



Autonomous Robots for Inspection and Maintenance

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submissions:

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Message from the Guest Editor

Dear Colleagues,

Since the current challenges of robotic autonomy are still limited to fundamental functions, applications to inspection and maintenance introduces various unexplored topics. The maintenance task often requires higher-precision position control and more intensive force control in highly constrained environments. This Special Issue invites articles addressing problems and solutions characterized for robotic inspection and maintenance. Potential topics include, but are not limited to, the following:

- High-precision robotic mapping;
- Semantic mapping and robot cognition;
- High-precision 3D reconstruction;
- Defect detection, identification and classification;
- Complex task planning and scheduling;
- High-precision mobile manipulation in highly constrained environments;
- Intensive force control;
- Long-term autonomy;
- Human–robot collaboration;
- Learning from demonstration;
- End-effectors for inspection and/or maintenance.

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Guest Editor





Editor-in-Chief

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Message from the Editor-in-Chief

It is my great pleasure to welcome you to our open access journal, *Robotics*, which is dedicated to both the foundations of artificial intelligence, bio-mechanics and mechatronics, and the real-world applications of robotic perception, cognition and actions. The 21st century is the robotics century and intelligent robots will change our lifestyle forever. Let us work together toward the realization of intelligent robots step by step.

It is great fun to create intelligent robots and imagine their practical applications. *Robotics* is now ready to serve you in the long journey towards such a goal.

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