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3D Indoor Mapping and Modelling

Guest Editors:

Dr. Lucía Díaz-Vilariño

Applied Geotechnologies
Research Group, Campus
Universitario de Vigo,
Universidade de Vigo, CINTECX,
As Lagoas, Marcosende, 36310
Vigo, Spain

lucia@uvigo.es

Dr. Abdoulaye Abou Diakité

Geospatial Research Innovation
and Development (GRID) group,
Faculty of Built Environment,
University of New South Wales,
Sydney, Australia

a.diakite@unsw.edu.au

Dr. Shayan Nikoohemat

Department of Earth Observation
Science, University of Twente,
7522 NB Enschede, The
Netherlands

s.nikoohemat@utwente.nl

Message from the Guest Editors

In the last few years, there has been intense research activity towards the mapping and automated modelling of indoor environments. Updated and detailed indoor models are being increasingly demanded for a variety of applications, such as building management, indoor navigation, location-based services, and emergency responses. However, existing interior models are often not up-to-date, and consequently, they do not represent the as-is condition of the scene.

LiDAR scanning and photogrammetry have been revealed to be suitable techniques to collect data at a large scale, especially when dealing with portable and mobile acquisition systems. Nevertheless, point clouds, which constitute massive and unstructured data, need to be efficiently processed in a way that useful information for the applications they intend to serve is extracted.

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Special Issue



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Editor-in-Chief

Prof. Dr. Wolfgang Kainz

Cartography and Geographic Information Science, Department of Geography and Regional Research, University of Vienna, Universitätsstr. 7, A-1010 Vienna, Austria

Message from the Editor-in-Chief

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ISPRS International Journal of Geo-Information
MDPI, St. Alban-Anlage 66
4052 Basel, Switzerland

Tel: +41 61 683 77 34
Fax: +41 61 302 89 18
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