

Article

# Importance of Remotely-Sensed Vegetation Variables for Predicting the Spatial Distribution of African Citrus Triozid (*Trioza erytreae*) in Kenya

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Received: 27 August 2018; Accepted: 27 October 2018; Published: 3 November 2018



**Abstract:** Citrus is considered one of the most important fruit crops globally due to its contribution to food and nutritional security. However, the production of citrus has recently been in decline due to many biological, environmental, and socio-economic constraints. Amongst the biological ones, pests and diseases play a major role in threatening citrus quantity and quality. The most damaging disease in Kenya, is the African citrus greening disease (ACGD) or Huanglongbing (HLB) which is transmitted by the African citrus trioqid (ACT), *Trioza erytreae*. HLB in Kenya is reported to have had the greatest impact on citrus production in the highlands, causing yield losses of 25% to 100%. This study aimed at predicting the occurrence of ACT using an ecological habitat suitability modeling approach. Specifically, we tested the contribution of vegetation phenological variables derived from remotely-sensed (RS) data combined with bio-climatic and topographical variables (BCL) to accurately predict the distribution of ACT in citrus-growing areas in Kenya. A MaxEnt (maximum entropy) suitability modeling approach was used on ACT presence-only data. Forty-seven (47) ACT observations were collected while 23 BCL and 12 RS covariates were used as predictor variables in the MaxEnt modeling. The BCL variables were extracted from the WorldClim data set, while the RS variables were predicted from vegetation phenological time-series data (spanning the years 2014–2016) and annually-summed land surface temperature (LST) metrics (2014–2016). We developed two MaxEnt models; one including both the BCL and the RS variables (BCL-RS) and another with only the BCL variables. Further, we tested the relationship between ACT habitat suitability and the surrounding land use/land cover (LULC) proportions using a random forest regression model. The results showed that the combined BCL-RS model predicted the distribution and habitat suitability for ACT better than the BCL-only model. The overall accuracy for the BCL-RS model result was 92% (true skills statistic: TSS = 0.83), whereas the BCL-only model had an accuracy of 85% (TSS = 0.57). Also, the results revealed that the proportion of shrub cover surrounding citrus orchards positively influenced the suitability probability of the ACT. These results provide a resourceful tool for precise, timely, and site-specific implementation of ACGD control strategies.

**Keywords:** African citrus trioqid; citrus greening disease; MaxEnt; phenological metrics; land use/cover

## 1. Introduction

Citrus is considered one of the most important fruit crops in the world due to its contribution to food and nutritional security [1]. Also, citrus is the top-ranked fruit crop with regard to its international trade value [2]. The commercially important citrus species are sweet oranges (*Citrus sinensis*), lemons (*Citrus limon*), limes (*Citrus aurantifolia*), grapefruit (*Citrus paradisi*), and tangerines (*Citrus reticulata*). Globally, sweet oranges represent approximately 70% of citrus production. In 2016, the global total production of sweet oranges was about 73 million tons [3]. In Kenya, citrus is a valuable fruit crop used mainly for domestic consumption as a fresh produce with only a small quantity being processed into juice and jams [4]. Citrus provides some minerals and vitamins like vitamin C, carotenoids, and polyphenols that are essential for human health. In terms of the area of production, citrus (mainly oranges) ranks third (7268 ha) after bananas (63,299 ha) and mangoes (54,332 ha) in the country [5].

Citrus plants can prosper in a wide range of environmental conditions from tropical to subtropical climatic conditions [6]. However, the best citrus production conditions are found in subtropical climate zones in elevations ranging from sea level up to 2100 m above mean sea level (m.a.s.l.), with an optimal growth temperature ranging from 20 °C to 30 °C. In Kenya, citrus fruits' quantity and quality have been considerably declining. For instance, oranges yields at 11.73 ton ha<sup>-1</sup> are far below (23% less) the global mean yield of 18.45 ton ha<sup>-1</sup> [7,8]. Two of the major production constraints that hinder citrus production in Kenya are insect pests and diseases, among which the African citrus triozid (ACT), *Trioxa erytrae*, plays a key role [9]. Direct feeding by ACT results in leaf curling and, furthermore, causes deposition of honeydews on infested plants [10]. In Africa, ACT is known for transmission of the devastating phloem-limited bacterium *Candidatus Liberibacter africanus* (CLaf), responsible for the African citrus greening disease (ACGD) or Huanglongbing (HLB) [11]. In addition to ACT, HLB is also transmitted by the Asian citrus psyllid (ACP) (*Diaphorina citri*), which is the primary vector in Asia [12,13] but was also recently discovered in eastern Africa [14]. These two psyllids are distributed according to their temperature requirements, with ACT being highly temperature sensitive and thus restricted to cooler elevated areas [15,16]. The common symptoms of ACGD are mottling and yellowing of the leaves, reduced tree foliage which results in small and bitter-tasting fruits, and the eventual death of severely infected citrus trees [17]. In Kenya, ACGD is reported to have had the greatest impact on citrus production in the highlands, causing yield losses of 25% to 100% [18]. The yield of affected trees is not only considerably reduced by continuous fruit drop, dieback, and tree stunting, but also by the poor quality of fruits that remain on the trees which are inedible.

Over the years, different approaches have been used for implementing various ACGD preventive and control measures [19]. This includes strict regulations of nurseries through a registered disease-free certification scheme to prevent the spread of ACGD and its vectors [20]. Little is known on the spatial distribution of the disease vectors, yet such information could greatly assist in developing precise geo- and time-referenced vector distribution maps. Such maps can be useful in monitoring the spatial spread and suitable areas for the vectors, enabling for a more targeted implementation of interventions. Vector-transmitted disease propagation follows vector ecological principles as an indirect explanation of disease cycles, outbreaks, and prevalence [21]. One of the most frequently used approaches for producing vector distribution maps is the ecological niche (EN) modeling approach [22]. EN models statistically link spatial variabilities in a set of predictor variables to the distribution of species of interest that can be a plant disease vector like ACT [23,24]. The dependence of plant disease propagation on spatio-temporal environmental niche factors of the disease vector has recently received considerable attention [25]. Yet, studies focusing on the ways in which geographical environmental factors affect the habitat suitability and host-vector dynamics are still limited. In addition, there is a need for studies that employ a multi-source variable (e.g., vegetation phenology and climate) approach to predict the spatial distribution of plant disease vectors.

Models have been developed to provide information about diseases and the distribution of associated environmental variables that are used as proxies for habitat suitability. The best known EN models used in insect-based distribution modeling include Generalized Linear Models (GLM),

Generalized Additive Models (GAM), Genetic Algorithm for Rule-Set Production (GARP), Boosted Regression Trees (BRT), and Maximum Entropy (MaxEnt) [26]. Studies have compared the performance of several EN modeling algorithms to predict the distribution of different species and found that MaxEnt was the best-performing model using presence-only data [27]. In addition, MaxEnt is the most utilized EN model for estimating the distribution of plant insect pests like stink bugs (*Halyomorpha halys* spp.) [28], large pine weevil (*Hylobius abietis*), and horse-chestnut leaf miner (*Cameraria ohridella*) [29], boreal forest insect pests [30], fruit flies [31], and disease vector ticks (*Ixodes ricinus*) [32].

For HLB, a number of studies employed mathematical, and geostatistical simulation, life table, and conceptual modeling routines [33–35], to study the distribution of ACP using environmental variables as predictors (i.e., temperature and rainfall) in regard to the biology of the vector (e.g., developmental stages and their populations) and host plant interactions (e.g., number of susceptible or infectious orange trees). These studies demonstrated the possibility of estimating the distribution, progression and optimal temperature ranges for ACP in countries like the USA, Mexico, Brazil, Vietnam, and Australia. In Africa, Shimwela et al. [36] and Narouei-Khandan et al. [37] employed two correlative MaxEnt and support vector machine modeling approaches to map the potential distribution of ACP using global-scale environmental predictors. These two studies reported that Eastern African countries like Kenya and Tanzania would be highly suitable for the psyllid. To the best of our knowledge, no other study has employed an EN modeling approach to predict the distribution of ACP vectors in Africa.

Yet, there is a need for an explicit ACT distribution mapping routine in countries such as Kenya, where the transmission of ACP is mainly due to this vector. Moreover, previous studies looked at the relevance and influence of environmental variables in predicting the distribution of ACP vectors but did not consider the expected relevance of vegetation patterns and phenology, resulting through interactions between climatic, topographic, and vegetation patterns at a landscape scale, which can considerably improve the performance of EN models like MaxEnt [30]. Moreover, vegetation patterns and phenology play a key role in influencing vector-host-pathogen transmission, including vector distribution, abundance, and diversity [38]. These vegetation-related patterns and phenological variables can only be extracted from temporal remotely-sensed datasets. When used in EN models, the remotely-sensed vegetation pattern and phenological variables are useful additional predictors for the spatial distribution of pests and diseases since EN models rely on the correlation between a habitat's characteristics and the biophysical properties of the studied pest and disease [39].

Further, much research has focused on the biology of ACT and its dispersal [40]; however, little is known regarding how land use/land cover (LULC) features influence the habitat suitability of the vector and its dispersal. However, remotely-sensed datasets from different systems have been widely used for the identification and separation of citrus orchards from other LULC types for appropriate policy making and citrus production forecasting [41–43]. More efforts concerning understanding the influence of the landscape on the survival of pests and diseases like ACT using remotely-sensed variables are crucial. For instance, the context of the landscape has been reported to affect the population of crop insects directly, or more frequently, indirectly, through its effects on the physical environment around the host plants [44]. For instance, landscape heterogeneity has been reported to influence the direction and distance moved by a dispersed pest and pathogens, in addition to the infestation rate [45]. For example, Rizzo et al. [46] reported that the proximity to the forest edge was associated with an increase in the infestation of sudden oak death disease in California. Avellino et al. [47] tested the relationship between the landscape context and three highly differentiated focal coffee pests and pathogens. They found a positive relationship between the studied coffee pest and disease incidences and the proportion of different LULC classes at different radii around coffee sample plots. Thies et al. [48] studied the correlation between the local proportion of destroyed oilseed canola buds and the characteristics of landscape context. They showed that an increase in the landscape complexity was associated with a decrease in damage caused to oilseed canola by *Meligethes aeneus*. All these studies alluded to the fact that the surrounding vegetation provides a refuge for the vectors during periods of time when the conditions are unfavorable for the spreading of

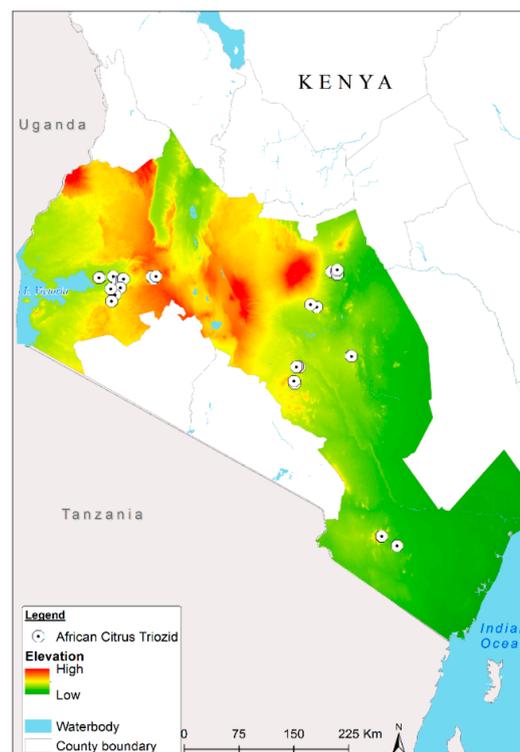
the disease. Despite this strong influence that the landscape properties have on the spread of pests and diseases, no research has explored the relationship between ACT habitat suitability with the surrounding landscape composition for a better understanding of the ecology and spread of ACGD.

The objectives of this study were, (i) to explore the potential and contribution of vegetation phenological variables and Land Surface Temperature (LST) derived from remotely-sensed data combined with environmental variables to predict the distribution and habitat suitability for ACT at a test site in Kenya using a MaxEnt model and, (ii) to test the effect of the surrounding landscape context on the habitat suitability for ACT. This was achieved by relating a set of bio-climatic and topographic environmental (BCL) variables and remotely-sensed (RS) variables to ACT presence-only distributions over a region-specific, i.e., representative agro-ecological gradient.

## 2. Methods

### 2.1. Study Area

The study site consists of 35 administrative counties in three main agro-ecological zones in Kenya lying in low-, mid-, and high- elevation zones, see Figure 1. The study area covers parts of the Coastal, Eastern, Central, and Western regions of Kenya. The Central and Western regions exhibit cooler and wetter climatic conditions which are particularly favorable for citrus growing. The two regions experience a bi-modal rainfall distribution with the major crops being maize and beans, which in most cases are interspersed with mangoes and citrus trees, in addition to tea and coffee. Generally, citrus growing across the entire country is commonly practiced in small orchards and backyards, with only a few big citrus plantations in Kenya.



**Figure 1.** Study area (major citrus-growing regions) in Kenya where the African citrus trioqid (*Trioza erytreae*) presence data were collected.

In the low-lying coastal region with higher humidity levels, farmers cultivate a wide range of food as well as tree crops like coconut palms, mango, citrus, and pawpaw. The major citrus-growing areas in the coastal region are Kwale Kilifi and Taita Taveta [49]. The Eastern region is located in the hot and dry

semi-arid savannah biome and has similar cropping patterns as the coastal region. It is dominated by steep slopes with elevations ranging from 500 to 1200 m above mean sea level (m. a. m. s. l.).

## 2.2. ACT Occurrence Data

Field surveys were conducted along a clearly defined transect within the citrus-growing regions from the lowlands to the highlands in Kenya. In general, horticultural farming in Kenya is mainly carried out by small-scale producers because of the scarcity of productive land for horticultural production. Thus, citrus is grown in a wide range of elevations ranging from the lowlands to the highlands of Kenya [50]. The study area was divided into three elevation zones: Low (0–500 m. a. m. s. l.), middle (501–1000 m. a. m. s. l.), and high (>1000 m. a. m. s. l.). Each elevation zone was regarded as a stratum; therefore, we followed a stratified random sampling protocol to collect the ACT presence data. In each stratum (i.e., elevation zone), we randomly selected citrus orchards and nurseries, including backyards of small farms with a minimum orchard-to-orchard distance of 2 km for sampling. At least 30 citrus orchards in each stratum were sampled and with the aid of a hand-held Global Positioning System (GPS) device with a positional accuracy of  $\pm 2$  m, the location of the citrus orchard, nursery, or backyard farm where ACT was present was recorded as an occurrence point. Specifically, for sample citrus orchard and backyard farms  $\leq 0.5$  ha, all citrus trees were inspected for ACT symptoms, while in orchards  $> 0.5$  ha only 20 randomly selected trees were sampled in each orchard by moving across the orchard in a W-pattern [36]. Presence-only observations ( $n = 47$ ) were collected across the study area, see Figure 1, between January 2015 and September 2016. This number of presence-only observations is regarded as acceptable in a MaxEnt modeling routine [51,52]. A subset of the ACT presence-only observations was used for training the MaxEnt model (75% of the sample observations), and 25% of the sample observations were used for model evaluation [53]. We also collected information on the representative sample vegetation cover and type surrounding citrus orchards and backyard farms where the ACT was present using geotagged photographs that were taken from the main four cardinal directions of the orchards for further inspection on how the landscape context could affect the presence of ACT.

## 2.3. Predictor Variables

We considered 35 variables as potential predictors for estimating ACT distribution and habitat suitability. The variables were categorized into BCL and RS variables, see Table 1. For the BCL variables, we selected variables based on the ecological requirements of the vector as reported in previous studies: temperature, humidity, and elevation [36]. Temperature and precipitation were represented by 19 “bioclimatic” variables, see Table 1, available from the WorldClim database ([www.worldclim.org](http://www.worldclim.org)) [54]. WorldClim projects current climatic conditions at 1-km spatial resolutions based on observations gathered from different weather stations between 1950 and 2000; the point datasets are interpolated using a thin plate smoothing spline algorithm to create a seamless raster dataset [54]. We also used topographical variables related to the potential ACGD vectors’ habitat. These included elevation, slope, hill shade, and aspect in degrees, see Table 1. Hill shade was included as a proxy for relative solar radiation load that accounts for the effect of topographic shading [55]. We observed in the field that the majority of ACT presence points were on the windward side for mountainous regions as opposed to the leeward side; hence, we included hill shade as a predictor variable in our ACT distribution model. The topographical variables were extracted from a void-filled 90 m digital elevation model (DEM) data set from the Shuttle Radar Topographical Mission (SRTM) [56]. Using the Environment for Visualizing Images (ENVI) version 4.8 (Exelis Visual Information Solutions, Boulder, CO, USA), both bio-climatic and topographical variables were resampled using a bilinear interpolation method to fit the 250m pixel size of the remotely-sensing variables [57].

RS variables on vegetation phenological metrics and vegetation productivity dynamics were derived from a Moderate Resolution Imaging Spectroradiometer (MODIS) Enhanced Vegetation Index (EVI) time-series data at a 250-m spatial resolution. MODIS products such as Normalized Difference

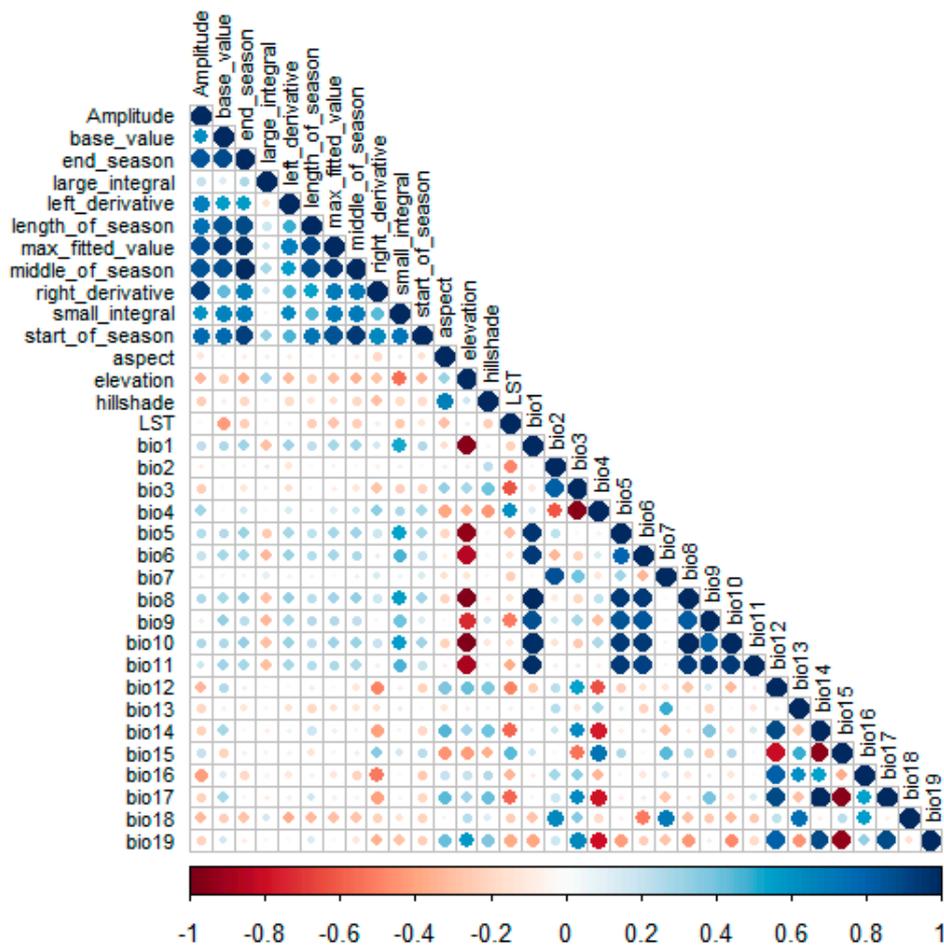
Vegetation Index (NDVI) and EVI are the most widely used indices for monitoring of the vegetation phenological pattern [58]. Matsushita et al [59] pointed out that NDVI is easily affected by soil background and low vegetation coverage and easily saturated in high vegetation coverage. On the other hand, EVI minimizes the noise of soil background and adjusts atmospheric aerosol interference, thus improving the sensitivity of mimicking densely vegetated sites as compared to NDVI [60–62]. In the present study, MODIS 16-day EVI composites for the years 2014 to 2016 from the National Aeronautics and Space Administration (NASA) Land Processes Distributed Active Archive Center (LP DAAC—<https://lpdaac.usgs.gov/>) were downloaded and preprocessed using the MODISTools package in R [63]. MODISTools provides a function for mosaicking and sub-setting the downloaded data to a selected geographical extent. Then, we calculated 11 vegetation phenological metrics, see Table 1, using the TIMESAT software [64]. Namely, we calculated (1) start of the season (start of season) which is the time of initial vegetation green up, (2) end of the season (end of season) representing time of initial vegetation senescence, (3) the length of growing season from green up to senescence (length of season), (4) base level, which was calculated by averaging the left and right minimum values (base value) that represent the baseline of the seasonal phenology curve, (5) time for the middle of the growing season (mid of season), (6) the highest EVI value of the season (max fitted value), (7) seasonal amplitude calculated as the difference between the peak EVI value and the average of the left and right minimum values corresponding to the amount of EVI change (amplitude), (8) the rate of vegetation green up (left derivative), (9) the rate of vegetation senescence (right derivative), (10) proxy for the relative amount of vegetation biomass without regarding the minimum EVI values (large integral), and (11) the proxy for the relative amount of vegetation biomass while regarding the minimum EVI values (small integral). All 11 vegetation phenological metrics [64–66] were calculated for the two growing seasons within each year. TIMESAT extracts vegetation phenological variables by fitting a local function to the time-series datasets [67]. We fitted the Savitzky-Golay smoothing model function that replaces the data value by values in a window using a second-order polynomial function with optimum smoothing parameters [64,68]. The Savitzky-Golay function reduces the effects of residual signals and smooths the time-series EVI dataset to a degree determined by the size of the smoothing window and reduces the noise caused primarily by cloud contamination and atmospheric variability [67]. The start and end of season threshold parameters for the smoothing function were set at 20%, as suggested by Jonsson and Eklundh [64], to optimize the error that could be caused by varying start and end of season dates in different locations across the study area [69]. Only variables for the first season were used in this study since data from the second season were not consistent throughout all the years across the study area [69]. Our study area cuts across different climatic zones in Kenya with a varying number of rainy seasons; hence, some of our sample sites commonly experience unimodal rainfall (one rainy season), while others have bi-modal rainfall (two rainy seasons) in a calendar year. This variability in the rainy seasons could have caused the variation and inconsistency in the vegetation phenological variable across the entire study area during the second rainy season. In addition to the vegetation phenological metrics, LST has proved to have a major influence on the spread and development of pests and diseases [70]. LST variables extracted from time-series MODIS data for the years 2014 to 2016 were averaged for each year and included in the set of predictor variables. MODIS LST has a high spatial characteristic that enables the capture of the spatial variability of land surface fluxes within a finer scale as opposed to point observations taken on the ground.

**Table 1.** Predictor variables used for modeling the ecological niche for the African citrus trioizid (*Trioza erythrae*). The variables were divided into two sets; environmental (bio-climatic and topographical) and remote-sensing variables. Bold text refers to variables which were selected through a multi-collinearity test using the Findcorrelation function in the caret package in the R software and finally used in the MaxEnt model.

Data Source	Category	Variables Description	Abbreviations	Units
WorldClim	Bioclimatic	Annual mean temperature	Bio 1	°C
		<b>Mean diurnal range (mean of monthly (max temp, min temp))</b>	<b>Bio 2</b>	°C
		Isothermality (Bio 2/Bio 7) (×100)	Bio 3	°C
		Temperature seasonality (standard deviation × 100)	Bio 4	°C
		Maximum temperature of warmest month	Bio 5	°C
		Minimum temperature of coldest month	Bio 6	°C
		Temperature annual range (Bio 5-Bio 6)	Bio 7	°C
		Mean temperature of wettest quarter	Bio 8	°C
		Mean temperature of driest quarter	Bio 9	°C
		Mean temperature of warmest quarter	Bio 11	°C
		Mean temperature of coldest quarter	Bio 11	°C
		Annual precipitation	Bio 12	mm
		<b>Precipitation of wettest month</b>	<b>Bio 13</b>	<b>mm</b>
		Precipitation of driest month	Bio 14	mm
		Precipitation seasonality (coefficient of variation)	Bio 15	mm
		<b>Precipitation of wettest quarter</b>	<b>Bio 16</b>	<b>mm</b>
		Precipitation of driest quarter	Bio 17	mm
		<b>Precipitation of warmest quarter</b>	<b>Bio 18</b>	<b>mm</b>
		Precipitation of coldest quarter	Bio19	mm
SRTM	Topographic	<b>Ground height</b>	<b>Elevation</b>	<b>m</b>
		<b>Sloping direction</b>	<b>Aspect</b>	<b>degree</b>
		Steepness of the ground	Slope	degree
MODIS EVI	Remotely sensed	Shading effect	Hill shade	n/a
		Time for the start of the season	Start of season	decades
		Time for the end of season	End of season	decades
		<b>Length of season from start to end</b>	<b>Length of season</b>	<b>decades</b>
		Mid of the season	Mid of season	decades
		Difference between maximum and base level	Amplitude	n/a
		Average minimum EVI value	Base value	n/a
		Maximum fitted value	Max fitted value	n/a
		<b>Rate of increase at the beginning of season</b>	<b>Left derivative</b>	<b>%</b>
		<b>Rate of decrease at the end of season</b>	<b>Right derivative</b>	<b>%</b>
		<b>Large seasonal integral</b>	<b>Large integral</b>	<b>n/a</b>
<b>Small seasonal integral</b>	<b>Small integral</b>	<b>n/a</b>		
MODIS		<b>Land surface temperature</b>	<b>LST</b>	°C

#### 2.4. Predictor Variable Selection

To examine the expected multi-collinearity among the predictor variables, we performed a Pearson correlation test, see Figure 2, between all the predictor variables shown in Table 1. Furthermore, the “Findcorrelation” function in the Caret package in R was used to eliminate highly correlated variables using the mean absolute error score. A correlation coefficient of  $|r| > 0.7$  was set as a collinearity indicator for variables that would severely affect our model [17]. Variables that met this criterion were eliminated from the analysis, and only the uncorrelated predictor variables were used in the MaxEnt model.



**Figure 2.** Collinearity matrix for predictor variables. Darker shades of blue and red colors indicate high variable collinearity while light shades indicate low collinearity between variables.

### 2.5. EN Modeling

A MaxEnt model algorithm [71] was used to predict the distribution and likely suitable sites for ACT. MaxEnt is a presence background machine-learning approach that estimates species' distribution that has maximum entropy subject to a set of constraints based upon a user's knowledge of the environmental conditions at known occurrence sites [27]. Like most maximum-likelihood estimation methods, the MaxEnt algorithm adopts a uniform distribution and performs several iterations in which the weights related to the environmental variables are adjusted to maximize the average probability of point localities. These weights are then used to compute the distribution over the entire geographical space [72].

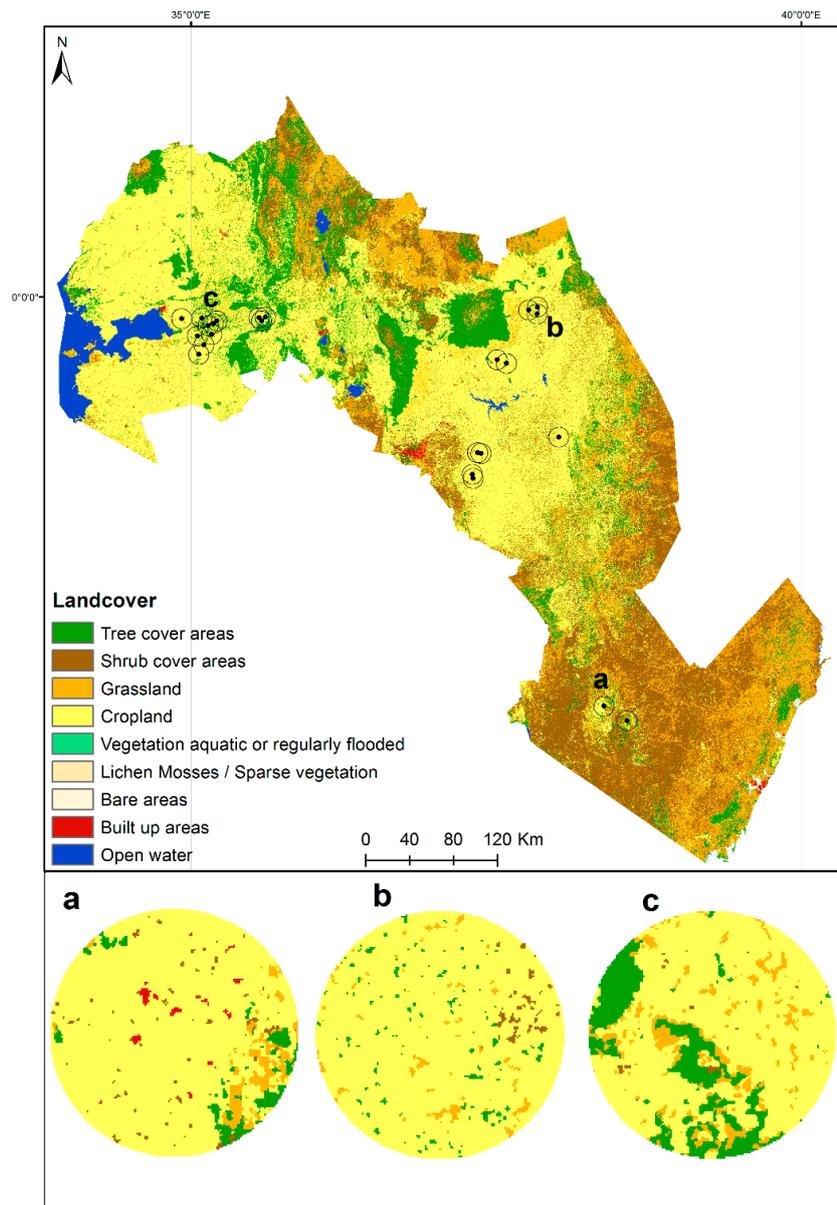
To minimize overfitting in the MaxEnt model, we implemented a regularization method to penalize the model in proportion to the coefficient magnitude [73]. Further, we ran MaxEnt models using the default variable responses setting and a logistic output format which results in the ACT distribution suitability prediction ranging from 0 (less suitable) to 1 (highly suitable). However, a default regularization multiplier was doubled to reduce the chance of under or over prediction [74]. In addition, we used the 10th percentile training presence threshold which predicts the 10% most extreme presence observations as absent to eliminate 'outliers' from the final model [75]. To study the effects of the vegetation phenology and dynamics for predicting ACT distribution, we performed two MaxEnt models, one included the environmental variables only (BCL model) and the other included both the environmental and remote-sensing variables (BCL-RS model).

## 2.6. EN Models Validation

Commonly, the accuracy of the MaxEnt distribution suitability maps is assessed using conventional accuracy measures such as the area under the curve (AUC) and chi-squared ( $\chi^2$ ) statistics. However, these accuracy statistics are somehow biased and highly sensitive to the proportional extent of the predicted presence observations [76], as a result of an overestimation of the pseudoabsence samples. Hence, in this study, we employed more reliable and adequate measures to evaluate the overall MaxEnt model performance. Specifically, we used true skill statistic (TSS) and Cohen's kappa coefficient ( $K_{\text{hat}}$ ) to evaluate the accuracy of the ACT distribution suitability maps [77]. As compared to TSS, kappa inherently depends on prevalence. However, an ideal measure of model performance should not be affected by prevalence but combine sensitivity and specificity [78]. Thus, TSS combines both sensitivity and specificity to account for both omission and commission errors and is not affected by prevalence and the size of the validation set and, therefore, is the best parameter to measure model performance. Both TSS and  $K_{\text{hat}}$  range from  $-1$  to  $+1$ , where  $+1$  indicates perfect agreement between the observed and predicted ACT observations, whereas values  $<0$  indicate no agreement or that most of the predicted ACT observations were produced by chance [79]. In addition, we used a Jackknife procedure to assess the relative importance of each individual predictor variable to the ACT distribution suitability model [80]. To test the null hypothesis that there was no statistical ( $p \leq 0.05$ ) difference between the predictions of the BCL and the BCL-RS MaxEnt models, a two-sample *t*-test was performed. Herein, using 'ArcGIS create random points' tool, we generated 500 random sample points throughout the study area and compared their predictive power for each of the two models (i.e., BCL and BCL-RS).

## 2.7. Landscape Context Calculation

To describe the landscape context, we used a LULC map at a 20-m spatial resolution over the study area based on one year of Sentinel-2A observations ranging from December 2015 to December 2016 developed and validated by Climate Change Initiative (CCI) Land Cover (LC) team [81]. Since ACT is likely to spread locally up to a distance of 1500 m by natural dispersal [82], we extracted the LULC proportion within a 1500 m radius buffer from the center for each of the 24 ACT occurrence points collected from the field which were not overlapped within each buffer, see Figure 3. The proportions of the four major LULC classes (tree cover, shrubs cover, grassland, and cropland) within each buffer were calculated. We hypothesize that these four major LULC classes could influence the occurrence of ACT within a landscape scale. The same buffers were also used to extract the corresponding average habitat suitability scores from the suitability map generated by the MaxEnt algorithm. Random forest (RF) regression [83,84] analysis was performed to determine the most relevant LULC classes for the ACT habitat suitability scores using the RF variable importance by-product. An RF regression model was performed using the default settings suggested by Breiman [83], and the importance of the LULC classes was assessed using the RF mean decrease in accuracy (%) metric.



**Figure 3.** A 20-m spatial resolution land use/land cover map for the study area generated by the Climate Change Initiative (CCI) Land Cover (LC) team. Using yearly Sentinel-2 observations. (a–c) represent zoomed buffers of 1500 m radius each around certain representative African citrus trioza (ACT) occurrence points.

### 3. Results

#### 3.1. EN Models

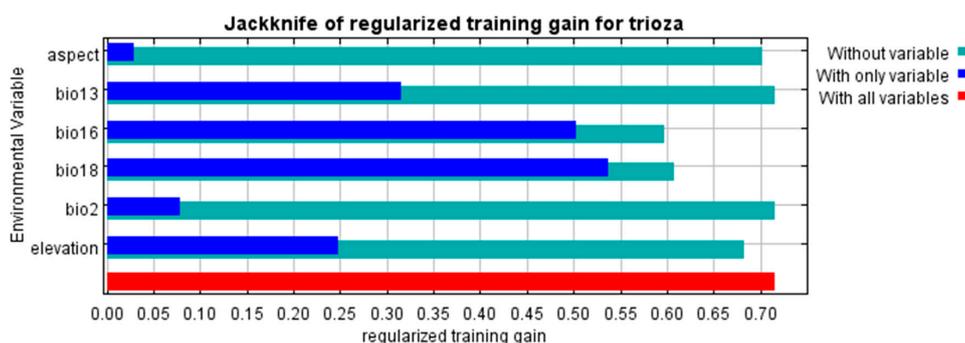
The Pearson correlation test for multi-collinearity resulted in selecting only six BCL and six RS uncorrelated predictor variables, respectively, see Table 1. The overall accuracy, TSS, and  $K_{\text{hat}}$  for both the BCL and BCL-RS MaxEnt models are shown in Table 2. A combined BCL-RS model gave the highest accuracy of 92% with a TSS score of 0.83 compared to the model with only environmental variables (BCL model), which had an overall accuracy of 85% and a TSS score of 0.572. TSS and  $K_{\text{hat}}$  statistics showed a prediction better than expected at random (TSS = 0.5) for both models, with the BCL-RS model performing better than the BCL model.

**Table 2.** Accuracy assessment statistics for the developed African citrus trioqid (*Trioza erytreae*) MaxEnt models.

Model	Bio-Climatic and Topographical Variables (BCL, <i>n</i> = 6)	Bio-Climatic, Topographical and Remotely-Sensed Variables (BCL-RS, <i>n</i> = 12)
Overall accuracy	0.85	0.92
Sensitivity	0.73	0.91
Specificity	0.85	0.92
K <sub>hat</sub>	0.30	0.42
TSS	0.57	0.83

### 3.2. Variable Importance

Figures 4 and 5 show the results of the jackknife test of variable importance for the BCL and BCL-RS models, respectively. Blue shades show the individual importance of each variable when used in isolation, while green shows the model performance when the variables are exempted from the model. The figures also show the variables which caused the greatest decreases in the gain when omitted, indicating that they provided a significant portion of information that was not contained in the other variables. For both models (BCL and BCL-RS), the variable with the highest gain (relevance) when used in isolation was Bio 18; therefore, Bio 18 appears to have the most useful information individually, followed by Bio 16 (for variable definitions see Table 1). Likewise, the variables that decreased the gain the most when they were omitted were Bio 16 and Bio 18 for the BCL model and Bio 16 and LST for the BCL-RS model. These variables appear to have the most influence on the models compared to the other variables.



**Figure 4.** Jackknife variable importance test of regulated gains for the BCL model. The dark blue shades show the regularized training gain for the specific variable, light blue shows the relevance when the variable is omitted, while red shows the regularized training gain with all the variables combined.



**Figure 5.** Jackknife variable importance test of regulated gains for the BCL-RS model. The dark blue shades show the regularized training gain for the specific variable, light blue illustrates gains without the variable, while red shows the regularized training gain with all the variables combined.

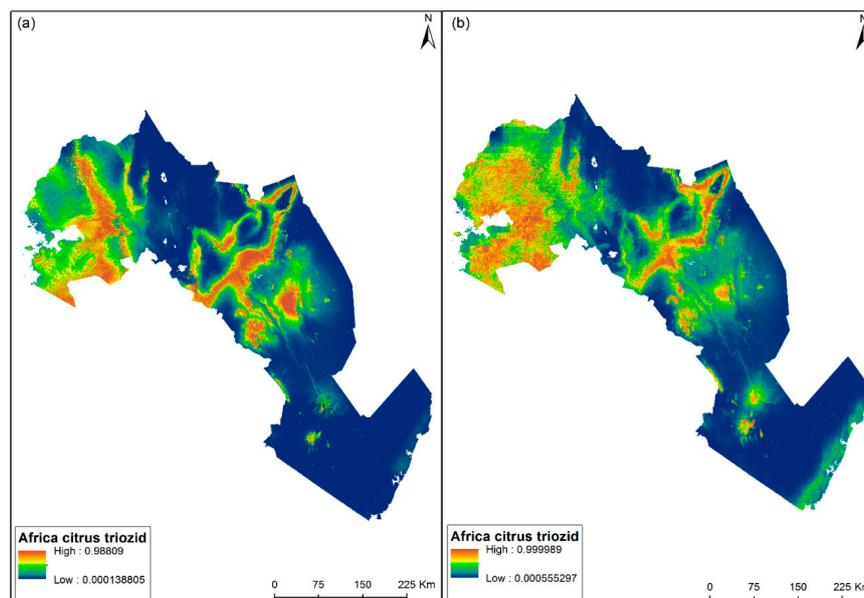
Table 3 presents the percentage that each variable contributed and its permutation importance in the BCL and BCL-RS models, respectively. In the BCL model, Bio 16 was the variable that contributed the most (48.3%) followed by Bio 18 (44.5%), Elevation (4.0%), and Aspect (2.2%), respectively. Similarly, in the BCL-RS model, Bio 16 contributed the most (41%), followed by Bio 18 (36.3%), while the contributions for LST, Elevation, and Aspect ranged from 4.9% to 6.6%.

**Table 3.** Percentage contributions and permutation importance for each variable to the BCL and BCL-RS models, respectively.

Variables	Percent Contribution	Permutation Importance
<b>BCL Model</b>		
Bio 16	49.3	40.5
Bio 18	44.5	38.9
Elevation	04.0	18.3
Aspect	02.2	02.3
Bio 2	00.0	00.0
Bio 13	00.0	00.0
<b>BCL-RS Model</b>		
Bio 16	41.0	30.6
Bio 18	36.3	23.9
Land surface temperature (LST)	06.6	11.5
Elevation	05.3	07.0
Aspect	04.9	07.8
Small integral	02.8	03.9
Large integral	02.5	07.6
Bio 13	00.5	04.2
Right derivative	00.2	03.4
Left derivatives	00.0	00.1

### 3.3. Habitat Suitability Mapping

Figure 6 shows the predicted habitat suitability map for ACT based on the BCL, see Figure 6a, and the BCL-RS, see Figure 6b, models. The maps indicate the more suitable predicted sites with warmer colors (red) and less suitable predicted sites with cooler colors (blue). Both models show better predicted conditions in Western, Central, and small parts of Eastern Kenya. These areas have a higher elevation above mean sea level. The least suitable sites are mostly towards the coastal region which has lower elevations.

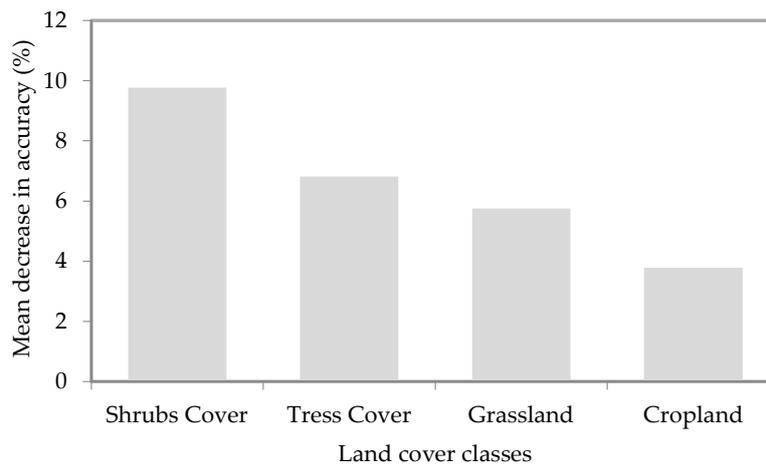


**Figure 6.** Predicted distribution suitability map for African citrus triozid (*Trioza erytreae*) using environmental (BCL model) variables (a), and environmental and remotely-sensed (BCL-RS model) variables (b). Blue indicates low distribution suitability, while red represents high distribution suitability.

The *t*-test result showed that the BCL-RS model produced significantly (*t*-statistic = 2.8279 and *p* = 0.005) higher AUC values compared to the BCL model. The *t*-test difference in the means, indicated that RS variables contributed 18% to the prediction model when combined with environmental variables.

#### 3.4. Relationship between ACT Habitat Suitability and Landscape Context

We realized that there are diverse and multiscale responses of landscape context (i.e., LULC) to the habitat suitability of ACT. Using the mean decrease in accuracy (%) in the RF variable importance rank, the “shrubs” class was found to be the most relevant LULC class to ACT habitat suitability followed by “trees”, “grassland”, and “cropland”, respectively, as shown in Figure 7.



**Figure 7.** The relevance of the four major land use/land cover classes to the habitat suitability of African citrus triozid (*Trioza erytreae*) using a random forest variable importance rank.

## 4. Discussion

This study tests the applicability of an EN modeling approach for predicting the distribution and suitable habitat for ACT in citrus-growing regions in Kenya. This was achieved through nesting ACT habitat variables with a MaxEnt modeling framework for generating distribution information that is fundamental for prioritizing sites in which the management of ACGD is most needed or feasible [85]. A reliable and accurate ACT distribution map is a valuable information source for monitoring vector infestation rates and disease spread. Such a spatial data set can also be used to prioritize interventions that prohibit the spread of the disease to unaffected areas [86]. The “near-real-time” aspect of the remotely-sensing data means that the largely neglected aspect of early response can be addressed within integrated pest management (IPM) strategies [87].

In general, our study shows that both the uncorrelated BCL and RS variables were well-associated with the occurrence of ACT in typical Eastern African landscapes with their heterogeneous agro-ecologies. The results showed the importance of fusing RS with BCL variables in reducing the overestimated spatial variability in the predictor variables and in enhancing the predictive power of the model [69]. For the best performing models, Bio 16 (annual precipitation) had the highest contribution towards predicting the habitat suitability for ACT followed by Bio 18 (precipitation of the warmest quarter), LST, elevation, aspect, and small integral (MODIS-derived vegetation productivity). Precipitation of both the wettest and warmest quarter were important variables in defining the habitat suitability of ACT since they regulate the optimal temperature ranges within which the triozid survives [88]. In addition, precipitation and temperature regulate citrus flushing circles which are known to be highly correlated with the occurrence of ACT [10]. The significance of the precipitation related variables in describing habitat suitability for ACT was more pronounced than elevation, which has been linked with the distribution of the vector in a previous study [36]. This could be due to the micro-climatic aspect which is not entirely dependent on elevation but also landscape heterogeneity, among other aspects. In the BCL model, Bio 16 and Bio 18 alone

contributed more than 92% to the model performance, while in the BCL-RS model, the contribution from these variables was reduced to 77% indicating that inclusion of RS variables contributes immensely to the model. Since our aim was to start from known BCL variables that are commonly used to predict the spatial distribution of crop pests, then explore the contribution of RS variables to the predictive model performance, we did not create a model without bioclimatic variables. Also, we did not create any bootstrapped MaxEnt models, which could have allowed the quantification of the effect sampling variability had on our model results (ACT distribution map).

Makori et al. [69] reported that RS information used within habitat suitability models is known to better account for explicit landscape patterns, that define habitats, thereby reducing model over-fitting and essentially increasing the accuracy and precision of habitat suitability models. In addition, our results showed that LST played a key role in defining the niche of the ACT vector. This is in agreement with previous studies which have shown LST to be a main parameter in pest modeling routines [89]. The influence of RS variables in modeling the habitat suitability of ACT was considerable. The BCL model, as shown in Figure 6a, had over-predicted the distribution of ACT compared to the BCL-RS model, as shown in Figure 6b. In our ACT prediction distribution map, areas with high occurrence probabilities are characterized by high precipitation, high elevation, lower temperature regimes, and relatively similar vegetation productivity patterns.

The ACT distribution maps using BCL-RS variables show high occurrences of ACT in specific locations of the coastal region of Kenya. This disagrees with the findings of previous studies that ACT is unlikely to be present in coastal ecosystems. This could be related to vegetation dynamics and landscape context (i.e., LULC), which are very distinct in some specific areas along the coastal region, such as Wundanyi sub-county in Taita-Taveta county where the habitat suitability was reported to be high compared to other coastal regions of Kenya using the MaxEnt model. Despite the climate conditions being very similar to other regions where the model has predicted a high suitability of ACT, vegetation patterns in regions where the habitat suitability is high are very distinct and of similar productivities since they have common climatic conditions in terms of rainfall and temperature. This is in alignment with the finding from the literature that vegetation dynamics play a key role in defining the niche of crop pests and diseases [90]. This result reinforced the importance of both BCL and RS variables for modeling the distribution of ACT. Further, our study is a step towards the understanding of how the spread of insect pests is enhanced by BCL (both bio-climatic and topographic) and RS (vegetation phenological variables and LST), that influence the spread and multiplication of the vector in African agro-ecosystems.

Furthermore, the results from this study revealed that landscape context should not be ignored regarding understanding the distribution and dispersal pattern of ACT. However, we did not include landscape context in our MaxEnt model since from our field observation, we realized that the majority of the citrus orchards in our study area are within a cropland class. In our case, a presence-only MaxEnt model would have extracted only 'cropland' features for all ACT presence points. Therefore, we opted to look at the effect of the landscape context on ACT habitat suitability based on the dispersal capability of the pest (which is 1500 m). The relationship between ACT habitat suitability and the four major LULC classes across the major citrus-growing regions showed that there is an association between the surrounding shrub cover proportion and habitat suitability for ACT. Shrub cover near citrus orchards could provide alternative host plants for the vector during the time when citrus trees are not flushing since ACT is correlated with the flushing rhythm of the citrus host [91]. In addition, from field observations, it became clear that the majority of the ACT-infected citrus trees were within shaded areas, and thus trees and shrubs surrounding the citrus orchards most likely provide more suitable temperature conditions for the survival of ACT.

To the best of our knowledge, our study is the first attempt to predict the distribution of ACT using an enhanced and optimized EN modeling algorithm with BCL and RS variables and habitat suitability relationships with the surrounding landscape classes. Previous studies have only investigated the role of various environmental variables for mapping ACP distribution, but in these studies, links between localized factors captured in more sophisticated modeling routines and better consideration

of landscape patterns were not considered [36]. Future studies should explore the relationship between vegetation phenological and other localized pest classification factors and ACT densities (i.e., number of insets per unit area) to better understand the survival and dispersal patterns of the vector as there is a need for a better and more concerted implementation of vector management practices.

## 5. Conclusions

The impact of spatially heterogeneous environmental factors on ACT population dynamics are complex to model. However, understanding the inter-relationship between vectors, hosts, and their niches environment can provide valuable information for identifying conditions suitable for pathogen introduction and transmission in citrus-growing regions. By exploring the spatial distribution of ACT, we identified a set of BCL factors that are favorable for its development, predicted its spatial occurrence, and identified potential areas that, due to their BCL conditions, would be suitable for its introduction.

The BCL-RS model showed higher accuracy metrics and was deemed appropriate for predicting the distribution and potentially suitable areas for ACT. Though less important, the influence of vegetation phenological variables and LST for determining the habitat suitability of ACT was considerable. Our results revealed that apart from the BCL variables like temperature, rainfall, and elevation, which have previously been found to define the EN of ACT, vegetation patterns and dynamics at a landscape level play a key role in influencing vector-host-pathogen transmission and distribution. The ACT distribution prediction maps are an important tool for identifying risk zones and understanding risk drivers. Also, the distribution maps can provide baseline information for the development and implementation of effective IPM strategies. Future studies should look at modeling the density of ACT on a landscape scale for the precise application of prevention and control measures.

**Author Contributions:** R.K. analyzed the data and wrote the manuscript. He is also the main author of all sections in this manuscript. All co-authors provided valuable input regarding fieldwork, data analysis, and manuscript preparation. Conceptualization, R.K., E.M.A.-R. and T.L.; Formal analysis, R.K.; Funding acquisition, S.A.M. and S.E.; Methodology, R.K.; Project administration, T.L. and E.M.A.-R.; Software, R.K.; Supervision, B.C. and T.L.; Validation, R.K.; Writing – original draft, R.K.; Writing – review & editing, E.M.A.-R, B.C., S.A.M. and S.E. and T.L.

**Funding:** This research was funded by Ministry for Economic Cooperation and Development (BMZ) and Deutsche Gesellschaft für Internationale Zusammenarbeit Advisory Service on Agricultural Research for Development (GIZ/BEAF) grant number 81180346 and the APC was funded by GIZ/BMZ.

**Acknowledgments:** We gratefully acknowledge the financial support for this research by Germany – Ministry for Economic Cooperation and Development (BMZ) and Deutsche Gesellschaft für Internationale Zusammenarbeit Advisory Service on Agricultural Research for Development (GIZ/BEAF) for the project “Citrus pest management in Kenya and Tanzania”. We also acknowledge the International Centre for Insect Physiology and Ecology (*icipe*) core funding provided by UK’s Department for International Development (DFID), Swedish International Development Cooperation Agency (Sida), the Swiss Agency for Development and Cooperation (SDC), the BMZ, and the Kenyan Government. The views expressed herein do not necessarily reflect the official opinion of the donors. Our appreciation also extends to the Plant Health Theme of *icipe* for helping in field identification and data collection. Special thanks to Mr. Jackson Kimani for preparing the final maps.

**Conflicts of Interest:** The authors declare no conflict of interest.

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