is always accompanied with a long coupling length (see Figure 4c) and a large footprint. Note that the gap width is fixed for the aforementioned ADCs, so the coupling strength is a constant for these structures. The recent studies have shown that a broad bandwidth can be ensured even with quite a short coupling length by simultaneously changing core width ($w_{wg,0}, w_{wg,1}$) and gap width (w_{gap}) [41]. In [42], a short and robust silicon ADC was realized by utilizing the novel STA method. A detailed description of an STA-based coupler can be found in [74]. For this optimal design, the coupling length is as short as 50 μ m, while ultra-low crosstalk (XT < -30 dB), ultra-broad bandwidth (BW > 150 nm) and ultra-large fabrication tolerance (\pm 50 nm) can still be ensured.

From the above discussions, the structures based on MMIs, asymmetric Y-junctions and ADCs all show some degrees of advantages in achieving mode (de)multiplexing. However, all these mode (de)multiplexers are not scalable, which means that these designs can only support a few modes (typically two modes). The scalable mode (de)multiplexers are desired in the MDM systems, which can be built by successively connecting several Y-junctions [75,76] or ADCs [77–82]. Figure 5a shows the configuration of a typical four-channel mode (de)multiplexer using the cascaded asymmetric Y-junctions [75]. Three higher-order TE modes (i.e., TE_1 , TE_2 , TE_3) can be independently excited by several different Y-junctions, while the fundamental TE mode, i.e., TE₀, is directly injected into the multi-mode bus waveguide. The arm widths are carefully chosen so that the mode-selective condition is satisfied for only one higher-order mode in each Y-junction. In [76], W. Chen et al. reported a three-channel MDM with cascaded asymmetric Y-junctions on silicon. The experimental results exhibit crosstalk of XT ≈ -10 dB for the first three TE modes (i.e., TE₀₋₂). Nevertheless, the cascaded asymmetric Y-junction still seriously suffers from significant insertion losses (IL > 5 dB) and the small feature size at the junction's tip. In contrast, the cascaded ADCs are broadly considered as a more promising candidate for mode (de)multiplexing based on the best overall performances. In 2013, the first cascaded ADC-based silicon mode (de)multiplexer was reported by D. Dai et al. [77], as illustrated in Figure 5b. In ADC #i, the phase matching is satisfied only between TM_0 and TM_i , so the input TM₀ mode can converted to TM_i mode and multiplexed into the multi-mode bus waveguide, while the other higher-order modes (i.e., TM_{j} , j < i) will go through the coupling section with negligible losses. Additionally, TM₀ mode is directly launched from the multi-mode bus waveguide without evanescent coupling or mode conversion. In this way, a four-channel mode (de)multiplexer can be built by cascading three ADCs with adiabatic tapers as connectors in between. Compared with the cascaded Y-junctions, the proposed cascaded ADCs can provide a larger feature size (>300 nm), lower insertion losses (IL < 1 dB) and lower crosstalk (XT < -23 dB). However, the experimental results also show a relatively narrow working bandwidth (BW \approx 20 nm), which can be further improved (BW > 100 nm) by exploiting adiabatic coupling [39,78,79] or ultra-thin waveguides [80]. Moreover, recent research also shows that the crosstalk of cascaded ADCs can also be further mitigated by exploiting coherence detection [83]. In Table 1, we summarize the reported silicon mode (de)multiplexers. It can be seen that

the various silicon mode (de)multiplexers have been realized with low losses, low crosstalk and a broad bandwidth. In theory, the mode capacity can be expanded at will by simply cascading more ADCs; however, an extremely long coupling length would be needed to achieve the conversion to a very high-order mode, which could lead to a large and complex device layout as well as increased crosstalk. The issue could be addressed by employing SWG waveguides with an engineered index [81,82]. However, the fabrication of SWG is immature given its subwavelength feature size. To further expand the capacity, a more effective solution is the wavelength/polarization/mode hybrid (de)multiplexing that combines multiple dimensions of light. A discussion about silicon hybrid (de)multiplexers will be given in Section 2.2.



Figure 5. The schematics for the scalable silicon mode (de)multiplexers based on (**a**) cascaded asymmetric Y-junctions [75,76] and (**b**) cascaded ADCs [77].

Pof	Voar	Size (um)	Canacity	IL (d	1B)	XT ((dB)	BW (nm)	
Kei	iear	312e (µ111)	Capacity	Sim.	Exp.	Sim.	Exp.	Sim.	Exp.
[24]	2012	80	2	1	/	<-40	/	60	/
[77]	2013	≈100	4	0.1	1	-25	-23	/	20
[38]	2013	50	2	/	0.3	-22	-16	200	100
[29]	2013	100	2	/	1.5	/	-30~-9	/	<20
[27]	2014	48.8	2	0.3	/	$-48 \sim -22$	/	100	/
[35]	2014	13.6	2	0.35	/	-17	/	100	/
[26]	2015	39.54	2	1	/	-36.3~-25	/	100	/
[42]	2015	≈150	4	< 0.5	/	-40	/	150	/
[39]	2015	≈ 400	3	0.18	/	/	$-20.5 \sim -10$	/	180
[76]	2016	≈350	3	0.32~0.82	5.7	$-44.9 \sim -11.9$	-31.5~-9.7	120	29
[30]	2016	180	2	0.3	1	-18	-20	100	75
[40]	2016	68	2	0.1~0.3	1.3	-40	-26	200	65
[84]	2016	2.6×4.22	2	<1	<1.2	<-18	<-12	100	100
[04]	2016	$\approx 5 \times 6$	3	/	1.7	/	<-14	/	>35
[78]	2017	≈450	4	0.7	1.3	-30	-23	200	100
[32]	2017	6.25	2	1	/	$-18 \sim -10$	/	120	/
[80]	2017	310	3	0.2	0.2	-20	$-33 \sim -18$	130	65
[85]	2019	2.3×3	2	$0.47 \sim 0.91$	1	-24	-24	60	60
[00]	2016	3.6×4.8	3	/	1.2~2.5	/	-22~-19	/	60
[28]	2018	36	2	0.84	/	-20	/	300	/
[81]	2018	507	11	/	0.1~2.6	/	$-15.4 \sim -26.4$	/	50
[34]	2019	8.75	2	0.39	/	-15	/	310	/
[79]	2019	≈900	4	/	1.3~5	<-15	-18	70	70
[25]	2020	136	2	0.22~1.3	1.8	-25.2~-20	-20	60	60

Table 1. Summary of the reported silicon mode (de)multiplexers.

IL, insertion loss. XT, crosstalk. BW, working bandwidth. Sim., simulation results. Exp., experimental results.

2.2. Silicon Hybrid (De)Multiplexers

As discussed above, mode (de)multiplexing can efficiently enhance the link capacity, but it is still quite difficult to (de)multiplex very high-order modes in a multi-mode bus waveguide. Therefore, it is more cost effective to build multi-dimensional on-chip communication systems by combining MDM with WDM [86–95] and PDM [96–100].

The wavelength/mode hybrid (de)multiplexers are able to simultaneously manipulate signals carried by wavelength and mode channels. WDM/MDM hybrid systems could be realized by using some special mode (de)multiplexers with strong wavelength-selectivity, e.g., asymmetric Y-junctions [86], grating-assisted ADCs [87], photonic crystals [88] and asymmetric micro-ring resonators [89,90]. However, such wavelength-selective mode coupling is usually quite sensitive to parametric deviations, which make it difficult to align each wavelength/mode channel. A more general architecture is to cascade the broadband mode (de)multiplexers (e.g., cascaded ADCs) with the conventional wavelength (de)multiplexers, such as arrayed waveguide gratings (AWGs) [91,92] and micro-ring resonators (MRRs) [94,95], as summarized in Figure 6.



Figure 6. The schematics for the silicon wavelength/mode hybrid (de)multiplexers with (**a**) bi-directional arrayed waveguide gratings (AWGs) [92] and (**b**) bi-directional micro-ring resonators (MRRs) [94]. The inset shows the wavelength and mode channel arrangement. Here, a 4 × 4 wavelength-division multiplexing (WDM)/MDM system is illustrated as an example.

The silicon AWGs are most commonly used in the dense wavelength division-multiplexing (DWDM) systems because of the large free-spectral range (FSR) and small channel spacing [101–107], showing great potential for large-scale hybrid (de)mulitplexing. In [91], a 64-channel WDM/MDM hybrid system was demonstrated on silicon by cascading four identical 16-channel AWGs with a four-channel mode (de)multiplexer. For each AWG, sixteen wavelength carriers are multiplexed into a single-mode waveguide with TM_0 . These four waveguide channels are then converted to TM_0 - TM_3 and multiplexed into a multi-mode bus waveguide, which makes a total link capacity of 64 (16×4). For such a structure, the insertion losses and crosstalk were measured to be IL \approx 7 dB and XT \approx -10 dB, respectively. It should be noted that the AWGs can be bi-directional, which means that two 1 × N AWGs can be replaced by one $(N + 1) \times (N + 1)$ AWG with equivalent functionalities [101], as shown in Figure 6a. This idea was implemented to realize an improved wavelength/mode hybrid (de)multiplexer with an AWG number reduced to half [92]. The measurement results show insertion losses of IL \approx 5 dB and crosstalk of XT \approx -14 dB for a 64-channel WDM/MDM hybrid system. Nevertheless, the device footprint is still quite large (a few millimeters) for AWG-based wavelength/mode hybrid (de)multiplexers even if bi-directional configurations are applied. As an alternative, the cascaded MRRs are also popular for WDMs because of the low insertion losses, high extinction ratios and, especially, the compact device sizes [108–110]. Moreover, according to the tight-binding model [111], the top-flattened transmission responses can be realized by simply cascading several side-coupled MRRs in a serial [112]. Additionally, both clockwise and counterclockwise propagations are allowed in MRRs, so the bi-directional configurations are also applicable, as illustrated in Figure 6b. In [94], a 32-channel WDM/MDM hybrid system was demonstrated on silicon by cascading two sets of bi-directional eight-channel MRR arrays with a four-channel mode (de)multiplexer. For the fabricated device, the insertion losses were measured to be IL < 4.5 dB while the crosstalk was measured to be XT < -18dB. The insertion losses and crosstalk can be further reduced by adopting flat-top MRR filters [95]. We give a summary of the reported silicon wavelength/mode hybrid (de)multiplexers in Table 2. It can be seen that, for most of the reported structures, the wavelength channels still outnumber the mode channels, which gives rise to the system cost and layout complexity. Hence, it is necessary to reduce the wavelength channels further by introducing TE/TM polarizations as a third dimension. Furthermore, coarse wavelength-division multiplexing (CWDM) with a larger channel spacing (> 20 nm) could also be helpful to enhance the stability and lower the cost [93,113–117].

Ref	V	C: ()	Cap	acity	AD (mm)	TT	УT	
	Year	512e (mm) —	W	М	$-\Delta \Lambda$ (nm)	IL	XI	
[86]	2014	1.2	3	2	8~10	/	-30	
[89]	2014	≈0.2	2	3	0.4	1.5	-22~-12	
[91]	2014	$\approx 3 \times 2$	16	4	3.2	7	-10	
[92]	2015	$< 1.5 \times 1.5$	16	4	3.2	3.5~5.5	-14	
[93]	2015	0.1	2	2	240	1.2	-18	
[94]	2018	1.3	8	4	2	4.5	-18	
[95]	2018	<1	8	4	3.2	0.5~5	-23.5~-16.5	

Table 2. Summary of the reported silicon wavelength/mode hybrid (de)multiplexers.

W, wavelength channels. M, mode channels. $\Delta\lambda$, channel spacing. IL, insertion loss. XT, crosstalk.

The polarization/mode hybrid (de)multiplexers are able to handle multiple mode channels with dual polarizations. One straightforward scheme is to directly cascade the two groups of ADCs designed for TE and TM modes, respectively, as illustrated in Figure 7a. In [96], an eight-channel polarization/mode hybrid (de)multiplexer was demonstrated on silicon with the first four TE/TM modes (i.e., TE_{0-3} and TM_{0-3}). The higher-order modes (i.e., TE_{1-3} and TM_{1-3}) are excited by using the cascaded ADCs, while TE_0 and TM_0 modes are coupled into the multi-mode bus waveguide by using a polarization beam splitter (PBS). The experimental results exhibit insertion losses of IL \approx 2dB and crosstalk of XT \approx –10 dB over a 30-nm bandwidth. For such polarization/mode hybrid (de)multiplexers,

the measured crosstalk is much higher compared with the conventional mode (de)multiplexers working on a single polarization [77]. Such a phenomenon is mainly due to the undesired inter-polarization crosstalk (IPC) at the receiver terminal. Here, we show a design example to illustrate this effect. We calculate the effective indices for TE_0 and TE_2 modes in the 220-nm-thick SOI with SiO₂ cladding, as shown in Figure 8a. The waveguide widths are chosen to be $w_{wg,0} = 400$ nm and $w_{wg,1} = 1.27 \mu m$ to meet the phase-matching condition between TE_0 and TE_2 at a 1.55-µm wavelength. The gap width is chosen to be $w_{gap} = 150$ nm. The coupling length is then optimized to be 15.5 μ m to achieve critical coupling. Thus, the input TE_2 mode can be completely demultiplexed from the multi-mode bus waveguide with negligible residual power, as shown in Figure 8c. Unfortunately, for these optimal parameters, the effective indices are also quite close between TM_0 and TM_1 (see the dashed lines in Figure 8a). As a result, part of the input TM_1 mode will also be extracted by the ADC optimized for TE₀–TE₂ conversion (see Figure 8c), leading to the significant IPC. The IPC could be reduced by optimizing the structural parameters to achieve a polarization-selective mode coupling [96–98]. However, this methodology always leads to a relatively narrow working bandwidth and a significant parametric sensitivity. Another possible solution is to cascade the polarizers to filter out the undesired polarizations [99], but polarization filtering will give rise to the total insertion losses [118–128].



Figure 7. The schematics for the silicon polarization/mode hybrid (de)multiplexers based on (**a**) cascaded ADCs [96] and (**b**) cascaded adiabatic ADCs [100].





Figure 8. (a) The calculated effective indices for $TE_0/TE_2/TM_0/TM_1$ modes in the SOI waveguide with varied waveguide width (w_{wg}). The inset shows the cross-section of an ADC with some key parameters labeled. (b) The calculated effective indices for $TE_0/TE_2/TM_0/TM_1$ modes (solid lines) and $TE_S/TE_{AS}/TM_S/TM_{AS}$ super-modes (dashed lines) in the ADC as the waveguide width ($w_{wg,0}$ and $w_{wg,1}$) varying. The inset shows the mode profiles. (c) The calculated light propagation profiles for ADC (left panel) and adiabatic ADC (right panel) when TE_2 and TM_1 modes are launched.

The IPC problem can be addressed by exploiting the cascaded adiabatic ADCs, as shown in Figure 7b. The idea is to optimally choose the core widths for each ADC, so that both TE and TM polarizations can be completely extracted from the multi-mode bus waveguide. The decoupled TE_0 and TM_0 modes are then separated by a PBS. To illustrate this idea, we show a design example of adiabatic ADC considering both TE_0 - TE_2 and TM_0 - TM_1 mode conversions. For waveguide #0, the core width is linearly varied from $w_{wg,0} = 270$ nm to $w_{wg,0} = 470$ nm, while for waveguide #1, the core width is linearly varied from $w_{wg,1} = 1.27 \mu m$ to $w_{wg,1} = 990 nm$. Here, the gap width is set to be w_{gap} = 150 nm. Figure 8b shows the calculated effective indices for $TE_0/TE_2/TM_0/TM_1$ modes (see the solid lines) and $TE_S/TE_{AS}/TM_S/TM_{AS}$ super-modes (see the dashed lines). Over this width variation range, the phase matching can be achieved for both TE_0-TE_2 and TM_0-TM_1 at different critical widths (see the curve intersections in Figure 8b). Thus, the input TE₂ and TM₁ modes can be simultaneously "pushed" into the single-mode waveguide (see the inset of Figure 8b). We then calculate the light propagation profiles for the optimized ADC when TE_2 and TM_1 modes are launched, as shown in the right panel of Figure 8c. Here, the coupling length is chosen to be 50 µm to satisfy the adiabatic condition. From the profiles, one can observe the efficient mode conversion and complete power transfer for both TE and TM polarizations. This idea was implemented to realize a 10-channel polarization/mode hybrid (de)multiplexer working with the first six TE and four TM modes (i.e., TE_{0-5} , TM_{0-3}). The experimental results show low losses (IL < 1.8 dB) and low crosstalk (XT < -15 dB) over a 90-nm wavelength band. In Table 3, we summarize the reported silicon polarization/mode hybrid (de)multiplexers. One can see that the link capacity can be efficiently enhanced (up to 10 channels) by combining MDM and PDM technologies, while low losses (IL < 2 dB) and low crosstalk (XT \approx -20 dB) can still the preserved over quite a broad wavelength band (BW ≈ 100 nm).

Ref.	Voor	Size (um)	Capacity (TF + TM)	IL	(dB)	ХТ	' (dB)	BW (nm)	
	Ical	512e (µ111)	Capacity (12 + 114)	Sim.	Exp.	Sim.	Exp.	Sim.	Exp.
[96]	2014	≈300	4 + 4	2	2	-10	-10	100	30
[99]	2014	≈600	4 + 4	/	0.2~3.5	/	-20	/	100
[100]	2018	≈500	6 + 4	< 0.1	0.2~1.8	-20	-25~-15	130	90
[97]	2019	74.75	6 + 4	<1	/	-11.4	/	85	/

Table 3. Summary of the reported silicon polarization/mode hybrid (de)multiplexers.

IL, insertion loss. XT, crosstalk. BW, working bandwidth. Sim., simulation results. Exp., experimental results.

The link capacity can be dramatically scaled up by employing WDM/MDM or PDM/MDM hybrid systems. However, it is still challenging to realize WDM/PDM/MDM hybrid systems that involve all the three dimensions of light. So far, there have been only a few demonstrations on the wavelength/polarization/mode hybrid (de)multiplexing. Recently, Y. He et al. demonstrated an eight-channel hybrid (de)multiplexer with two wavelengths, two polarizations and two modes [129]. The device is based on the cascaded contra-directional couplers that assist with Bragg gratings. According to the Bragg condition, each coupling section can select a single carrier on a specific wavelength/polarization/mode channel. Nevertheless, the capacity is still restricted for this structure, and the insertion losses are also quite significant (IL \approx 6.6 dB). Here, we propose a general configuration for the scalable WDM/PDM/MDM hybrid systems, as illustrated in Figure 9. As an example, we show a 32-channel hybrid (de)multiplexer with four wavelengths, two polarizations and four modes. At the transmitter terminal, the 32-channel carriers with TE_0 are firstly coupled into eight single-mode waveguides in term of the wavelengths. Four of them are cascaded with the broadband polarization rotators [130–141] that convert TE_0 to TM_0 . The PBSs [142–153] are then utilized to combine the orthogonal polarizations, so that the 32-channel signals can be carried by four single-mode waveguides. Finally, all the carriers are coupled into a multi-mode bus waveguide by using a polarization/mode hybrid multiplexer working on TE_{0-3} and TM_{0-3} [100]. At the receiver terminal, the 32-channel carriers are decoupled from the multi-mode bus waveguide by cascading MDM, PDM and WDM in sequence. This configuration can be used as a general architecture to build any user-defined WDM/PDM/MDM hybrid system.



Figure 9. A proposal for the scalable WDM/polarization-division multiplexing (PDM)/MDM hybrid systems.

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2.3. Densely Packed Waveguide Array

For the MDM system, the signals are usually carried by multiple higher-order modes in a wide multi-mode bus waveguide. However, from the above discussions, one might find that the high-performance mode (de)multiplexers are not easily realized. Instead of using the higher-order modes, the MDM can also be obtained by using the super-modes supported by several closely placed single-mode waveguides, leading to the novel concept of a densely packed waveguide array (DPWA) [154–160], as shown in Figure 10.



Figure 10. The schematics for the silicon (a) densely packed waveguide array (DPWA) [154,157], (b) densely packed multi-mode waveguide array (DPMWA) [158] and (c) densely packed bent-waveguide array (DPBWA) [159,160].

In [154], the DPWA-based MDM was proposed for the first time. The structure consists of three single-mode SOI waveguides each with different core widths and narrow gap widths in between, as shown in Figure 10a. Three super-modes can be supported by the DPWA. Unlike the conventional guided modes that are supported by a single isolated waveguide, the super-modes are supported by an array of waveguides, so the field contribution can be engineered by modifying parameters for each waveguide. If the core widths are uniform ($w_{wg,0} = w_{wg,1} = w_{wg,2}$), each super-mode will have power distributions in more than one waveguide. In contrast, if the core widths are non-uniform $(w_{wg,0} \neq w_{wg,1} \neq w_{wg,2})$, each super-mode will be well confined in a single core region due to phase mismatching (see the inset of Figure 10a). Moreover, such distinguishable distribution can be kept for all the three super-modes even if the gap widths are deep-subwavelength ($w_{gap} = 100 \text{ nm}$), so the waveguide array can be regarded as a multi-mode bus waveguide with a small lateral-dimension. For DPWA, mode (de)multiplexing can be achieved by using a simple fan-in/out structure since the mode profiles are perfectly matched between super-modes and individual TE₀ mode, leading to a simple device layout. Such DWPA-based MDM can provide low losses (IL < 0.1 dB), low crosstalk

(XT < -20dB) and a broad bandwidth (BW >100 nm). Furthermore, the DPWA can also be used as a sub-cell in an even larger waveguide super-lattice structure [155,156].

For DPWA-based MDM, the total capacity can be expanded further by introducing dual polarizations or higher-order modes [157,158]. In [157], a five-channel polarization/mode hybrid multiplexing was demonstrated with a DPWA supporting three TE super-modes and two TM super-modes. The fabricated device exhibits low losses (IL < 0.6 dB) and low crosstalk (XT < -15 dB) over an 80-nm wavelength span. However, the scalability is limited for this design since there are only two orthogonal polarizations. The densely packed multi-mode waveguide array (DPMWA) was proposed to break the limit [158]. The DPMWA structure is comprised of three parallel multi-mode waveguides each supporting three TE modes (i.e., TE₀₋₂), leading to a transmission capacity of nine super-modes, as shown in Figure 10b. Each super-mode can be effectively restricted within a single core region (see the inset of Figure 10b) because of the core width differences. To realize the mode multiplexing, the higher-order modes are firstly excited in each waveguide by using the cascaded ADCs; the excited higher-order modes can directly convert to the corresponding super-modes through a simple butt-coupling process. From the experimental results, one can find low losses (IL < 1 dB) and low crosstalk (XT < -15 dB).

For DPWA, large effective-index difference is always desired between the adjacent cores in order to reduce the crosstalk in the MDM system. Phase mismatching can be achieved by changing the core widths, as discussed above. However, the width variation design requires a high-resolution fabrication process. An alternative is to engineer the waveguide curvature. For the bent waveguides, the phase-matching condition can be written as [161]:

$$\mathbf{n}_{\mathrm{eff},0}\mathbf{R}_0 = \mathbf{n}_{\mathrm{eff},1}\mathbf{R}_1,\tag{4}$$

where $n_{eff,0}$ and $n_{eff,1}$ are the effective indices, R_0 and R_1 is the bending radii. From the equation, it can be seen that the adjacent cores can be phase-mismatched even with the same core widths ($n_{eff,0} = n_{eff,1}$) as long as the bending radii are different ($R_0 \neq R_1$), which leads to the densely packed bent-waveguide array (DPBWA), as shown in Figure 10c. In [159], a 16-channel DPBWA-based MDM was demonstrated with low losses (IL < 1 dB), low crosstalk (XT < -20 dB) and a broad bandwidth (BW > 80 nm). All the waveguides in the proposed DPBWA have the same core widths, which makes the DPBWA quite easy to fabricate. In [160], a similar super-lattice structure was also demonstrated with low losses (IL < 0.5 dB) and low crosstalk (XT < -19.5).

The working performances for the reported silicon DPWAs are summarized in Table 4. One can see that the major advantage of the DPWA/DPMWA/DPBWA-based MDM is the large capacity (up to 16 channels) since the channel number can be easily scaled up by involving more waveguides. The losses and crosstalk are also quite weak due to the convenient mode (de)multiplexing. We believe that the novel DPWA can offer great opportunities for high-density on-chip optical transmissions.

Table 4. Summary of the reported DPWA-based MDMs.

Ref.	Veer	Size (um)	Canacity	IL (dB)		XT	(dB)	BW (nm)	
	Ical	312e (µ111)	Capacity -	Sim.	Exp.	Sim.	Exp.	Sim.	Exp.
[154]	2015	15	3	0.05	/	-20	/	100	/
[155]	2015	<100	11	/	/	<-20	<-20	70	70
[157]	2015	60	5	0.05	0.6	-20	-15	80	80
[159]	2016	≈30	16	0.1	1	-30	-20	100	80
[158]	2017	<200	9	<1	≈ 1	≈20	-15	100	55
[160]	2019	<100	11	0.1	0.5	<-20	-19.5	/	80

IL, insertion loss. XT, crosstalk. BW, working bandwidth. Sim., simulation results. Exp., experimental results.

3. Silicon Multi-Mode Routing Devices

A complex topology is always desired to boost the performance of an on-chip data link. For example, Figure 11 shows the configuration for the multi-mode interconnects in a micro-processor with five cores. From the configuration, one can find that a situation has arisen where multi-mode routing devices are necessary to facilitate the multi-mode network; also, the multi-mode routing devices should fall into three categories: multi-mode bends, multi-mode crossings and multi-mode splitters. The multi-mode bends enable light transmission with a sharp curvature, which will be discussed in Section 3.1. Another essential building block is the multi-mode crossing, which enables simultaneous cross-over propagations for multiple higher-order modes. The silicon multi-mode crossings will be reviewed in Section 3.2. Multi-mode splitters are also necessary to realize the broadcast topology, which will be discussed in Section 3.3.



Figure 11. The configuration for MDM-enabled interconnects with multi-mode routing devices.

3.1. Silicon Multi-Mode Bends

The waveguide bend is a basic component that constitutes the cornerstone of a photonic integrated circuit. The SOI waveguide can support an extremely small bending radius [162–165], taking advantage of its ultra-high-index contrast. However, most of the reported silicon waveguide bends only work for the fundamental modes (i.e., TE_0 , TM_0) since the higher-order modes are vulnerable in the bending section. The underlying reason is the significant inter-modal crosstalk (IMC) induced by the distinct modal profiles between straight/bent waveguides. Here, we give a calculation example to explain this phenomenon. Figure 12a shows the calculated field profiles for the first four TE and TM modes (i.e., TE_{0-3} , TM_{0-3}) in a straight multi-mode waveguide with a 220-nm thickness and 2-µm width. From the profiles, each straight-waveguide mode (SWM) has a symmetric power distribution over the core region. In contrast, the power distribution is asymmetric for each bent-waveguide mode (BWM), as shown in Figure 12b. Here, the bending radius is chosen to be 15 µm as an example. Thus, when the incident light meets the straight–bent junction, a single SWM will be decomposed into multiple BWMs, which will interfere with each other along the waveguide bend, leading to the significant IMC. The light propagation profiles are calculated for the multi-mode bend when TE_{0-3} and TM_{0-3} .

modes are launched, as shown in Figures 11d and 12c, where a strong inter-modal interference can be observed. Thus, one has to adopt an extremely large bending radius (typically > 200 μ m) to relax the perturbation at the straight–bent junction and depress the undesired IMC [11,166]. Over the past few years, great attention has been paid to developing multi-mode bending structures, including gradient index bends [167,168], mode converter-assisted bends [169,170], gradient curvature bends [171] and corner bends [172], as summarized in Figure 13.



Figure 12. The calculated field profiles for (**a**) straight-waveguide mode (SWM) and (**b**) bent-waveguide mode (BWM). The calculated light propagation profiles for a 15- μ m multi-mode bend when (**c**) TE₀₋₃ and (**d**) TM₀₋₃ modes are launched.



Figure 13. The schematics for different silicon multi-mode bends: (**a**) gradient index bend [167,168], (**b**) mode converter-assisted bend [170], (**c**) gradient curvature bend [171], (**d**) corner bend [172].

To eliminate the bending-induced IMC, the modal mismatch between SWMs and BWMs should be depressed. In 2012, L.H. Gabrielli et al. reported the first sharp multi-mode bend on silicon [167], as illustrated in Figure 13a. Transformation optics (TO) is utilized to map the lateral index profile. The transformed BWMs and SWMs have identical power distributions; thus, the incident higher-order modes will directly propagate through the multi-mode bend without any disturbance since the modal mismatch is eliminated. However, complicated grayscale lithography is needed to attain a non-uniform index distribution by pattering the thickness profile, leading to a CMOS-incompatible fabrication. Additionally, the bending radius is still quite large (\approx 78.8 µm). In [168], an improved design was proposed to overcome these obstacles. For this design, the gradient index profile is generated by patterning a series of SWGs on the waveguide's top surface. The effective medium index can be precisely mapped by tailoring the SWG duty cycle. Furthermore, this novel structure can be easily fabricated by performing a simple shallow etching, which is a standard fabrication process in silicon

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photonics foundries. Such SWG-based multi-mode bends can provide low losses (IL < 0.7 dB), low crosstalk (IMC < -22 dB) and a broad bandwidth (BW > 80 nm) for the first three TE modes (i.e., TE₀₋₂).

Alternatively, a multi-mode bend can also be realized by adopting a pair of mode converters, as shown in Figure 13b. The incident SWMs are firstly converted to the corresponding BWMs by converter #1; thus, the light transport in the multi-mode bend will not introduce any inter-modal interference. At the output port, the SWMs are then restored from the BWMs by converter #2. Therefore, the key issue is to realize the mode converter enabling SWM-BWM conversion with a low IMC. In [169], the authors optimized a SWM-BWM converter working for TE_0 and TE_1 modes. The bending radius is as small as 5 μ m. The mode conversion efficiency could reach $\approx 100\%$ by implementing a particle-swarm optimization (PSO) that defines the waveguide geometry. Low losses (IL < 0.2 dB), low crosstalk (IMC < -22 dB) and a broad bandwidth (BW > 100 nm) were experimentally demonstrated. However, this structure can only support two modes; meanwhile, the PSO process could be very time-consuming when a larger mode capacity is considered. Later, the SWG-based mode converter was proposed [170]. This converter consists of a multi-mode waveguide and a group of SWGs on the top-surface. The SWGs are non-uniform along both lateral and propagation directions, so the input SWMs can be gradually "pushed" to one sidewall, leading to the adiabatic conversion from SWMs to BWMs. Another identical mode converter is inserted at the output port to revert BWMs to SWMs. Such an SWG-based converter is able to support the first four TM modes (i.e., TM₀₋₃) with a sharp bending radius of 30 µm. The losses and crosstalk were measured to be IL < 1 dB and IMC < -20 dB over a broad wavelength band from $1.52 \ \mu m$ to $1.60 \ \mu m$ (BW > 80 nm).

Multi-mode bends also need to be fabrication-friendly, given that the bending structures are recurring in the MDM system. However, the aforementioned designs usually require complex index mapping with subwavelength structures. A more convenient and robust scheme is based on the gradient curvature bend [171], as shown in Figure 13c. The idea is to engineer the bending trajectory by using some special curves with variant curvature, such as spline [162] or Euler curves [163,164]. For a Euler bend, the curvature is minimal at the input/output port, and adiabatically reaches its maximum value at the middle point. Thus, the inter-modal coupling can be efficiently inhibited as long as the curvature gradient is small enough. By using this method, low losses (IL < 0.5 dB), low crosstalk (IMC < -20 dB) and a broad bandwidth (BW > 90 nm) can be achieved for the first four TM modes (i.e., TM_{0-3}). The effective radius is also as small as 45 μ m. Actually, such gradient curvature bends can be regarded as special forms of mode converter-assisted bends, except that the "mode converters" are merged into the bending section, so that the footprint can be reduced. Another simple scheme is based on the corner bend [172], as illustrated in Figure 13d. The idea is to simultaneously change the propagation directions for all the supported modes at an inclined Si-SiO₂ interface, where total internal reflection (TIR) happens. The corner bend is intrinsically lossless and crosstalk free (IL < 0.5 dB, IMC < -20 dB) since there is no SWM-BWM conversion. In theory, the working bandwidth can be as large as >420 nm and the capacity can be scaled up to ten modes. However, it should be noted that the core width has to be wide enough (typically >10 μ m) to lower the diffraction losses at the corner junction; thus, one has to use two additional mode size converters (e.g., adiabatic tapers) as connectors between the bus waveguide and corner bend [173,174]. We give a summary of the reported silicon multi-mode bend in Table 5. One can find that MDM-compatible bending structures can be realized with a small radius (<20 μ m) and a high performance (IL < 1 dB, IMC < -20 dB).

Ref.	Year	Radius (um)	Capacity –	IL((dB)	IMC	(dB)	BW (nm)	
		παατάδ (μπ)		Sim.	Exp.	Sim.	Exp.	Sim.	Exp.
[167]	2012	78.8	4	/	<3	/	/	/	/
[166]	2014	10	8	< 0.1	/	<-20	/	/	/
[169]	2017	5	2	< 0.1	< 0.2	-23	-22	100	100
[170]	2018	<30	4	0.88	1.5	<-20	<-20	80	80
[171]	2018	≈ 45	4	< 0.1	0.5	<-25	-19.2	100	90
[175]	2018	3.6	2	< 0.5	< 0.8	<-25	<-24	80	60
[168]	2019	10	3	0.1~0.5	$0.1 \sim 0.7$	<-30	-22	100	80
[176]	2019	3.9	3	< 0.84	< 0.95	<-20	<-20	80	80
[172]	2020	>7 *	2~10	< 0.18	< 0.53	<-36	<-15	>420	280
[177]	2020	3.9	4	<1.1	<1.8	<-20	<-17	40	40

Table 5. Summary of the reported silicon multi-mode bends.

IL, insertion loss. IMC, inter-modal crosstalk. BW, working bandwidth. Sim., simulation results. Exp., experimental results. * Taper lengths are not included.

3.2. Silicon Multi-Mode Crossings

Waveguide crossing plays an important role in the photonic integrated circuit, with a complex pathway topology. Over the past few years, various single-mode waveguide crossings have been reported, including ones based on MMIs [178–186], ridge expanders [187], inter-layer couplers [188,189] and subwavelength structures [190–193]. Among them, the MMI-based crossing is most commonly used due to its simple design, compact size ($<10 \times 10 \mu m^2$) and low insertion losses (IL < 0.2 dB). The MMI can serve as a waveguide-lens that focuses the incident light at the cross-over position, which effectively reduces the diffraction losses [178]. However, such a focusing process only works for a single fundamental mode. To explain this, we show a calculation example considering the first two TE modes (i.e., TE₀, TE₁), as shown in Figure 14. The focal length of MMI is basically determined by interference-induced self-imaging, which can be formulated as [178]:

$$L_{f,0} = L_{B,0} = \lambda / (n_{eff,TE0} - n_{eff,TE2})$$
(5)

$$L_{f,1} = L_{B,1} = \lambda / (n_{eff,TE1} - n_{eff,TE3})$$
(6)

where $L_{f,i}$ is the focal length for TE_i , $L_{B,i}$ is the beat length for TE_i , $n_{eff,TEi}$ is the TE_i effective index, λ is the working wavelength. We calculate the beat lengths for TE_0 and TE_1 with varied waveguide width (w_{wg}) using Equations (5) and (6), as shown in Figure 14a. Here, the waveguide thickness is chosen to be $h_{wg} = 220$ nm, while the working wavelength is set to be $\lambda = 1.55 \ \mu$ m. We also calculate the light propagation profiles for the MMI-based crossings with L_f optimized for TE_0 and TE_1 , as shown in Figure 14b. It can be seen that the beat lengths are always different between TE_0 and TE_1 regardless of the variant waveguide widths. Consequently, it is challenging to focus multiple modes at the same cross-over position.

Some works suggest that the multi-mode cross-over propagation could be simply realized by employing a direct-crossing structure [194], since the beam divergence is negligible with a wide waveguide, enabling a lossless multi-mode transport (see Figure 15a). To achieve this, the waveguide width (w_{wg}) should be:

$$w_{wg} >> \lambda/n_s$$
 (7)

where n_s is the effective index for the slab mode, λ is the working wavelength. For instance, to support a four-mode cross-over (e.g., TE₀₋₃), the waveguide width should be chosen as $w_{wg} > 10 \ \mu\text{m}$. On the other hand, the multi-mode bus waveguide is usually quite narrow (e.g., $w_{wg} < 2 \ \mu\text{m}$); thus, the long adiabatic tapers (typically > 100 μ m) should also be involved to convert the mode size [173,174], leading to an extremely large total device size (>200 μ m). It is crucial that the crossing structures should have small footprints (<20 μ m) to fit in the dense cross-bar networks [195,196]. In this regard, such a direct crossing is not applicable for practical uses unless the taper length can be effectively shrunk to $\approx 10 \ \mu m$.



Figure 14. (a) The calculated beat lengths (L_B) for TE_0 and TE_1 modes with varied waveguide width (w_{wg}). (b) The calculated light propagation profiles for MMI-based crossings when TE_0 (left panel) and TE_1 (right panel) are launched. The beat lengths are different between TE_0 and TE_1 .



Figure 15. The schematics for different silicon multi-mode crossings: (a) direct crossing [194], (b) MMI-based crossing [197,198], (c) mode converter-assisted crossing [199,200], (d) Maxwell's fisheye lens (MFL)-based crossing [201,202].

A multi-mode crossing with a reduced size was firstly reported in 2016 [197], as shown in Figure 15b. The proposed scheme is still based on the MMI structure, but the focal length is chosen to be the common multiple of beat lengths for TM_0 and TM_1 :

$$L_f = p \cdot L_{B,0} = q \cdot L_{B,1} \tag{8}$$

$$L_{B,0} = \lambda / (n_{eff,TM0} - n_{eff,TM2})$$
(9)

$$L_{B,1} = \lambda / (n_{eff,TM1} - n_{eff,TM3})$$
(10)

where p and q are two integers, L_f is the focal length, L_{B,i} is the beat length for TM_i, n_{eff,TMi} is the TM_i effective index. In this way, light focusing can be simultaneously achieved for TM₀ and TM₁. The measurement results exhibit insertion losses of IL \approx 1.5 dB and crosstalk of XT < –18 dB. The working performances can be further improved by cascading several multi-sectional taper structures (IL \approx 0.1 dB, XT < –30 dB) [198]. However, there are two major drawbacks for the MMI-based crossings: first, the device size is still relatively large (\approx 30 \times 30 μ m²) since the focal length is multiplied; second, the capacity is restricted to two modes, because it is tough to find the common multiple of beat lengths for a large number of higher-order modes.

Another type of multi-mode crossing is based on mode converters. In [199], a two-mode crossing was proposed by using a 2×2 single-mode waveguide crossing matrix cascaded with four symmetric Y-junctions, as illustrated in Figure 15c. For such a scheme, the input TE₀/TE₁ modes are converted

to the symmetric/asymmetric super-modes (i.e., TE_S/TE_{AS}) in the Y-junction, so that all the crossing structures only need to work with TE_0 . The footprint is quite small ($\approx 21 \times 21 \ \mu m^2$), but the insertion losses are significant (IL ≈ 1.82 dB) owing to the intrinsically strong scattering at the junction tip. In [200], the similar idea was implemented to realize a three-mode crossing by using a 3 × 3 crossing matrix cascaded with four asymmetric Y-junctions. The insertion losses and crosstalk were measured to be IL < 0.9 dB, XT < -24 dB, respectively. Nevertheless, the mode capacity is still quite limited for

Maxwell's fisheye lens (MFL) is a perfect imaging instrument with a gradient index map that focuses rays emanating from a point on the boundary to a conjugate point on the opposite side [203]. In [201], an MFL-based multi-mode crossing was proposed and demonstrated, as shown in Figure 15d. In this work, MFL is constructed on a silicon slab based on the following equation:

this type of multi-mode crossing since higher-order mode conversion is difficult to realize.

$$n_{\rm eff}(R) = n_{\rm max} / [1 + (R/R_0)^2]$$
(11)

where $n_{eff}(R)$ is the index distribution, n_{max} Is the maximum index, R_0 is the maximum radius. To realize the gradient index map, the silicon slab is covered by a layer of metamaterial film comprised of a two-dimensional array of nano-rods whose effective medium index can be controlled by varying the nano-rod filling factor. Due to the perfect-imaging feature of MFL, the incident light will propagate through the crossing section and then form its self-image regardless of the mode order, so that all the input modes can be preserved throughout the crossing section. This MFL-based crossing can provide low losses (IL < 0.3 dB) and low crosstalk (XT < -20 dB) for the first two TM modes (i.e., TM₀, TM₁). The footprint is also as small as $18 \times 18 \ \mu\text{m}^2$. Later, another MFL-based three-mode crossing was reported based on the grayscale lithography technology [202]. The MFL-based crossing is considered as a universal and scalable scheme that could work for any higher-order mode since the imaging process is independent from the mode order. Moreover, conjugate imaging of MFL also enables multiple cross-over pathways at a single junction, which allows for a multi-port star-crossing with an enhanced integration density.

In Table 6, we summarize the reported silicon multi-mode crossings. For most of the reported structures, low losses (IL < 0.5 dB), low crosstalk (XT < -20 dB) and a broad bandwidth (BW > 80 nm) can be achieved, whereas the mode capacity is still restricted to two or three modes. Although the MFL-based structures have offered a clear prospect for an arbitrarily large capacity, there is still a lack of experimental demonstrations for a higher capacity (e.g., more than four channels) due to the complex index map. Therefore, the next goal should be developing simple and reliable multi-mode crossings.

Daf	Year	Size (um^2)	Capacity -	IL (dB)		XT (dB)		BW (nm)	
Kel.		512e (µiii)		Sim.	Exp.	Sim.	Exp.	Sim.	Exp.
[197]	2016	30×30	2	0.25~1.7	1.5	<-32	<-18	100	80
[199]	2017	21×21	2	0.3~0.5	1.82	<-30	<-18	100	90
[200]	2018	34×34	3	<1.5	< 0.9	<-22	<-24	60	80
[201]	2018	19×19	2	0.06~0.21	< 0.3	<-30	<-20	100	80
[202]	2018	21×21	3	< 0.5	≈2	≈ -20	≈ -20	400	≈ 40
[204]	2018	$<5 \times 5$	2	< 0.5	<0.6	<-30	<-24	80	60
[176]	2019	8×8	3	0.2~0.59	0.28~0.82	<-30	<-20	80	80
[205]	2019	$< 4 \times 4$	3	$0.24 \sim 0.45$	/	<-27	/	415	/
[198]	2020	$<34 \times 34$	2	< 0.1	0.1~0.2	<-56	<-30	100	75

Table 6. Summary of the reported silicon multi-mode crossings.

IL, insertion loss. CT, crosstalk. BW, working bandwidth. Sim., simulation results. Exp., experimental results.

3.3. Silicon Multi-Mode Splitters

Single-mode power splitting can be easily realized by exploiting Y-junctions [61,62,206], directional couplers [207–209] and MMI couplers [50,210]. However, these approaches cannot be directly employed in the multi-mode regime, because there are two underlying constraints for multi-mode power splitting: first, the splitting ratios (SRs) should be equivalent for all the input modes; second, the mode order should be preserved. The simplest case is a symmetric Y-junction, where the input TE₁ mode will convert to a pair of TE₀ modes in two branches, as shown in Figure 16. Hence, the Y-junction cannot serve as a multi-mode power splitter since the mode order is changed. Recently, a variety of multi-mode splitters have been reported, including ones based on directional couplers [211], adiabatic couplers [212], mode converter-assisted Y-junctions [213] and SWG transflectors [214], as summarized in Figure 17.



Figure 16. The calculated light propagation profiles for a Y-junction when TE_0 (**left panel**) and TE_1 (**right panel**) are launched. The mode order cannot be preserved in the splitting process.



Figure 17. The schematics for different silicon multi-mode splitters based on (**a**) directional coupler [211], (**b**) adiabatic coupler [212], (**c**) mode converter-assisted Y-junction [213], (**d**) subwavelength grating (SWG) transflector [214].

The first silicon multi-mode power splitter was designed based a directional coupler [211], as shown in Figure 17a. The incident modes (i.e., TM_0 , TM_1) can be partially transferred to the adjacent waveguide with evanescent coupling. The problem is that the half-beat lengths are distinct for different mode orders. Thus, one has to carefully choose the structural parameters to ensure that the coupling length satisfies the following equation:

$$L_{c} = (1/2 + p) \cdot L_{\pi,0} = (1/2 + q) \cdot L_{\pi,1}$$
(12)

where p and q are two integers, L_c is the coupling length, $L_{\pi,i}$ is the half-beat length for TM_i . Here, $L_{\pi,i}$ can be obtained by using the super-mode theorem [70]. In this way, both TM_0 and TM_1 modes can be allocated to two waveguides with the same splitting ratio of SR = 50%. For the fabricated device, the insertion losses and crosstalk were measured to be IL < -0.7 dB and XT < -14.3 dB, respectively. The major disadvantage is the narrow bandwidth (BW < 30 nm) since $L_{\pi,i}$ is strongly wavelength dependent. Moreover, this approach is not scalable, because it is difficult to find an optimal parameter for more than two modes. As an improvement, the adiabatic coupler was proposed to enhance the bandwidth and expand the capacity [212]. The input modes are firstly converted to the corresponding super-modes, which are then evenly split by a symmetric Y-junction, as shown in Figure 17b. In theory, this adiabatic coupler-based structure can provide an ultra-broad bandwidth (BW > 165 nm) as well

as an arbitrarily large capacity. The insertion losses and crosstalk are also quite low (IL < 0.12 dB, XT < -18.5 dB). However, for this scheme, the coupling length has to be extremely long (> 800 µm) to meet the adiabatic condition. In [213], the mode converter-assisted Y-junction was proposed to realize a scalable multi-mode splitter with a smaller footprint as well as a broad bandwidth. The input TM_i is firstly converted to the TM_{2i+1} mode as a transition, which is then divided into two beams and reverted to the TM_i mode through a symmetric Y-junction, as shown in Figure 17c. The TM_i-TM_{2i+1} conversion can be achieved for any higher-order mode by bridging two groups of cascaded ADCs. Based on this scheme, the device footprint can be reduced to ≈ 120 µm. The measurement results show low losses (IL < 0.86 dB) and low crosstalk (XT < -15.7 dB). For the aforementioned multi-mode splitters, the splitting ratio is fixed to SR = 50% (i.e., 3-dB power splitting). However, an arbitrary splitting ratio is commonly required for a wide scope of applications, e.g., power distribution [215], power monitoring [210] and box-like filtering [216]. Hence, it is also very important to develop multi-mode splitters with a splitting ratio beyond 50:50.

In [214], an ultra-broadband silicon multimode splitter with an arbitrary splitting ratio was proposed for the first time, as shown in Figure 17d. The structure is a direct crossing with an obliquely embedded SWG that partially reflects the incident modes. The SWG is formed by a one-dimensional array of subwavelength nano-holes that can be collectively regarded as an effective medium transflector. The reflectance can be almost the same for all the input modes (i.e., TE_{0-2}) since the effective indices are quite close when $w_0 >> \lambda/n_s$. More importantly, any desired splitting ratio, ranging from 0% to 100%, can be achieved by simply changing the SWG duty cycle. Additionally, the splitting ratio spectra can be very uniform over an extremely broad bandwidth (BW > 415 nm) covering O-, E-, S-, C-, L- and U-bands. The insertion losses and crosstalk are also quite low (IL < 0.1 dB, XT < -20 dB). In [194], a four-mode power splitter was realized by using a uniform trench as a transflector, whose splitting ratio can also be modified by tuning the trench width.

The reported silicon multi-mode splitters have been summarized in Table 7. Among all these schemes, the SWG transflector is the one with the most potential in terms of scalability, flexibility and overall performance. One obstacle might be the adiabatic tapers required by the direct crossing, as discussed in Section 3.2. As a possible way to proceed, extensive efforts should be made to develop a MDM-compatible mode size converter with a shorter conversion length [217,218], so that a compact and high-performance multi-mode splitter can be realized.

Ref.	Year	Size (µm)	Capacity	SR	IL (dB)		XT (dB)		BW (nm)	
					Sim.	Exp.	Sim.	Exp.	Sim.	Exp.
[211]	2016	15.2	2	0.5	< 0.1	< 0.7	<-17	<-14.3	60	30
[213]	2016	120	2	0.5	0.47	0.86	<-19	-15.7	100	80
[212]	2018	800	3	0.5	< 0.12	/	<-18.5	/	165	/
[219]	2018	2.88	2	0.5	< 0.9	<1.5	<-20	<-20	80	60
[214]	2020	15 *	3	0~1	< 0.1	/	<-20	/	415	/
[220]	2020	<4.5	3	0.5	< 0.9	<1.5	<-19	<-15	40	40
[194]	2020	10 *	4	0~1	/	2.4	/	/	/	75

Table 7. Summary of the reported silicon multi-mode splitters.

SR, splitting ratio. IL, insertion loss. CT, crosstalk. BW, working bandwidth. Sim., simulation results. Exp., experimental results. * Taper lengths are not included.

4. Inverse Design in Multi-Mode Photonics

A variety of building blocks need to be assembled to construct a practical MDM system with full functionalities, as discussed in Section 1. However, the design methodologies and working principles are various for different types of mode-handling devices (see Sections 2 and 3), which hinder the standardization of MDM modules. Furthermore, most of the reported MDM components are optimized by hand-tuning a small collection of parameters, so designers are not aware of how close a particular device comes to the performance limits, especially when a great number of modes are involved.

Photonic inverse design uses computational algorithms to discover an optimal set of parameters $\varepsilon(x,y)$ as incident/scattering responses are given [221,222], as shown in the upper panel of Figure 18. Based on this method, different types of MDM components can be designed under the same framework, because such target-first optimization requires no prior knowledge or user intervention. A major obstacle is the tremendous computational cost caused by the full-space parameter searching. In recent years, various algorithms have been developed to solve this problem, e.g., genetic evolution [223], the level-set method [224], topological optimization [225], the adjoint method [226] and direct-binary search (DBS) [227,228]. For example, in 2016, L.F. Frellsen et al. reported the first experimental demonstration of an inverse-designed three-channel mode (de)multiplexer [84]. Low losses and low crosstalk were measured (IL < 1.7 dB, XT < -14 dB). Remarkably, this inverse-designed structure has an ultra-compact footprint ($\approx 5 \times 6 \ \mu m^2$) much smaller than any previously reported ones.



Figure 18. Upper panel: the schematic for photonic inverse-design. Lower panel: the schematic for inverse-designed mode (de)multiplexer [85], multi-mode bend [175], multi-mode crossing [204] and multi-mode splitter [220].

Generally, inverse-designed nanophotonics can be "analog" or "digital". The analog nanophotonic devices have free-form geometries with continuous boundaries. However, the analog structures usually have an irregular feature size over the pattern region, so one has to redefine the pattern parameters to compensate for random errors induced by line-width broadening [229] and lag effect [130,230]. On the other hand, the digital nanophotonic devices are formed by a series of identical pixels, each with a regular shape (e.g., circle or square), so the fabrication errors can be easily predicted according to pre-treatment results. Therefore, by adopting a digitized configuration, the inverse design could be more reliable and fabrication-friendly. In the lower panel of Figure 18, we have summarized the reported "digital" MDM components, including mode (de)multiplexers [85], multi-mode bends [175,177], multi-mode crossings [204] and multi-mode splitters [219,220]. The working performances are summarized in Table 1, Table 5, Table 6, Table 7. These reported devices all exhibit ultra-small footprints (<10 μ m), which is helpful for dense integration. Moreover, it can be seen that all these mode-handling devices share a similar template, leading to feasible MDM systems based on a standardized component library. For example, in [176], an arbitrarily routed multi-mode circuit with a bit rate of 112 Gbit/s was demonstrated where several different kinds of inverse-designed MDM components were integrated on a single chip. Nevertheless, it is still quite time-consuming to carry out this optimization for a large number of modes, even with graphical processing unit (GPU) accelerations [231], so advanced algorithms need to be developed to further enhance the optimization efficiency.

5. Reconfigurable Multi-Mode Photonics

Reconfigurability is a very desirable attribute in MDM systems. A reconfigurable MDM is developed to select any desired mode channels and deploy them at will. This allows for a dynamic

and flexible MDM network where carriers can be optimally utilized. For single-mode photonics, there are two main streams of reconfigurable devices, i.e., non-blocking switches [201,202,232–236] and reconfigurable optical add-drop multiplexers (ROADM) [237–239]. The counterparts in multi-mode photonics are mode switches [240–249] and mode ROADM [250,251], as summarized in Figure 19.



Figure 19. The configurations for (**a**) mode switch [245] and (**b**) mode reconfigurable optical add-drop multiplexers (ROADM) [250]. The insets show the mapping relation between signals and modes. Here, a four-channel MDM system is illustrated as an example.

The mode switches can re-allocate the signal mode relation directly in the optical realm without add/drop operations. The simplest case is a mode exchanger that swaps two-channel signals carried by TE_0 and TE_1 [240]. The proposed structure consists of two symmetric Y-junctions with a phase shifter in between. The controllable TE_0 – TE_1 exchange can be achieved by tuning the phase difference between two arms. The measured extinction ratio is as large as $ER \approx 24 \text{ dB}$ as TE_0 and TE_1 are switched. Such mode exchange can also be realized by applying some analogous schemes, such as ones based on adiabatic couplers [241], MMIs [242,243] and long-period gratings [244]. However, all these structures can only work for a two-channel MDM. In [245], a general architecture was proposed for scalable mode switches, as illustrated in Figure 19a. For a mode switch with four channels, the inputted TE_{0-3} modes are firstly demultiplexed into four waveguide channels with TE₀, which are then arbitrarily routed by a non-blocking single-mode switch (with Benës or Spanke-Benës fabrics) and reverted to TE_{0-3} modes by a mode multiplexer. Generally, the N-mode switch can be easily obtained by cascading an N-channel mode demultiplexer, an N × N non-blocking switch and an N-channel mode multiplexer. Furthermore, by using a MN × MN fabric, the modified mode switch is also capable of arbitrarily distributing M × N modes among M multi-mode waveguides. The mode switching is also achievable for the WDM/MDM or PDM/MDM hybrid systems by exploiting tunable MRRs [246–248] or polarization-selective switches [249].

The mode ROADM can add/drop signals carried by any desired mode channels. This functionality allows light paths to be set up and taken down dynamically as needed in the MDM network. In 2015, B. Stern et al. reported an asymmetric-MRR-based structure that can select and extract a single WDM/MDM hybrid signal from the multi-mode bus waveguide [252]. However, in the strict sense, this design is not a mode ROADM since it is unable to upload carriers. To the best of our knowledge, the first mode ROADM was reported in [250]. The device consists of two four-channel mode (de)multiplexers and four parallel Mach–Zehnder interferometer (MZI) switches, as shown in Figure 19b. The incident TE_{0-3} modes are firstly transferred to different waveguide channels with TE_0 . When the switches are off, the hitless signals will propagate through. A mode demultiplexer is then utilized to restore the higher-order modes. On the other hand, when the switches are on, the MDM

signals can be added and dropped at different ports of MZI. The experimental results show low losses (IL $\approx 1 \sim 5$ dB) and high extinction ratios (ER $\approx 15 \sim 20$ dB) over a 30-nm wavelength band. Based a similar scheme, the authors also reported a WDM/MDM-compatible ROADM where MZI switches are

replaced by tunable MRRs [251]. A total link capacity of 60 Gbit/s was demonstrated. From the above discussions, the multi-mode switching processes are actually operated in the single-mode realm, so the reconfigurable multi-mode devices can be easily constructed by assembling mode (de)multiplexers with single-mode switches. Thus, extensive efforts still need to be made in terms of improving mode (de)multiplexers (with lower IL and XT) and single-mode switches (with lower IL and higher ER) to obtain mode switches/ROADM with better performances.

6. Conclusions and Perspectives

In summary, we have reviewed the recent progresses on silicon integrated nanophotonic devices for on-chip multi-mode interconnects. In the first section, we reviewed high-dimensional (de)multiplexers, including mode (de)multiplexers, hybrid (de)multiplexers and DPWA-based MDMs. Mode (de)multiplexers were successfully developed based on cascaded ADCs with low losses and low crosstalk, whose mode capacity can be expanded further by introducing a hybrid scheme involving WDMs, PDMs or DPWAs. In the second section, a review of multi-mode routing devices was carried out, including multi-mode bends, multi-mode crossings and multi-mode splitters. Low losses, low crosstalk and compact footprints have all been proven for these devices, enabling arbitrarily routed MDM circuits and complex multi-mode networks. In the third section, we gave a brief review of the inverse design method for multi-mode photonic devices. Based on this method, the component library can be standardized for MDMs. In the fourth section, we reviewed reconfigurable MDM devices, including mode switches and mode ROAMD. The mode channels can be dynamically deployed by using these devices, leading to an efficient and flexible MDM network.

So far, silicon MDMs have been applied in actual communication systems, especially for short-reach optical links, where on-chip MDM devices are employed to excite higher-order modes (e.g., LP_{01} , LP_{11}) in few-mode fibers [253–255] or multi-core fibers [256,257] to boost their capacity. However, the practical applications of monolithic on-chip communications are still limited. Several key improvements would enable the widespread use of practical on-chip MDM interconnects. The mode (de)multiplexers and multi-mode routing devices are cornerstones in the MDM system, so, first and foremost, we must improve the performance of these basic components, especially when a larger capacity is desired. There might be two possible ways to proceed. One approach is to adopt a hybridized scheme involving all the three dimensions, i.e., wavelengths, polarizations and modes, as proposed in Section 2.2. Moreover, the inverse design method appears poised to reshape the landscape of multi-mode photonics due to its ability to explore the full parameter space, which could enable mode manipulation at a higher level of freedom. Another emerging trend lies in reconfigurable multi-mode photonics. As discussed in Section 5, the mode switching processes always happen in the single-mode realm; as a result, the multi-mode reconfigurable devices are actually combinations of mode (de)multiplexers and single-mode switches, leading to quite a large footprint (a few millimeters). The device size could be effectively shrunk if higher-order modes can be directly switched without demultiplexing. Phase-change material (PCM) could potentially realize such direct switching since it can provide an extremely large index variation range [258–262]. Finally, it would be both interesting and impactful to build practical on-chip interconnects that fully integrate all the required components (e.g., LDs, PDS, MDMs) with micro-processors. To achieve this, Si-III/V hybrid integration technology can be exploited to combine silicon MDM devices with other high-performance active components [263–267]. In conclusion, this novel silicon MDM technology has significantly motivated high-capacity optical communications, paving the way for the future of on-chip interconnects. We believe that multi-mode photonics will become more and more important in a wide range of applications.

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